Orchestrating Networked Machine Learning Applications using Autosteer

Zhenyu Wen, Renyu Yang, Bin Qian, Ringo W.H Sham, Rui Sun, Jie Xu, Pankesh Patel, Omer Rana, Rajiv Ranjan

Abstract—A platform for orchestrating networked Machine Learning (ML) applications over distributed environments is described. ML applications are transformed into automated pipelines that manage the whole application lifecycle and production- grade implementations are automatically constructed. We present AUTOSTEER, a software platform that can deploy ML applications on various hardware resources interconnected using heterogeneous network resources, across cloud and edge devices. Device placement optimization and model adaptation are used as control actions to support application requirements, and maximize the performance of ML model execution over heterogeneous computing resources. The performance of deployed applications are continually monitored at runtime to overcome performance degradation due to incorrect application parameter settings or model decay. Three real-world applications are used to demonstrate how AUTOSTEER can support application deployment and runtime performance guarantees.

Index Terms—machine learning, application deployment, runtime optimization, model update

1 INTRODUCTION

Machine Learning (ML) systems and applications are intrinsically non-deterministic and need to operate in an environment which is constantly-evolving, and contains ever-changing data. Typically, a networked machine learning application consists of a variety of components for data collection, device control, model inference (e.g., speech recognition, object detection), which are deployed and managed at different locations, i.e. either on locally managed servers or remotely in cloud data centers or edge environments.

ML applications executing over a networked platform are arguably complex systems which have to be continuously updated and maintained. ML applications need to be transformed into automated pipelines that manage the whole application lifecycle and build production-grade machine learning implementations. A pipeline workflow, typically in the form of a graph representing the component interconnections in an ML application, can comprise: data management, model learning (model selection, training and hyper-parameter selection), model testing and validation and model deployment. Thereafter, run time management is responsible for ensuring performance guarantee, i.e., end-to-end model performance optimization and model update [1], so that the deployed ML applications can be dynamically modified to run time environment.

Doing so manually is generally unrealistic and not scalable, particularly when thousands of ML applications are submitted and maintained in edge and cloud platform that may be composed of hundreds of devices with heterogeneous hardware and software specifications. Continuous and automatic orchestration plays a pivotal role in deploying, managing and synchronizing models of the ML applications across multiple tiers in a distributed computing environment. For instance, the trained models will be published and delivered to specific cloud servers or edge devices to run inference. Some specific applications, e.g., federated learning tasks require on-device training, indicating more complex device placement and model synchronization. Moreover, model decay arising from changes in data, would inevitably diminish model accuracy over time. Hence, an orchestrator calls for observation of the performance deviation and redeployment of the updated models.

Deploying such networked machine learning systems, particularly in an IoT and edge environment can be challenging due to the difficulty in managing the complexity of heterogeneous network and hardware resources. A variety of devices are used for data exchange, model training and data analysis encompassing edge devices (such as IoT gateways and base stations) and servers (such as GPU, CPU, and TPU-based devices). Existing ML model development can be computationally expensive and resource intensive, which impede the effective deployment of applications, particularly those with strict latency requirements to resource-constrained devices.

In this article, we propose a platform solution to deployment and runtime management for the pipelines of networked machine learning applications. We devise AUTOSTEER, a management system that can automatically deploy networked machine learning applications over heterogeneous network and hardware resources while ensuring their performance through deployment plan optimization and model adaptation. At runtime, AUTOSTEER continually

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monitors the performance of deployed applications and automatically performs model update to mitigate performance degradation caused by obsolete application parameters setting or model decay. Finally, we use three real-world applications that are executed upon AUTOSTEER to showcase how the mechanisms are engaged in the application deployment and run-time maintenance.

2 MOTIVATION

2.1 Motivating Examples

We primarily categorize the networked machine learning applications into a) *centralized off-site* ML applications that can be trained offline or offsite, and b) *distributed on-site/federated* ML applications that must build their models using local dataset on individual device and, in some cases, share and aggregate models with other peer devices.

Centralized off-site learning applications. A smart home application allow users to observe the occupancy of their house, remotely control the smart devices (e.g., LEDs, air conditioner) via smartphone and even automatically control the smart devices. For example, a smart home application can automatically adjust the temperature of air conditioners based on the occupancy, weather and so on.

Distributed on-site/federated learning applications. A high-quality brain tumor detection application relies on a huge amount of magnetic resonance imaging (MRI) data that is only locally available and managed within a specific institution domain due to GDPR and other privacy regulations. A shared model is typically distributed to different data owners and trained locally. Locally-trained models will be combined into a consensus model.

2.2 Research Scope and Overview

In general, the pipeline for such an application can be depicted as the workflow in Fig. 1. The pipeline starts with and augments an initial model that has been trained offline along with a reference to meta data and the associated data sources on which the model has been trained. Thereafter, the workflow management platform typically addresses two fundamental problems: planning for device placement and model adaptation in the *deployment* phase and model execution performance guarantee in the *runtime* phase.

Determining the placement of ML components on available resources remains a key challenge – especially due to heterogeneity of resources. Additionally, models have to be converted, for example through model pruning [2], post-training quantization [3], and identifying a "focus" for the associated model through *distillation* techniques. This enables the generated models to best fit the target device, balancing the model size with accuracy of prediction. Significant recent efforts in this area include TinyML and EdgeML.

Once the plan of deployment comes into effect, run time management ensures that the model performance can be monitored and overcomes model staleness. In the automated and continuous pipeline, triggers can be used to update application parameters or retrain the stale model with fresh data when performance observably degrades due to dynamic environment changes, such as network speed drop, workload bursting, model drift or lack of generalization. For applications of federated learning and distributed training, the platform run time also needs to enforce efficient on-device training.

A key focus of this work is to devise an orchestration system for supporting multiple ML model development and performance optimization. Additionally, the system needs to scale to support both application size and resource heterogeneity. To underpin precise performance monitoring and anomaly detection while measuring platform health and resource utilization, we also need to track and inspect (distributed) system *fingerprints* – consisting of various performance indicators and application metrics such as drift and prediction scores.

3 CHALLENGES

We elaborate on these specific challenges facing the ML workflow platform in the following notable aspects:

Complexity of device placement and model adaptation. Planning for a pipeline of a given ML application indicates a mapping procedure between awaiting models and available computing resources on the devices. To accommodate the specific demands of diverse distributed or federated learning applications, infrastructure resources have become increasingly heterogeneous, making the planning a far more intricate task:

1) Device placement: Successfully deploying sizeable components of the ML applications served in the platform requires stringent capacity check and optimization solution under numerous constraints. The manifestation of heterogeneity intrinsically stems from the static attributes of the hardware, such as CPU, GPU, memory, SSD and network bandwidth, and of the software including operating system version, clock speed, and particularly software libraries. The compatibility of a given hardware or library version even becomes a hard constraint, for any violations of such requirements would completely fail the deployment. For example, some components are compiled for ARM MALI cannot be executed on Nvidia GPU. The network constraints, such as bandwidth sharing among co-located components or network latency specified by each individual component, will further exacerbate the planning complexity.

2) Model adaptation: The advancement of deep models such as RNNs and CNNs leads to the substantially increased parameter number and the resultant computational cost, which hinders the real-world model deployment into embedded and edge devices. Hence, model pruning and compression can be used to reduce model size, remove redundant weights such that pre-trained models can better adapt to portable devices with limited resources (e.g. memory, CPU, power and bandwidth) and be applied into real-time applications.

3) Enabling dependent components within a pipeline: Each individual ML model has its own specification and format of input and output data. Dependencies are referred to as the interactions, such as the data flows and remote callings, among interconnected components. This would be problematic and challenging particularly when components deployed on various devices are interconnected via different network types and protocols. Hence, it is imperative to design an effective data messaging system to orchestrate the data flow and manage the network traffic across different

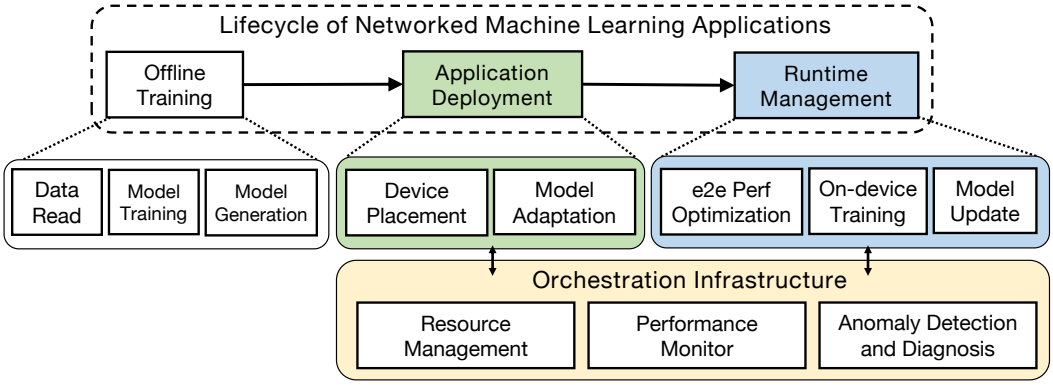

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Fig. 1: Conceptual workflow

models whilst considering the particular specification and data format.

Optimized runtime management. Improper application parameter setting or model decay could result in poor performance of a ML application and even failures. The first task of runtime management is to perform end-to-end and intra-application optimization. Application parameters (e.g., model accuracy, task off-loading rate) need to be adjusted at runtime to ensure the allocated resource can guarantee the expected performance level. To do so, the orchestration system should be capable of automatically detecting any performance degradation of the deployed applications and then dynamically work out the optimal configuration to rescue the abnormal performance. Secondly, in the face of any model failures, the orchestration system should automatically perform local on-device training while synchronize and aggregate the up-to-date global models on the fly.

Low-cost platform monitoring and troubleshooting. Monitoring is one of the primary issues in maintaining ML applications and systems; outline or anomaly detection is important to find out unexpected model prediction or any system-wide issues in the early stage. However, anomaly detection and trouble-shooting could be challenging as high-quality labeled data is sparse and difficult to obtain and hence only semi-supervised or unsupervised approaches could be applied. The overhead is another non-negligible consideration when designing application instrumentation and metric collection. This usually indicates a tradeoff between the accuracy and granularity of the measured data. Hence, the platform solution of infrastructure monitor should have an overall co-design of metric sampling, storage and real-time analysis.

4 System design

In response to the aforementioned challenges, we develop AUTOSTEER, an orchestration platform for application deployment and runtime management. In this section we mainly highlight a set of key techniques used for implementing the orchestration mechanism. Fig. 2 describes the architecture of AUTOSTEER.

4.1 Automatic Application Deployment

Application and resource specification. The user submits a ML application with execution logic, pre-trained models and specifies the pertaining requirements such as model accuracy, end-to-end latency, etc. To achieve an automatic deployment, we need to translate these knowledge to machine-understandable language. We use a UML-based visual domain specific language [4] that can easily represent the component dependencies within an application and specify the format and source of input and output of each individual component. As a result, the interactions between components, such as data flows and service calls, are loosely-coupled through interfaces and agnostic about any model updates. Apart from the application specification, standardized resource specification is the key to automatic and efficient deployment. we exploit TOSCA [5] for specifying the available underlying computing resources and the hardware and software requirements of each application.

Planning optimization for device placement. To navigate the algorithmic complexity, the orchestrator in AUTOSTEER adopts two optimization techniques: gradient based optimization [6] and reinforcement learning (RL) [7]. Gradient-based approaches work upon a realistic model to formalize an optimization problem and usually have relatively low time complexity without the need of apriori knowledge or experience, which are therefore suitable for new applications. In contrast, RL-based methods can learn the optimal planning from the experiences and can better support the uncertainties compared the Gradient-based solutions.

We also construct an efficient data messaging subsystem where two types of dependencies are defined – *data flow* and *service call*. Since the orchestration system needs to deliver a large volume of data in distributed environments, high system throughput becomes a critical system objective. We employ the publish/subscribe paradigm implemented in Apache Kafka to underpin the data flows. The service call, on the other hand, is implemented through RESTful APIs, as the precise command delivery is the primary goal. Both the publish/subscribe and RESTful paradigms can be implemented upon the a vast majority of network types and protocols, hence capable of supporting most networked machine learning applications.

4.2 Model Adaptation

Computation optimization aims to improve the execution efficiency of different computation units associated with the model (e.g., vector-vector, vector-matrix and matrix-matrix

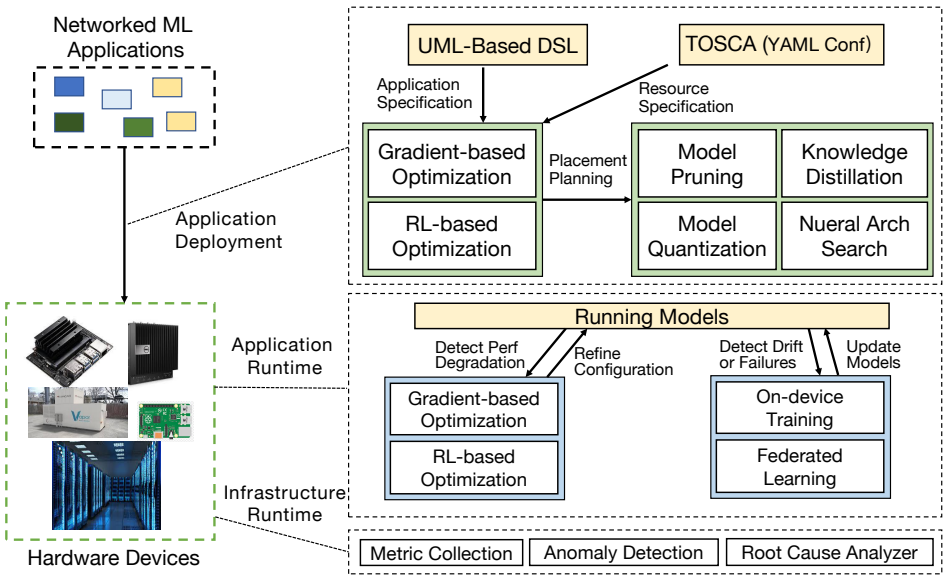


Fig. 2: The architecture of AUTOSTEER

operations) on various hardware. Optimizing the execution pipeline of the computation graph of a neural network can further improve model performance. We use TensorRT along with the adjustment of weights and numerical precision associated with the activation function (e.g., INT8 and FP16). Model architecture optimization improves the efficiency of on-device computation through well-designed models such as MobileNetV2, ShuffleNet etc – part of the TensorFlow-Lite toolkit). We use *YOLOv3* [8] to strike a balance between computation efficiency and model accuracy.

In addition, more advanced and customizable approaches such as neural architecture search (NAS) [9] and model compression can be implemented in AUTOSTEER further. NAS automates the search of an optimal network structure with the aid of reinforcement learning or Genetic Algorithm (GA) based approaches. However, it is computation-intensive and tend to be problematic given the portable devices with limited resources. Model compression is thus extensively studied in three notable aspects: *model pruning* that removes the redundant parameters within the networks; *quantization* that reduces the weights precision and *knowledge distillation* [10] that trains a new small model based on a larger model. Quantization is the most straightforward approach at the risk of precision degradation and model pruning is the most well-established approach but requires extra calibration process. Integrating mixed techniques in the platform is already underway for building more adaptive and robust models.

4.3 End-to-end Application Optimization

In a networked machine learning system, computational and network resources are dynamically available at different levels. Application parameters such as input rate and the targeted accuracy need to be adjusted, in response to the ever-changing traffic congestion, to assure the end-to-end latency or system throughput.

We specify model parameters based on extensive benchmarking experiments and transform the problem of finding the "best " setting of parameters into an optimization problem using techniques such as convex optimization, evolution based and gradient based methods. Reinforcement learning is an alternative approach that use statistical or deep learning model where the application parameters are the actions of the agent, and the available computing resources represent the environment. The system performance is represented by the reaction of the environment to the actions. As opposed to the optimization-based approaches that have better interpretability but need extra hand-crafted modeling process, the reinforcement learning based approaches have better representation capabilities and can learn to set optimal application parameters from experience.

4.4 Model Update

Coping with the drift. During the lifecycle of a ML application, the relationship between the input variables and the performance of the targeting prediction inevitably experiences constant change and drift over time. The model drift usually originates from the following aspects: 1) *invalid measurement indicator*: the replacement of data collection devices may give rise to different value spaces and a broken device could always deliver nil reading. 2) *concept drift*: data distribution or statistical characteristics, which is uncertain and frequently varying over time, may lead to concept drift. 3) *data drift*: The model effectiveness is also prone to inherent changes such as the seasonal temperature rise and fall. Drifts can be roughly categorized into several classes: sudden drift (sudden change of the data pattern). gradual/incremental drift (new pattern that replaces the old ones within a period of time), and reoccurring drift (old patterns re-pop up later).

It is imperative to detect such drifts, understand the degree of drift and intervene the model for adapting to changing environments. There are three representative classes of drift detection: 1) error rate based approaches focus on the online detection of errors or sudden changes for triggering the model update. 2) data distribution based approaches

mainly measure the statistical similarities between the original data and the new data and check if the difference is sufficient for model update. 3) hypothesis test based approaches, built upon the previous two methods, apply various hypothesis tests to quantify further the severity of model drift. Base on these approaches, our solution can determine *when to intervene* according to the starting and ending points of the drift, *where to intervene*, i.e., localizing the concept/data drift in the feature space. and *how to intervene*, in the light of the type and degree of the drift, by adaptively choose model update strategies. The most straightforward approach is the model retraining and updating. For concept drift, we ensemble several base classifiers or utilize knowledge transfer learning for the emerging new target variables.

System implementation. The amount of data engaged in the model update has an impact on the training effectiveness and the system overhead: less data can reduce computation and storage cost but only reflect the latest data distribution; more data is beneficial for reshaping models with higher precision, along with increased overhead. We employ an adaptive window-based solution to select the optimal data amount used for on-device training and/or global model synchronization via ADWIN [11] algorithm: instead of using a fixed time window, the algorithm calculates the drift rate from all possible windows and selects the best cut that reveals the optimal drift level. We modularize and implement the drift detection and alarming system in AUTOSTEER. The detection module is responsible for data retrieval and extraction of data statistical properties, and we then leverage hypothesis tests to evaluate the drift degree. Once the alarming system confirms the existence of the model drift, we employ techniques in §4.2 for efficient on-device training. For federated learning applications, once local model has been updated, we also trigger gradient aggregation to keep the global model up-to-date.

4.5 Infrastructure Monitor and Maintenance

To learn how the applications perform, we either collect general-purpose telemetry metrics in a black-box manner or instrument, as an integral part of the models, subsystems or system services, in a white-box manner. The metric tracking and tracing system of our orchestration infrastructure collects system logs, model metrics (task execution status, prediction statistics and evaluation metrics as baselines), system metrics (request latency, error rates, network status, etc.), and resource metrics (CPU utilization, memory utilization, GPU usage, etc.) in real time, and ships them to a centralized analytic platform. We adopt the random sampling mechanism on each agent that is deployed on each physical node, for reducing the overhead of data collection. More advanced technologies such as sketch [12] can be further added. *Anomaly Detector* comprises real-time event-based processing units, used for identifying per-application performance degradation while *Root-cause Analyzer* is implemented to troubleshoot the causes of performance degradation based on the collected performance indicators.

5 CASE STUDY

In this section, we showcase several real-world applications backed up by the deployment and runtime management mechanisms in AUTOSTEER.

Case A: adaptive air quality monitoring. We develop and deploy an air quality monitoring application, comprising air quality sensors and traffic cameras installed on the streets. It is capable of monitoring real-time air quality level around the city and predict the trends in the short run. Fig. 3 illustrates how components are pipelined and orchestrated in our platform – We first automatically deploy the application on a basis of pre-trained models in a distributed environment and continuously refine the prediction models taking into account new data through fine-tuning or retraining, followed by a model re-deployment.

More specifically, there are three separate stages: *Initial stage:* Both controller and agent start by performing a registration and initialization of API endpoints. *Training stage:* A container in the cloud server is launched, overseen by the controller, for training a model that can predict the air quality in the next hour. The trained model is stored in the cloud storage (e.g., Github, Google Drive) which maintains all historical versions. *Deploy stage:* Once the controller detects a new model version, it instructs all necessary agents to deploy or re-deploy the application.

Case B: edge-based real-time video analytics. As shown in Fig. 4(a), we develop an video analytical application following the edge-cloud paradigm. A set of video generating devices (e.g., traffic surveillance cameras, drones, mobile phones) produce live video streams which are then processed either on low-power edge devices (e.g. Raspberry pi, Jetson Nano, computing chips), or GPU cluster in Cloud datacenters. We prototype the video analytic application via object detection models yolo3 and the Wide Area Network (WAN) communication between edge devices and the data center is implemented by using the real time video stream transmission protocol (RTSP).

The heterogeneity of edge nodes and the interplay among the edge and cloud introduce uncertainties regarding network latency, hardware slowdown or failures. As discussed in §4.3, the collected fingerprints and system status are mathematically modeled with a hierarchy queuing model that reveals the relationships between the workload offloading rate (between the edge and cloud) and the system latency and throughput. We then formulate a min-latency optimization problem bounded by a minimal throughput threshold. For model optimization, we implement two gradient-based optimization algorithms (i.e., PGD-VAO, PGS-VAO) to ascertain a solution to minimizing the overall latency. Fig. 4(b) shows that our solution outperforms other state-of-the-art task-offloading approaches.

Case C: federated learning enabled connected and autonomous vehicles (CAV). Understanding the road environments is essential for enabling autonomous vehicles into reality with reduced traffic accidents and increased transportation efficiency. However, road environments are miscellaneous and dynamic due to road types, weather and road conditions, etc. Fig. 5 illustrates a practical solution underpinned by our orchestration platform.

The orchestrator first deploys a shared model onto different base stations with a complete knowledge of the original model and onto CAVs with adaptive versions. We transform the shared model into various size by using knowledge dis-

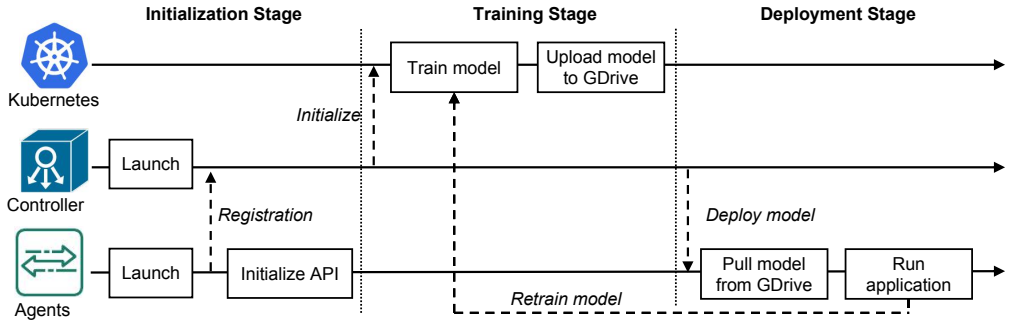
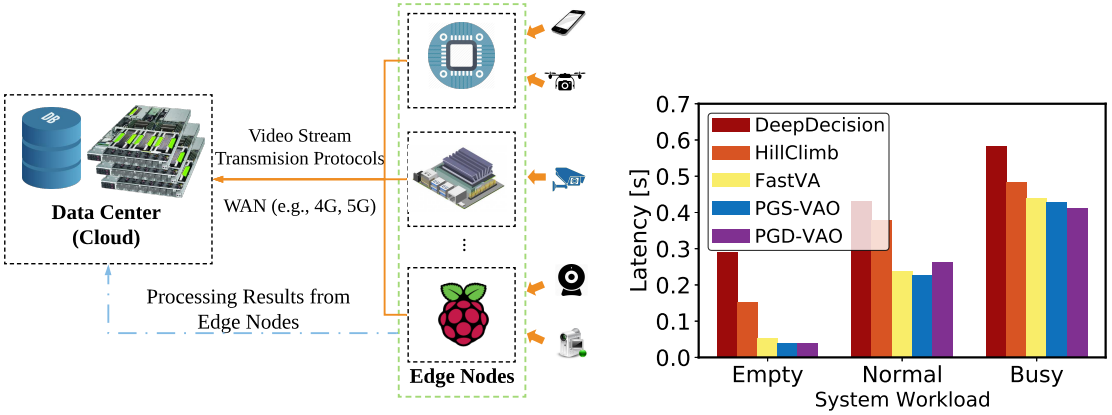


Fig. 3: The orchestration in the air quality monitoring application



(a) Illustration of an edge-cloud video analysis system.

(b) Performance of workload optimizer in different system working conditions.

Fig. 4: The edge-cloud video analysis application and an early performance comparison

tillation and enable the execution smoothness on different type of CAVs with diverse computing resources. If a vehicle detects the change of the road environment, the deployed model will be retrained and updated locally. In the current prototype, once a vehicle comes into the networking area covered by a base station, the vehicle attempts to exchange its local update, e.g., the gradients, with the global model in the base station. As a result, the global model can always be kept up-to-date and shared among other CAVs.

6 Conclusion

Most prior work related to ML applications focuses on algorithm design and optimization for better training ML models. Although such work is essential for specific applications, there are few studies on the holistic orchestration solution to maintaining the lifecycle of networked ML applications. In this article, we firstly highlight several key challenges facing the orchestration systems. We then present a set of techniques to deploy ML applications onto resources across cloud and edge devices and assure their runtime performance, making models being served free from model decay and performance degradation due to inappropriate parameter setting. These assist in finding effective pathways to automating the management of networked ML applications at production level, although, admittedly, it still calls for significant effort in large-scale engineering practices and integration with wider domain-specific scenarios.

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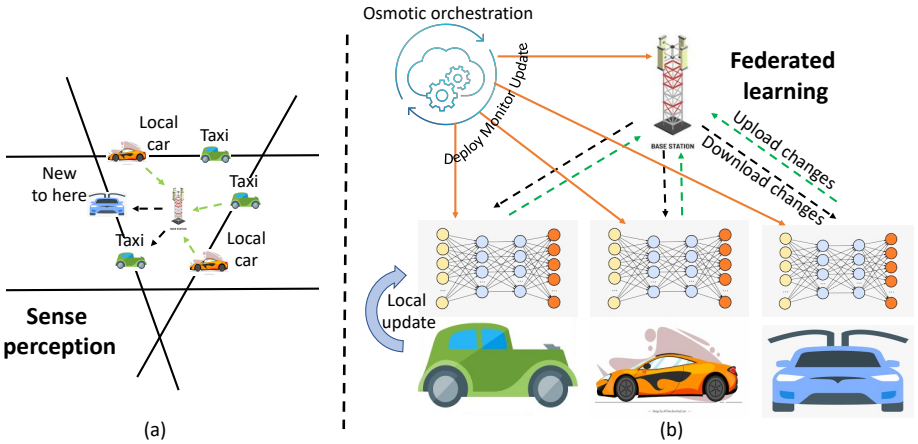

Fig. 5: Federated learning enabled CAV system architecture. CAV can update its sense perception model by interacting with the base station in close proximity, if the CAV is emerging or does not have the latest information of the road

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