

This is an Open Access document downloaded from ORCA, Cardiff University's institutional repository: <https://orca.cardiff.ac.uk/id/eprint/86769/>

This is the author's version of a work that was submitted to / accepted for publication.

Citation for final published version:

Baes, Michel, Oertel, Timm and Weismantel, Robert 2016. Duality for mixed-integer convex minimization. *Mathematical Programming* 158 , pp. 547-564. 10.1007/s10107-015-0917-y

Publishers page: <http://dx.doi.org/10.1007/s10107-015-0917-y>

Please note:

Changes made as a result of publishing processes such as copy-editing, formatting and page numbers may not be reflected in this version. For the definitive version of this publication, please refer to the published source. You are advised to consult the publisher's version if you wish to cite this paper.

This version is being made available in accordance with publisher policies. See <http://orca.cf.ac.uk/policies.html> for usage policies. Copyright and moral rights for publications made available in ORCA are retained by the copyright holders.



Duality for Mixed-Integer Convex Minimization

Michel Baes, Timm Oertel, and Robert Weismantel

April 7, 2015

Abstract

We extend in two ways the standard Karush-Kuhn-Tucker optimality conditions to problems with a convex objective, convex functional constraints, and the extra requirement that some of the variables must be integral. While the standard Karush-Kuhn-Tucker conditions involve separating hyperplanes, our extension is based on mixed-integer-free polyhedra. Our optimality conditions allow us to define an exact dual of our original mixed-integer convex problem.

1 Introduction

Several attempts have been made in the past to define formally a dual of a linear integer or mixed-integer programming problem. Let us first mention some important developments in this direction.

One idea to define a dual program associated with a binary linear integer programming problem is to encode the given 0/1-problem in form of a linear program in an extended space, so that the new variables correspond to linearizations of products of original variables. The variables of the dual of the resulting linear optimization program can be reinterpreted in terms of the original variables. This concept of duality has its origins in the work of [21, 22] and [16] and is closely connected with the earlier work of [3, 2] on disjunctive optimization. It also provides us an interesting link to the theory of polynomial optimization including duality results associated with hierarchies of semidefinite programming problems, see [13]. For a comprehensive survey treating the relationships and differences between several relaxations of this kind we refer to [14].

A second important development in integer optimization is based on the connections between valid inequalities and subadditive functions. This leads to a formalism that allows us to establish a subadditive dual of a general mixed integer linear optimization problem, see [9, 6, 7, 8, 10] and [19] for a treatment of the subject and further references. Recently, a strong subadditive dual for conic mixed integer optimization has been constructed in [17].

There are several other special cases for which the dual of a mixed integer optimization problem has been derived. One such example is based on the theory of discrete convexity established in [18]. Here, an explicit dual is constructed for L-convex and M-convex functions.

A third general approach to develop duality in several subfields of optimization is based on the Lagrangian relaxation method. The latter method is broadly applicable and – among others – leads to a formalism of duality in convex optimization. The connection between the Lagrangian dual and linear relaxations of linear integer optimization problems has its origins in [5]. This paper developed a combinatorial version of a Lagrangian relaxation in form of 1-trees for the traveling salesman problem. Since then there have been a large number of applications using this relaxation technique for integer optimization problems, see e.g. Chapter II.3 in [19].

Our point of departure is the strong duality theorem for convex optimization based on the Lagrangian relaxation method. We will show that optimality certificates and duality in convex optimization have a very natural mixed-integer analogue. A duality theory in Euclidean space follows from a precise interplay between points – that are viewed as primal objects – and level sets of linear functions, that is, closed half-spaces, interpreted as dual objects. It turns out that there is a similar interplay in the mixed-integer setting. Here, the primal objects are sets of points, whereas the dual objects are mixed-integer-free open polyhedra. Where a set is mixed-integer-free if its interior does not contain any mixed-integer point. (If $d = 0$, we just say that the set is integer-free.) Our motivation for studying optimality certificates and a mixed-integer convex dual comes from the important developments in convex optimization in the past decade. As a first step towards new mixed-integer convex algorithms, it seems natural to make an attempt of extending some of the basic convex optimization tools to the mixed-integer setting.

2 Mixed-integer optimality certificates

Let $f : \text{dom}(f) \mapsto \mathbb{R}$ be a continuous convex function. In order to simplify our exposition we may assume w.l.o.g. here that $\text{dom}(f) = \mathbb{R}^n$. Assume that f has a, not necessarily unique, minimizer x^* . Then a necessary and sufficient certificate for x^* to be a minimizer of f is that $0 \in \partial f(x^*)$, i.e. the zero-function is in the subdifferential of f at x^* . Hence

$$x^* = \underset{x \in \mathbb{R}^n}{\operatorname{argmin}} f(x) \iff 0 \in \partial f(x^*).$$

The question emerges how to obtain a certificate that a point $x^* \in \mathbb{Z}^n \times \mathbb{R}^d$ solves the corresponding mixed-integer convex problem

$$x^* = \underset{x \in \mathbb{Z}^n \times \mathbb{R}^d}{\operatorname{argmin}} f(x)? \tag{1}$$

Let us first explain the idea of our approach. By definition, $x^* = \underset{x \in \mathbb{Z}^n \times \mathbb{R}^d}{\operatorname{argmin}} f(x)$ if and only if

$$\{x \in \mathbb{Z}^n \times \mathbb{R}^d \mid f(x) < f(x^*)\} = \emptyset. \tag{2}$$

The level set $\{x \in \mathbb{R}^{n+d} \mid f(x) \leq f(x^*)\}$ is convex. If it is nonempty, then its projection to its first n components, that is, to the subspace spanned by the integer variables is again a convex set. Clearly, $x^* = \underset{x \in \mathbb{Z}^n \times \mathbb{R}^d}{\operatorname{argmin}} f(x)$ if and only if

$$Q := \{z \in \mathbb{R}^n \mid \exists y \in \mathbb{R}^d, x = (z, y) \text{ and } f(x) < f(x^*)\} \cap \mathbb{Z}^n = \emptyset.$$

From a theorem of Lovasz, inclusionwise maximal integer-free convex sets are polyhedra [15]: we can restrict our attention to such polyhedra P that contain the (convex) projection Q . From the theorem of Doignon [4], it follows that a subset of at most 2^n inequalities in the description of P are enough to prove that $\text{int}(P) \cap \mathbb{Z}^n = \emptyset$. It remains to show how to relate these 2^n inequalities to the function f . The following theorem, which is an immediate consequence of our Theorem 5 proved at the end of this section, clarifies this relationship, providing a necessary and sufficient condition for our original mixed-integer convex problem.

Each of these 2^n inequalities is related to a mixed-integer point, the set of which constitutes our *optimality certificate*. The verification of this optimality certificate can be performed in polynomial time, provided that the number of integer variables is a constant.

Throughout this paper we make the following assumption.

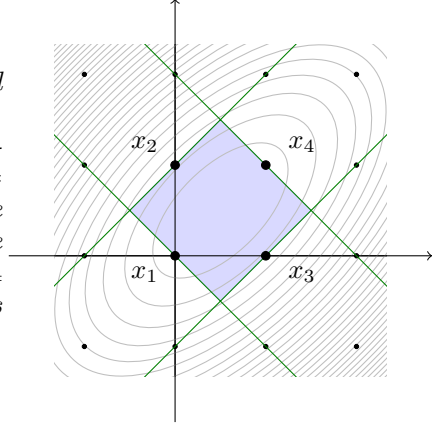
Assumption 1. Given a convex minimization problem, either (1) or its constrained version (3), we assume that the set of continuous minima exists and is bounded. Note that this implies that the feasible domain intersected with any level-set is bounded.

Theorem 2. $x^* = \operatorname{argmin}_{x \in \mathbb{Z}^n \times \mathbb{R}^d} f(x)$ if and only if there exist $k \leq 2^n$ points $x_1 = x^*, x_2, \dots, x_k \in \mathbb{Z}^n \times \mathbb{R}^d$ and vectors $h_i \in \partial f(x_i)$ such that the following conditions hold:

- (a) $f(x_1) \leq \dots \leq f(x_k)$.
- (b) $\{x \in \mathbb{R}^{n+d} \mid h_i^\top (x - x_i) < 0 \text{ for all } i\} \cap (\mathbb{Z}^n \times \mathbb{R}^d) = \emptyset$.
- (c) $h_i \in \mathbb{R}^n \times \{0\}^d$ for $i = 1, \dots, k$.

Condition (a) ensures that x^* is one of the points of the optimality certificate and is the best of them. Also, in view of Condition (c), every point $(z, y)^\top$ in the certificate minimizes f on its own fiber, that is, in the set $\{z\} \times \mathbb{R}^d$. Finally, the subgradient of f at each point of the certificate defines a half-space. The interior of their intersection plays the role of a polyhedron whose projection on the first n components is the P described above. Condition (b) ensures that this interior is mixed-integer-free.

Example 3. We consider the function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ defined as $f(x) := \|Ax - c\|_2^2$, where $A := \begin{pmatrix} 2 & -2 \\ 1 & 1 \end{pmatrix}$ and $c := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$. The continuous minimum of f is attained at the non-integer point $(1/2 \ 1/2)^\top$. We choose $x_1 = (0 \ 0)^\top, x_2 = (0 \ 1)^\top, x_3 = (1 \ 0)^\top$ and $x_4 = (1 \ 1)^\top$ and we define $P = \{x \in \mathbb{R}^2 \mid h_i^\top x \leq h_i^\top x_i, i = 1, \dots, 4\}$, where $h_i = \nabla f(x_i)$. It holds that $f(x_1) \leq f(x_i)$ for $i = 2, 3, 4$ and $\operatorname{int}(P) \cap \mathbb{Z}^2 = \emptyset$ (see Figure). Then Theorem 2 implies that $x_1 = \operatorname{argmin}_{z \in \mathbb{Z}^2} f(z)$.



As announced, we formulate and prove a version of the above theorem that takes possible convex functional constraints to problem (1) into account.

Let $g_1, \dots, g_m : \operatorname{dom}(f) \mapsto \mathbb{R}$ be continuous convex functions. Again we may assume w.l.o.g. that $\operatorname{dom}(g_j) = \mathbb{R}^n$ for all j . By $g(x)$ we denote the vector of components $g_1(x), \dots, g_m(x)$. Let us first discuss the continous convex optimization problem

$$x^* = \operatorname{argmin}_{\substack{x \in \mathbb{R}^n, \\ g(x) \leq 0}} f(x). \quad (3)$$

Assume that there exists a feasible point $y \in \mathbb{R}^n$ fulfilling the so-called Slater condition, that is, $g_i(y) < 0$ for all functions g_i that are not affine linear. Under this assumption the Karush-Kuhn-Tucker (KKT) conditions (e.g. [11, 12]) provide necessary and sufficient optimality conditions. Namely, the point x^* such that $g(x^*) \leq 0$ attains the optimal continuous solution if and only if there exist $h_f \in \partial f(x^*)$, $h_{g_i} \in \partial g_i(x^*)$, for $i = 1, \dots, m$ and non-negative λ_i , $i = 1, \dots, m$, such that

$$h_f + \sum_{i=1}^m \lambda_i h_{g_i} = 0 \text{ and } \lambda_i g_i(x^*) = 0 \ \forall i. \quad (4)$$

Note that in this representation it suffices to consider only those $g_i(x^*)$ that are binding, i.e. $\lambda_i \neq 0$, and for which the corresponding h_{g_i} are linearly independent.

It is our intention to generalize these optimality conditions to the mixed-integer setting

$$x^* = \underset{\substack{x \in \mathbb{Z}^n \times \mathbb{R}^d, \\ g(x) \leq 0}}{\operatorname{argmin}} f(x). \quad (5)$$

We first generalize the Slater condition.

Definition 4. *We say that the constraints $g(x) \leq 0$ fulfill the mixed-integer Slater condition if for every point $(z, y) \in \mathbb{Z}^n \times \mathbb{R}^d$ with $g((z, y)) \leq 0$ there exists a $y' \in \mathbb{R}^d$ such that $g((z, y')) \leq 0$ and $g_i((z, y')) < 0$ for every function g_i that is not affine linear.*

Under the assumption of the mixed-integer Slater condition, we next formulate and justify mixed-integer optimality conditions.

Similarly to the unconstrained case, one implication of this result is that the optimality of a mixed-integer point can be verified in polynomial time, provided that the number of integer variables is a constant.

Theorem 5. *Let g fulfill the mixed-integer Slater condition. A point $x^* \in \mathbb{Z}^n \times \mathbb{R}^d$ is optimal for the mixed-integer constrained problem (5) if and only if $g(x^*) \leq 0$ and there exist $k \leq 2^n$ points $x_1 = x^*, x_2, \dots, x_k \in \mathbb{Z}^n \times \mathbb{R}^d$ and k vectors $u_1, \dots, u_k \in \mathbb{R}_+^{m+1}$ with corresponding $h_{i,m+1} \in \partial f(x_i)$, and $h_{i,j} \in \partial g_j(x_i)$ for $j = 1, \dots, m$ and $i = 1, \dots, k$ such that the following five conditions hold:*

- (a) *If $g(x_i) \leq 0$ then $f(x_i) \geq f(x^*)$, $u_{i,m+1} > 0$ and $u_{i,j}g_j(x_i) = 0$ for $j = 1, \dots, m$.*
- (b) *If $g(x_i) \not\leq 0$ then $u_{i,m+1} = 0$ and $u_{i,j} = 0$ for all $j \notin I_i := \{1 \leq j \leq m : g_j(x_i) = \max_{1 \leq \ell \leq m} g_\ell(x_i)\}$.*
- (c) *$1 \leq |\operatorname{supp}(u_i)| \leq d + 1$ for $i = 1, \dots, k$.*
- (d) *$\{x \in \mathbb{R}^{n+d} \mid \sum_{j=1}^{m+1} u_{i,j} h_{i,j}^\top (x - x_i) < 0 \text{ for all } i\} \cap (\mathbb{Z}^n \times \mathbb{R}^d) = \emptyset$.*
- (e) *$\sum_{j=1}^{m+1} u_{i,j} h_{i,j} \in \mathbb{R}^n \times \{0\}^d$ for $i = 1, \dots, k$.*

As in the unconstrained situation, a certificate is given by a list of $k \leq 2^n$ mixed-integer points x_1, x_2, \dots, x_k . Our substitute for the nonnegative multipliers λ are k nonnegative vectors u_1, \dots, u_k of size $m + 1$. Condition (c) asserts that none of these vectors is null; their maximal sparsity is a consequence of Caratheodory's Theorem. As in Theorem 2, Condition (e) indicates that the points of the certificate are optimal in their own fiber. Condition (a) ensures that the mixed-integer optimum x^* is in the certificate, and is the best among all those that are in it. The additional complementarity conditions are inherited from the continuous KKT theorem quoted above. Among the certificate points x_2, \dots, x_k , several might be infeasible for the primal problem. Let us define the set $I_i := \{1 \leq j \leq m \mid g_j(x_i) = \max_{1 \leq \ell \leq m} g_\ell(x_i)\}$ for every $1 \leq i \leq k$. Condition (b) addresses infeasible points x_i in the certificate, that is, those for which $g_j(x_i) > 0$ for any $j \in I_i$. It ensures that $u_{i,j} > 0$ only when $j \notin I_i$. (Note that the complementarity condition for feasible points x_i 's in Condition (a) can be expressed identically). The mixed-integer-freeness Condition (d) is the natural extension of Condition (b) in Theorem 2.

Proof. In order to prove the first implication, we assume that x^* is optimal. Let X^* denote the set of all optimal solutions to (5). If there exists a point $x \in X^*$ with $0 \in \partial f(x)$, then the theorem follows directly from the purely continuous version of the KKT conditions described

above; we can also take $k = 1$. Next, assume there exist an $x \in X^* \cap \text{int}(\text{conv}(X^*))$ and $h_x \in \partial f(x)$ such that $h_x \neq 0$. By convexity, f must be constant on $\text{conv}(X^*)$, contradicting that $h_x \neq 0$. This implies that if $X^* \cap \text{int}(\text{conv}(X^*)) \neq \emptyset$, then $0 \in \partial f(x)$ for all $x \in X^*$. Hence, let us assume that $X^* \cap \text{int}(\text{conv}(X^*)) = \emptyset$ and that $0 \notin \partial f(x)$ for all $x \in X^*$.

For every $z \in \mathbb{Z}^n$ we consider the following continuous convex subproblem,

$$\min_{\substack{y \in \mathbb{R}^d, \\ g((z, y)) \leq 0}} f((z, y)). \quad (6)$$

We distinguish two cases.

(i) **Problem (6) is infeasible.** Let us define

$$y_z := \operatorname{argmin}_{y \in \mathbb{R}^d} \max_{1 \leq i \leq m} g_i((z, y)).$$

Let $I_z := \{1 \leq j \leq m \mid g_j((z, y_z)) = \max_{1 \leq i \leq m} g_i((z, y_z))\}$. Since y_z is an optimal solution to an unconstrained convex problem, there exists a vector $h_z \in \partial \max_{1 \leq i \leq m} g_i((z, y_z)) = \text{conv}(\{\partial g_{i,z}((z, y_z)) \mid i \in I_z\})$ such that $h_z \in \mathbb{R}^n \times \{0\}^d$ [20, Lemma 3.1.10]. We can write

$$h_z = \sum_{j=1}^m u_{z,j} h_{z,j}$$

with $u_{z,j} \geq 0$ for $j \in I_z$, $u_{z,j} = 0$ for $j \notin I_z$, $\sum_{j \in I_z} u_{z,j} = 1$ and $h_{z,j} \in \partial g_j((z, y_z))$ for $j = 1, \dots, m$. We also define $u_{z,m+1} := 0$. From Caratheodory's Theorem it follows that we can choose $u_z = (u_{1,z}, \dots, u_{m,z}, u_{z,m+1}) = (u_{1,z}, \dots, u_{m,z}, 0)$ such that $|\text{supp}(u_z)| \leq d + 1$. We verify Conditions (b), (c), and (e).

(ii) **Problem (6) is feasible.** We define

$$y_z := \operatorname{argmin}_{y \in \mathbb{R}^d} \{f((z, y)) \mid g((z, y)) \leq 0\}.$$

Since by our initial assumption x^* is optimal, it follows that $f((z, y_z)) \geq f(x^*)$. From Slater's condition, we can apply the standard continuous KKT conditions. There exists a vector of multipliers $u_z \in \mathbb{R}_+^{m+1}$, a vector $h_{z,m+1} \in \partial f((z, y_z))$, and vectors $h_{z,j} \in \partial g_j((z, y_z))$ for $j = 1, \dots, m$ such that

$$u_{z,m+1} > 0, \quad u_{z,j} g_j((z, y_z)) = 0 \text{ for } j = 1, \dots, m.$$

Condition (a) would thereby be verified whatever fiber minimizer we would take in our certificate.

Furthermore, the KKT conditions imply also that $\sum_{j=1}^{m+1} u_{z,j} h_{z,j} \in \mathbb{R}^n \times \{0\}^d$, which will lead to Condition (e).

Note that $u_{z,m+1} > 0$ implies that $|\text{supp}(u)| \geq 1$. Caratheodory's Theorem implies that we can choose u such that $|\text{supp}(u)| \leq d + 1$, which will yield Condition (c).

It remains to verify Condition (d) for both cases. To this end, we define

$$h_z := \sum_{j=1}^{m+1} u_{z,j} h_{z,j} \in \mathbb{R}^n \times \{0\}^d$$

and the open half-space

$$L_z := \{(z', y') \in \mathbb{R}^n \times \mathbb{R}^d \mid h_z^\top((z', y') - (z, y_z)) < 0\}. \quad (7)$$

Note that the half-spaces are well defined, because h_z is always different from zero. This case was handled in the beginning of this proof. Since the last d components of h_z are null, (z', y') belongs to L_z if and only if the whole fiber containing z' belongs to L_z . So, the fiber of z does not belong to L_z because $(z, y_z) \notin L_z$.

Suppose now that (z', y') is a (continuous) feasible point that does not belong to L_z . Then $f((z', y')) \geq f((z, y_z))$. Indeed, we first have:

$$0 \geq \sum_{j=1}^m u_{z,j} g_j(z', y') = \sum_{j=1}^m u_{z,j} (g_j(z', y') - g_j(z, y_z)) \geq \sum_{j=1}^m u_{z,j} h_{z,j}^\top ((z', y') - (z, y_z)),$$

where we have used successively the nonnegativity of the multipliers $u_{z,j}$, the complementarity conditions, and the convexity of the functions g_j . Since $u_{z,m+1} > 0$, we deduce that:

$$0 \leq h_{z,m+1}^\top ((z', y') - (z, y_z)) \leq f((z', y')) - f((z, y_z)) \quad (8)$$

as announced.

Therefore, the intersection $L := \bigcap_{z \in \mathbb{Z}^n} L_z$ is mixed-integer-free and contains every feasible point $(z, y) \in \mathbb{R}^n \times \mathbb{R}^d$ for which $f((z, y)) < f(x^*)$. We have excluded at the beginning of this proof the situations where L could be empty.

It follows from [4] and our Assumption 1, that a sub-selection of $k \leq 2^n$ inequalities $h_{z_i}^\top y < h_{z_i}^\top z_i$, $i = 1, \dots, k$ suffices to describe a polyhedron containing L that does not contain any integer point in its interior.¹ By (8), one of those k points has to be a solution x^* to our mixed-integer problem. Then we obtain the desired certificate by defining $x_1 = x^*$, $x_2 = (z_2, y_{z_2}), \dots, x_k = (z_k, y_{z_k})$. Note that we have written h_i for h_{z_i} in the theorem's statement.

All the conditions are now satisfied.

To prove the other direction, let x_1, \dots, x_k be the points in the certificate, and consider the open polyhedron:

$$P := \{x \in \mathbb{R}^{n+d} \mid \sum_{j=1}^{m+1} u_{i,j} h_{i,j}^\top (x - x_i) < 0 \text{ for all } i = 1, \dots, m\},$$

with $h_{i,j}$ as defined in the statement of the Theorem. We assume that Conditions (a) – (e) are satisfied. In particular, P is mixed-integer-free. Let $\bar{x} \in \mathbb{Z}^n \times \mathbb{R}^d$. Then \bar{x} must violate at least one inequality of P , say the i -th inequality, i.e.,

$$\sum_{j=1}^{m+1} u_{i,j} h_{i,j}^\top (\bar{x} - x_i) \geq 0.$$

Since $v := \sum_{j=1}^{m+1} u_{i,j} h_{i,j}$ is a subdifferential of the convex function $\psi(x) := u_{i,m+1} f(x) + \sum_{j=1}^m u_{i,j} g_j(x)$ at x_i , the minimum of $\psi(x)$ over the half-space $\{x \mid v^\top (x - x_i) \geq 0\}$ is precisely x_i .

Assume $g(x_i) \not\leq 0$. Since $u_{i,m+1} = u_{i,j} = 0$ for all $j \notin I_i$, we get

$$0 \leq \sum_{j \in I_i} u_{i,j} h_{i,j}^\top (\bar{x} - x_i) \leq \sum_{j \in I_i} u_{i,j} (g_j(\bar{x}) - g_{\max}(x_i)),$$

with $g_{\max}(x_i) := \max_{1 \leq j \leq m} g_j(x_i)$, from which we deduce that \bar{x} is not feasible.

¹We provide all the details of this assertion in the appendix.

Assume now that $g(x_i) \leq 0$. Then $u_{i,j}g_j(x_i) = 0$, so

$$\begin{aligned} 0 \leq \sum_{j=1}^{m+1} u_{i,j} h_{i,j}^\top (\bar{x} - x_i) &\leq \sum_{j=1}^m u_{i,j} (g_j(\bar{x}) - g_j(x_i)) + u_{i,m+1} (f(\bar{x}) - f(x_i)) \\ &= \sum_{j=1}^m u_{i,j} g_j(\bar{x}) + u_{i,m+1} (f(\bar{x}) - f(x_i)). \end{aligned}$$

So, if \bar{x} is feasible, the sum of the m first terms above is nonpositive, and $f(\bar{x}) \geq f(x_i)$. Thus the best point x^* among those in the certificate must be optimal. \square

Remark 6. Note that Assumption 1 is necessary. Consider the problem $\inf\{x_2 \mid g(x_1, x_2) = e^{x_1} - x_2 \leq 0\}$, if we assume that $x_1, x_2 \in \mathbb{R}$, then the infimum is 0. This infimum is not attained by any point, i.e., the problem is unbounded. On the other hand, if we require $x_1, x_2 \in \mathbb{Z}$, then the infimum is 1 and it is attained at any point of the form $x^* = (x_1, 1)^\top$ with $x_1 \in \mathbb{Z}_-$. However, Theorem 5 cannot be applied: the integer-free set would have a face contained in the line $\{(t, 1)^\top : t \in \mathbb{R}\}$. Also, $\frac{\partial g}{\partial x_1}(x) > 0$ for all x . Thus, no finite number of the integer points $(x_1, x_2)^\top$ with $x_2 \leq 0$ can cut all the integer points of $\{(t, 1)^\top : t < 0\}$.

As an application of the above theorem, let us consider the mixed-integer Euclidean Projection problem:

$$y^* = \arg \min\{\|x - y\|_2 \mid g(x) \leq 0, x \in \mathbb{R}^n \times \mathbb{Z}^d\}, \quad (9)$$

for a given point $y \in \mathbb{R}^{n+d}$.

The continuous version of this problem has a unique solution, say y_{cont} , which satisfies the so-called *projection condition*:

$$\text{for all feasible } x, \quad (y - y_{\text{cont}})^\top (x - y_{\text{cont}}) \leq 0.$$

Observe that this projection condition implies:

$$\text{for all feasible } x, \quad \|x - y\|_2 \geq \|x - y_{\text{cont}}\|_2.$$

Corollary 7. Assume that the feasible set fulfills the mixed-integer Slater's condition. The certificate x_1, \dots, x_k given for the problem (9) satisfies the projection property:

$$\text{for all mixed-integer feasible } x \text{ there exists } 1 \leq i \leq k \text{ for which } (y - x_i)^\top (x - x_i) \leq 0,$$

and

$$\text{for all mixed-integer feasible } x \text{ there exists } 1 \leq i \leq k \text{ for which } \|x - y\|_2 \geq \|x - x_i\|_2.$$

Proof. We denote by S the feasible set $\{x \in \mathbb{R}^{n+1} \mid g(x) \leq 0\}$. Theorem 5 for $f(x) := \|x - y\|_2^2/2$ provides us with a certificate of points x_1, \dots, x_k , its accompanying set of nonnegative vectors u_i and subgradients $h_{i,j}$. Let $x \in S \cap (\mathbb{Z}^n \times \mathbb{R}^d)$. By Condition (d), the point x violates at least one of the inequalities describing the open mixed-integer-free polyhedron, say $\sum_{j=1}^{m+1} u_{i,j} h_{i,j}^\top (x - x_i) \geq 0$

for some $i = 1, \dots, k$. This implies that since x is feasible x_i must be feasible as well and therefore, by Condition (a), we know that $u_{i,m+1} > 0$. Thus:

$$\begin{aligned}
0 &\leq \sum_{j=1}^m u_{i,j} h_{i,j}^\top (x - x_i) + u_{i,m+1} h_{i,m+1}^\top (x - x_i) \\
&\leq \sum_{j=1}^m u_{i,j} (g_j(x) - g_j(x_i)) + u_{i,m+1} (x_i - y)^\top (x - x_i) \\
&= \sum_{j=1}^m u_{i,j} g_j(x) + u_{i,m+1} (x_i - y)^\top (x - x_i) \\
&\leq u_{i,m+1} (x_i - y)^\top (x - x_i).
\end{aligned}$$

The second inequality in the Corollary's statement comes readily from:

$$\|x - y\|_2^2 = \|x - x_i\|_2^2 + \|x_i - y\|_2^2 + 2(x_i - y)^\top (x - x_i) \geq \|x - x_i\|_2^2 + \|x_i - y\|_2^2.$$

□

The following theorem characterizes another set of optimality conditions. We use here a larger set of points in the certificate, and therefore a more complex mixed-integer-free polyhedron. Moreover, these points do not necessarily belong to the lattice. However, the Slater condition becomes much simpler to verify.

Theorem 8. *Assume the standard Slater's condition: there exists a point $s \in \mathbb{R}^{n+d}$ such that $g(s) < 0$. A point $x^* \in \mathbb{Z}^n \times \mathbb{R}^d$ is optimal with respect to (5) if and only if*

- (a) $g(x^*) \leq 0$,
- (b) *there exist $k + l \leq 2^n(d + 1)$ points $x_1 = x^*, x_2, \dots, x_k$ and y_1, \dots, y_l in \mathbb{R}^{n+d} such that $f(x_i) \geq f(x^*)$ for $i = 1, \dots, k$ and $g(y_i) \leq 0$ for $i = 1, \dots, l$,*
- (c) *there exist numbers $1 \leq j_1, \dots, j_l \leq m$ such that $g_{j_i}(y_i) = 0$ and there exist subgradients $h_{x_i} \in \partial f(x_i)$ and $h_{y_i} \in \partial g_{j_i}(y_i)$ such that*

$$\begin{aligned}
P := \{x \in \mathbb{R}^{n+d} \mid & h_{x_i}^\top x < h_{x_i}^\top x_i \text{ for all } i = 1, \dots, k, \\
& h_{y_i}^\top x \leq h_{y_i}^\top y_i \text{ for all } i = 1, \dots, l\}
\end{aligned}$$

is mixed-integer-free.

Proof. Let X^* denote the set of all optimal solutions. We can assume that X^* is not empty, for otherwise the statement holds vacuously. In view of Slater's condition, the case where a point of X^* coincides with a continuous optimum corresponds to the continuous KKT conditions (4), which imply the stated optimality certificate: if all the Lagrange multipliers are null, we simply take $k = 1, l = 0, x_1 = x^*$ to ensure that the set P is empty; if the Lagrange multipliers are not all null, we take $k = l = 1, x_i = y_1 = x^*$, and, using the notation of (4), we take $h_{y_1} := \sum_{j=1}^m \lambda_j h_{g_j} / \sum_{j=1}^m \lambda_j$ to get an empty P .

Therefore, we assume without loss of generality that no $x^* \in X^*$ has a nonnegative $\lambda \in \mathbb{R}^m$ that satisfies the KKT conditions (4). Using the argument of the proof of Theorem 5, we can assume that $X^* \cap \text{int}(\text{conv}(X^*))$ is empty.

Denote by L the level set $L := \{x \in \mathbb{R}^{n+d} \mid f(x) \leq f(x^*)\}$, where $x^* \in X^*$, and by S_1, \dots, S_m the sets $S_j := \{x \in \mathbb{R}^{n+d} \mid g_j(x) \leq 0\}$, whose intersection S is the feasible set. Thus $X^* = L \cap S \cap (\mathbb{Z}^n \times \mathbb{R}^d)$.

In fact, our assumptions ensure that $\text{int}(L) \cap S \cap (\mathbb{Z}^n \times \mathbb{R}^d)$ is empty. Suppose otherwise and take a point $x^* \in X^*$ that would be in the above set. Then there exists a closed ball B centered in x^* and contained in L . By convexity, the maximum of f on B is attained on $\text{bd}(B)$ and cannot exceed $f(x^*)$. Hence the function f is constant on B , so that $f'(x^*) = 0$. Taking $\lambda := 0$ shows that x^* satisfies the continuous KKT conditions, a contradiction.

Since f and g are continuous, L and S are closed. Additionally, the existence of a point \hat{x} with $f(\hat{x}) < f(x^*)$ — because $0 \notin \partial f(x^*)$ — allows us to describe L as the intersection of half-spaces defined by its boundary points and their corresponding subdifferentials:

$$L = \bigcap_{\substack{z \in \text{bd}(L), \\ h \in \partial f(z)}} \{x \in \mathbb{R}^{n+d} \mid h^\top x \leq h^\top z\}. \quad (10)$$

The interior of L is easily seen to coincide with:

$$\bigcap_{\substack{z \in \text{bd}(L), \\ h \in \partial f(z)}} \{x \in \mathbb{R}^{n+d} \mid h^\top x < h^\top z\}.$$

Similarly, in view of Slater's conditions, every set S_j can be described as:

$$S_j = \bigcap_{\substack{z \in \text{bd}(S_j), \\ h \in \partial g_j(z)}} \{x \in \mathbb{R}^{n+d} \mid h^\top x \leq h^\top z\},$$

so that S is:

$$S = \bigcap_{j=1}^m \bigcap_{\substack{z \in \text{bd}(S_j), \\ h \in \partial g_j(z)}} \{x \in \mathbb{R}^{n+d} \mid h^\top x \leq h^\top z\} = \bigcap_{j=1}^m \bigcap_{\substack{z \in \text{bd}(S_j) \cap S, \\ h \in \partial g_j(z)}} \{x \in \mathbb{R}^{n+d} \mid h^\top x \leq h^\top z\}.$$

It follows from [1], the Assumption 1 and the compactness of the boundary, that a subset of $2^n(d+1)$ half-spaces suffice in order to guarantee that the corresponding intersection remains mixed-integer-free². Without loss of generality, we can choose one of the supporting half-spaces in this description (see the construction in [1]); thus, we can take the inequality in the description of L corresponding to x^* for x_1 .

To prove the other direction, let $x_1, \dots, x_k, y_1, \dots, y_l$ be the points of the certificate and consider the mixed-integer-free set P given by the statement of the theorem. Let $x \in \mathbb{Z}^n \times \mathbb{R}^d$. Then x violates one of the inequalities in the description of P . If that violated inequality is of the form $h_{x_i}^\top x < h_{x_i}^\top x_i$, for a point x_i in $\text{bd}(L)$, then we have $f(x) \geq f(x_i) + h_{x_i}^\top (x - x_i) \geq f(x_i) = f(x^*)$ and x cannot be better than x^* . Otherwise the violated inequality is of the form $h_{y_i}^\top x \leq h_{y_i}^\top y_i$, for a point y_i in $\text{bd}(S_{j_i})$ and a subgradient $h_{y_i} \in \partial g_{j_i}(y_i)$. Since $g_{j_i}(y_i) = 0$, we have

$$0 < h_{y_i}^\top (x - y_i) = g_{j_i}(y_i) + h_{y_i, j}^\top (x - y_i) \leq g_{j_i}(x),$$

so x is not feasible and therefore not a solution to our problem. \square

3 The mixed-integer convex dual

In the purely continuous setting, it is not too difficult to apply the KKT-theorem in order to show a duality theorem. Provided that the standard Slater condition holds, that all functions

²We relegate the proof of that fact in the appendix.

f and g_j , $j = 1, \dots, m$ are continuous and convex, and that the primal and dual feasible sets are nonempty, one has

$$f^* = \min_{x \in \mathbb{R}^n} \{ f(x) \mid g(x) \leq 0 \} = \alpha^* := \max_{\alpha, u \in \mathbb{R}_+^m} \{ \alpha \mid \alpha \leq f(x) + u^\top g(x) \quad \forall x \in \mathbb{R}^n \}. \quad (11)$$

In other words, any multiplier $u \geq 0$ gives rise to an unconstrained convex optimization problem $\alpha = \min \{ f(x) + u^\top g(x) \mid x \in \mathbb{R}^n \}$ whose optimum is a lower bound on the optimal primal value f^* . The naive extension of the continuous convex dual would be to replace \mathbb{R}^n in (11) everywhere by $\mathbb{Z}^n \times \mathbb{R}^d$. This is not correct, though.

Example 9. Let $n = m = 2$, $d = 0$, $f(x) = \frac{1}{2} \|x - \mathbf{1}\|_2^2$, $g_1(x) = x_1 - \frac{1}{2}$, and $g_2(x) = x_2 - \frac{1}{2}$, where $\mathbf{1}$ is the all-one vector. The optimal integer point is $x^* = 0$, so $f(x^*) = 1$. However,

$$f(x) + u^\top g(x) = \frac{1}{2} \|x - \mathbf{1}\|_2^2 + u_1 x_1 + u_2 x_2 - \frac{1}{2}(u_1 + u_2).$$

Note that $f(x) + u^\top g(x)$ equals $\frac{1}{2} + \frac{u_1 - u_2}{2}$ at $x = (1, 0)^\top$ and $\frac{1}{2} + \frac{u_2 - u_1}{2}$ at $x = (0, 1)^\top$. Then

$$\begin{aligned} \alpha^* &= \max_{\alpha, u \in \mathbb{R}_+^2} \{ \alpha \mid \alpha \leq f(x) + u^\top g(x) \quad \forall x \in \mathbb{Z}^2 \} \\ &\leq \max_{\alpha, u \in \mathbb{R}_+^2} \{ \alpha \mid \alpha \leq f(x) + u^\top g(x) \quad \forall x \in \{(1, 0)^\top, (0, 1)^\top\} \} = \frac{1}{2}. \end{aligned}$$

Instead of using just one multiplier per constraint, our dual, as in our KKT Theorem 5 for mixed-integer problems, must use a selection of up to 2^n multipliers per constraint. To every mixed integer point is associated one multiplier of the selection. We denote the function that describes this association as $\pi : \mathbb{Z}^n \times \mathbb{R}^d \mapsto \{1, \dots, 2^n\}$.

Formally, let (6) denote the primal problem. Then, the dual object is the pair of the function π and the matrix $U \in \mathbb{R}_+^{2^n \times m}$ that pile up the multipliers. Here is a geometrical interpretation of that dual object. Consider a polyhedron $P = \{x \in \mathbb{R}^{n+d} \mid Ax \leq b\}$, where $A \in \mathbb{R}^{2^n \times (n+d)}$ and $b \in \mathbb{R}^{2^n}$ with a mixed-integer-free interior that contains the continuous optimum and suppose that we are given vectors $U_i \in \mathbb{R}_+^m$ associated to each row of $Ax \leq b$. We can use this polyhedron and these nonnegative vectors to generate a lower bound α for the original minimization problem (5) as follows. For each $i = 1, \dots, 2^n$, we consider the continuous convex problem

$$\min_{x \in \mathbb{R}^{d+n}} \{ U_i g(x) \mid A_i x \geq b_i \}. \quad (12)$$

If the half-space $\{x \in \mathbb{R}^{d+n} \mid A_i x \geq b_i\}$ contains feasible points, the optimal value of (12) is non-positive. Denote by I_P the set of indices i of all those half-spaces containing feasible points. We can write:

$$f(x^*) \geq \alpha_{P,U} = \min_{i \in I_P} \left\{ \min_{x \in \mathbb{R}^{d+n}} f(x) + U_i g(x) \mid A_i x \geq b_i \right\}.$$

These lower bounds lead to the mixed integer duality result stated below.

Theorem 10. Let $f : \mathbb{R}^{n+d} \mapsto \mathbb{R}$ and $g : \mathbb{R}^{n+d} \mapsto \mathbb{R}^m$ be convex functions, and assume that the mixed-integer feasible set $\{x \in \mathbb{Z}^n \times \mathbb{R}^d \mid g(x) \leq 0\}$ is non-empty, compact and contained in the domain of f . Further, assume that g fulfills the mixed-integer Slater condition. Then $\min \{ f(x) \mid g(x) \leq 0, x \in \mathbb{Z}^n \times \mathbb{R}^d \}$ equals:

$$\max_{\substack{\alpha \in \mathbb{R} \\ U \in \mathbb{R}_+^{2^n \times m}}} \{ \alpha \mid \exists \pi : \mathbb{Z}^n \times \mathbb{R}^d \mapsto \{1, \dots, 2^n\} \text{ satisfying:}$$

$$\forall x \in \mathbb{Z}^n \times \mathbb{R}^d \text{ we have } \alpha \leq f(x) + U_{\pi(x)} g(x) \text{ or } 1 \leq U_{\pi(x)} g(x) \},$$

where U_i denotes the i -th row of U .

Proof. We call the minimization problem the primal problem and the maximization problem the dual problem. The assumptions regarding f and g guarantee that there exists a feasible point x^* such that $f(x^*)$ attains the primal optimum. Then, for any $u \in \mathbb{R}_+^m$ we obtain using the point x^* as a condition on the optimal dual value,

$$\alpha \leq f(x^*) + u^\top g(x^*) \leq f(x^*).$$

This bound on α guarantees that the optimal dual solution must be less or equal than the primal value.

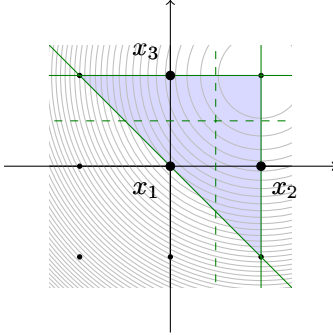
To show the other direction we apply Theorem 5 using the same notation. Since x^* is optimal it follows from Theorem 5 that there exist u_1, \dots, u_k fulfilling the conditions in Theorem 5. If $u_{i,m+1} > 0$, we define $U_{i,j} := \frac{u_{i,j}}{u_{i,m+1}}$ for $j = 1, \dots, m$. Otherwise, $u_{i,m+1} = 0$ and we define $U_{i,j} := \frac{u_{i,j}}{\mu_i}$ for $j = 1, \dots, m$, where $\mu_i := \sum_{j=1}^m u_{i,j} g_j(x_i)$. Note that, if $k < 2^n$ we can introduce artificial redundant rows $U_i = U_k$ for $i = k+1, \dots, 2^n$. Now, we define π as follows: $\pi(x) := \min\{i \mid \sum_{j=1}^{m+1} u_{i,j} h_{i,j}^\top(x - x_i) \geq 0\}$. The mixed-integer-freeness of the set P in the statement of Theorem 5 shows that this function is well-defined for every point in $\mathbb{Z}^n \times \mathbb{R}^d$. If x happens to be infeasible, then $\sum_{i=1}^m u_{i,j} g_j(x_i) > 0$, i.e., $U_i g(x) \geq 1$. If x is feasible, then $u_{i,m+1} > 0$ and

$$f(x) + U_i g(x) = f(x) + \sum_{j=1}^m \frac{u_{i,j}}{u_{i,m+1}} (g_j(x) - g_j(x_i)) \geq f(x_i) + \sum_{j=1}^{m+1} \frac{u_{i,j}}{u_{i,m+1}} h_{i,j}^\top(x - x_i) \geq f(x_i) \geq f(x^*).$$

We conclude that the primal and the dual solution attain the same objective function value. \square

Example 11. Let us apply the above theorem to the problem given in Example 9. The integer Slater condition holds. We see that the certificate $x_1 := (0, 0)^\top$, $x_2 := (1, 0)^\top$, $x_3 := (0, 1)^\top$ along with the vectors $u_1 := (0, 0, 1)^\top$, $u_2 := (1, 0, 0)^\top$, $u_3 := (0, 1, 0)^\top$, satisfy the statement of Theorem 5; indeed x_1 is the only feasible point, where the constraints are satisfied strictly. The two other points violate only one constraint. Then, the corresponding integer-free set is

$$P = \left\{ x \in \mathbb{R}^n \mid \begin{pmatrix} -1 & -1 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} x \leq \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}.$$



See the figure for an illustration.

Next, we illustrate how to apply Theorem 10. We choose the matrix U corresponding to our multipliers u as: $\begin{pmatrix} 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \end{pmatrix}^\top$. Note that the fourth row is a dummy one as we will never use it. Further we set the assignment function π to:

$$\pi(x) = \begin{cases} 1 & \text{if } (-1 \ -1)x \geq 0 \\ 2 & \text{else if } (1 \ 0)x \geq 1 \\ 3 & \text{else } (0 \ 1)x \geq 1. \end{cases}$$

When $\pi(x) = 1$, the conditions on α can be read as:

$$\alpha \leq \frac{1}{2} \|x - \mathbf{1}\|^2 \text{ for } x \in \mathbb{Z}^2, \text{ s.t. } (-1, -1)x \leq 0.$$

Thus, $\alpha \leq 1$. On the other hand, for those x with $\pi(x) = 2$ or 3 , we have that $1 \leq U_{\pi(x)} g(x)$. Hence, together with the lower bound on α , we obtain $\alpha = 1$.

It is straightforward to generalize the previous result slightly: one may drop the assumptions about the convex functions $f : \mathbb{R}^{n+d} \mapsto \mathbb{R}$ and $g : \mathbb{R}^{n+d} \mapsto \mathbb{R}^m$ that ensure that the primal and

dual problem are feasible and bounded. This then forces us to replace the minimum and the maximum with the infimum and the supremum, respectively.

Let us finally comment on the linear case. In this special situation we have that $f(x) = c^\top x$ and $g(x) = Ax - b$, with $c \in \mathbb{Q}^{n+d}$, $A \in \mathbb{Q}^{m \times (n+d)}$ and $b \in \mathbb{Q}^m$. This special setting allows us to simplify the min-max relation and at the same time highlight the connection to mixed-integer-free polyhedra. Let us assume without loss of generality that the row vectors U_1, \dots, U_k correspond to the first type of inequality in the duality statement, i.e. $\alpha \leq f(x) + U_i g(x)$, and the remaining U_i 's correspond to the second type of inequality, $1 \leq U_i g(x)$. We define

$$P(\alpha, U) := \{x \in \mathbb{R}^{n+d} \mid \begin{array}{l} \alpha - U_i b > (c^\top - U_i A)x \text{ for } i = 1, \dots, k \\ 1 - U_i b > -U_i A x \text{ for } i = k+1, \dots, 2^n \end{array}\}.$$

Then the duality statement in the linear mixed-integer situation can be recast as follows:

Corollary 12. *With the notation introduced above one has*

$$\min_{x \in \mathbb{Z}^n \times \mathbb{R}^d} \{c^\top x \mid Ax \leq b\} = \max_{\substack{\alpha \in \mathbb{R} \\ U \in \mathbb{R}_{+}^{2^n \times m}}} \{\alpha \mid P(\alpha, U) \cap (\mathbb{Z}^n \times \mathbb{R}^d) = \emptyset\}.$$

Appendix

We display in this appendix some elementary technical observations needed in the proof of Theorems 5 and 8. The notation $B(x, R)$ designate the open Euclidean ball centered in x of radius $R > 0$ and $B[x, R]$ its closure. The relative interior of a set S is written $\text{ri}(S)$.

Observation 13. *We know by Doignon's Theorem [4] that if a possibly infinite intersection of convex sets is integer-free and if one of these sets is bounded, then a sub-selection of at most 2^n of them is integer-free.*

As in the proof of Theorem 5, we consider the sets L_z defined in (7) and their intersection L . Since the d last components of h_z are null, we can restrict our attention to the projection \hat{L}_z of L_z on its n first component and the intersection \hat{L} .

First, we show that \hat{L} is bounded. Suppose otherwise and consider one of its rays $\ell := \{z_0 + td : t \geq 0\}$. Pick a few points $z_1, \dots, z_N \in \mathbb{Z}^n$ so that the interior of their convex hull contains $B[z_0, \sqrt{n}]$. Since the level set corresponding to $\max_{1 \leq i \leq N} f(z_i)$ is bounded, there exists a ball $B[z_0, M]$ containing it. Further, there exists an integral point $\hat{z} \notin B[z_0, M]$ at a distance smaller than $\frac{\sqrt{n}}{2}$ from ℓ . The half-space $\{y \in \mathbb{R}^n : h^\top y < h^\top \hat{z}\}$, with $h \in \partial f(\hat{z})$, contains L . Now, ℓ cannot be entirely in this half-space. This contradiction shows that \hat{L} is bounded.

Let us take a closed ball $B[0, R]$ containing \hat{L} . Consider the compact set $C := B[0, 2R] \setminus B(0, R)$. The sets $B(0, 3R) \setminus \text{cl}(\hat{L}_z)$ are open and cover C . Hence, a finite number of them are enough to cover C , say $C \subseteq \cup_{i=1}^N B(0, 3R) \setminus \text{cl}(\hat{L}_{z_i})$. Thus $\cap_{i=1}^N \hat{L}_{z_i} \subseteq B[0, R]$ by connectivity of this intersection. \square

Observe that the previous observation holds also when we replace some L_z by their closure. The second observation follows closely the proof of the main result in [1].

Observation 14. *Let $C \subseteq \mathbb{R}^{n+d}$ be a mixed-integer-free convex set. Assume that $C = \text{int}(L) \cap S$, where L and S are the bounded level sets of two convex functions f and g . (In the context of Theorem 8, g plays the role of g_{\max}) Suppose that:*

$$\text{int}(L) := \bigcap_{\substack{z \in \text{bd}(L), \\ u \in \partial f(z)}} \{y \in \mathbb{R}^{n+d} : u^\top(y-z) < 0\} \neq \emptyset \quad \text{and} \quad S := \bigcap_{\substack{z \in \text{bd}(S), \\ v \in \partial g(z)}} \{y \in \mathbb{R}^{n+d} : v^\top(y-z) \leq 0\}.$$

Denote by Π the projection operator on the first n components and $\hat{C} := \Pi(C)$. By continuity of Π , we know that $\Pi(\text{cl}(C)) = \text{cl}(\hat{C})$. Since $\text{int}(C)$ is nonempty, it is easy to verify that $\Pi(\text{int}(C)) = \text{ri}(\hat{C})$. Define for every $x \in \text{bd}(\hat{C}) := \text{cl}(\hat{C}) \setminus \text{ri}(\hat{C})$ the sets $C_x := (\{x\} \times \mathbb{R}^d) \cap C$ and $\bar{C}_x := (\{x\} \times \mathbb{R}^d) \cap \text{cl}(C)$ (Note that \bar{C}_x is not necessarily the closure of C_x). For every $x \in \text{bd}(\hat{C})$, we know $C_x \subseteq \text{bd}(C)$. If C_x is empty (and then $x \notin \hat{C}$), there exists $y \in S \cap \text{bd}(L)$ with $\Pi(y) = x$ (for otherwise $x \notin \text{cl}(\hat{C})$). If C_x is not empty, then there exists $y \in C$ with $\Pi(y) = x$, $y \in \text{int}(L)$, and $y \in \text{bd}(S)$ (for otherwise $x \in \text{ri}(\hat{C})$).

Let us apply our previous observation on Doignon's Theorem. We obtain $N \leq 2^n$ inequalities, say the k first from L and the $N - k$ last from S whose intersection is integer-free, namely:

$$\hat{P} = \bigcap_{i=1}^k \{y \in \mathbb{R}^n : u_i^\top(y - x_i) < 0\} \cap \bigcap_{j=k+1}^N \{y \in \mathbb{R}^n : u_j^\top(y - x_j) \leq 0\}.$$

Note that some x_i with $1 \leq i \leq k$ might coincide with some x_j with $k < j \leq N$. Now, let $x \in \{x_1, \dots, x_N\}$. By what precedes, $x \notin \hat{P}$ iff $C_x = \emptyset$, in which case $x \in \text{bd}(L)$ and $x = x_i$ for some $1 \leq i \leq k$. As in [1], for every $x \in \text{bd}(\hat{C})$ we define a point $y \in \text{ri}(\bar{C}_x)$ and the closed convex cone N_x of affine functions from \mathbb{R}^{n+d} to \mathbb{R} vanishing on y and nonnegative on C . The extreme rays of N_x are in $\partial f(y)$ if $y \in \text{bd}(L)$ and in $\partial g(y)$ if $y \in \text{bd}(S)$. Since \hat{C} is of dimension n , the dimension of N_x is not larger than $d + 1$.

Now, $(u_i, 0)^\top \in N_x$, so we can represent this vector as a combination of at most $d + 1$ extreme vectors in N_x , say $b^{(1)}, \dots, b^{(d+1)}$, with possibly repeated vectors. If C_x is not empty, then $y \in \text{int}(L)$ because $y \in \text{ri}(C_x)$, so all these vectors belong to $\partial g(y)$, yielding inequalities of the type $\{z \in \mathbb{R}^{n+d} : (b^{(j)})^\top(z - y) \leq 0\}$. If C_x is empty, the corresponding inequalities are of the form $\{z \in \mathbb{R}^n : (b^{(j)})^\top(z - y) < 0\}$ or $\{z \in \mathbb{R}^n : (b^{(j)})^\top(z - y) \leq 0\}$, with at least one of the first type, depending on $b^{(j)} \in \partial f(y)$ or $b^{(j)} \in \partial g(y)$. Note that y is not in the intersection of these half-spaces, and in fact, no point of $\{x\} \times \mathbb{R}^d$.

The mixed-integer-freeness of the resulting intersection is now clear. \square

4 Acknowledgments

We would like to thank the reviewers, whose careful comments improved significantly the presentation of our results.

References

- [1] G. Averkov and R. Weismantel. Transversal numbers over subsets of linear spaces. *Adv. Geom.*, 12(1):19–28, 2012.
- [2] E. Balas. Disjunctive programming and a hierarchy of relaxations for discrete optimization problems. *SIAM Journal on Algebraic and Discrete Methods*, 6:466–486, 1985.
- [3] Egon Balas. Disjunctive programming: Cutting planes from logical conditions. In O. L. Mangasarian, editor, *Nonlinear Programming 2*, pages 279–312. Academic Press, New York, NY, 1975.
- [4] J.-P. Doignon. Convexity in cristallographical lattices. *J. Geometry*, 3:71–85, 1973.
- [5] M. Held and R. M. Karp. The traveling salesman problem and minimum spanning trees. *Operations Research*, 18:1138–1162, 1970.
- [6] R. G. Jeroslow. Cutting plane theory: Algebraic methods. *Discrete Mathematics*, 23:121–150, 1978.
- [7] R. G. Jeroslow. An introduction to the theory of cutting planes. *Annals of Discrete Mathematics*, 5:71–95, 1979.

- [8] Robert G. Jeroslow. Minimal inequalities. *Math. Programming*, 17(1):1–15, 1979.
- [9] E. L. Johnson. Cyclic groups, cutting planes and shortest paths. In T. C. Hu and S. M. Robinson, editors, *Mathematical Programming*, pages 185–211. Academic Press, New York, NY, 1973.
- [10] E. L. Johnson. On the group problem and a subadditive approach to integer programming. *Annals of Discrete Mathematics*, pages 97–112, 1979.
- [11] W. Karush. Minima of functions of several variables with inequalities as side conditions. Dissertation, Department of Mathematics, University of Chicago, 1939.
- [12] H.W. Kuhn and A.W. Tucker. Nonlinear programming. In *Proceedings of the Second Berkeley Symposium on Mathematical Statistics and Probability, 1950*, pages 481–492. University of California Press, Berkeley and Los Angeles, 1951.
- [13] Jean B. Lasserre. A Lagrangian relaxation view of linear and semidefinite hierarchies. *SIAM J. Optim.*, 23(3):1742–1756, 2013.
- [14] Monique Laurent. A comparison of the Sherali–Adams, Lovász–Schrijver and Lasserre relaxations for 0-1 programming. *Mathematics of Operations Research*, 28(3):470–496, 2003.
- [15] L. Lovász. Geometry of numbers and integer programming. In M. Iri and K. Tanabe, editors, *Mathematical Programming: State of the Art*, pages 177–201. Mathematical Programming Society, 1989.
- [16] László Lovász and Alexander Schrijver. Cones of matrices and set-functions and 0/1 optimization. *SIAM Journal on Optimization*, 1:166–190, 1991.
- [17] Diego A. Morán R., Santanu S. Dey, and Juan Pablo Vielma. A strong dual for conic mixed-integer programs. *SIAM J. Optim.*, 22(3):1136–1150, 2012.
- [18] Kazuo Murota. *Discrete convex analysis*. SIAM Monographs on Discrete Mathematics and Applications. Society for Industrial and Applied Mathematics (SIAM), Philadelphia, PA, 2003.
- [19] G. L. Nemhauser and L. A. Wolsey. *Integer and Combinatorial Optimization*. Wiley, New York, NY, 1988.
- [20] Y. Nesterov. *Introductory Lectures on Convex Optimization*, volume 87 of *Applied Optimization*. Kluwer Academic Publishers, Boston, 2004.
- [21] Hanif D. Sherali and Warren P. Adams. A hierarchy of relaxations between the continuous and convex hull representations for zero-one programming problems. *SIAM Journal of Discrete Mathematics*, 3:411–430, 1990.
- [22] Hanif D. Sherali and Warren P. Adams. *A Reformulation-Linearization Technique for Solving Discrete and Continuous Nonconvex Problems*. Kluwer, Norwell, MA, 1999.