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3 **Models linking production and comprehension**

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1 comprehension. A comprehensive review of these and other arguments is beyond the scope of this
2 chapter. Here, we just note that these arguments do not necessarily imply that comprehension and
3 production are completely separate. Rather, dissociations and asymmetries are in principle
4 compatible with some degree of sharing, as long as there are subcomponents of production that are
5 not used in comprehension and *vice versa*.

6 When discussing the issue of what is shared between production and comprehension, it is
7 useful to bear in mind the distinction between linguistic *representations* and *processes* acting on
8 those representations. Linguistic representations are the components of memory that store
9 information about linguistic units (e.g., phonemes, words, syntactic rules, concepts).
10 Comprehension and production processes are the cognitive operations that can be applied to
11 linguistic representations (e.g., retrieval, spreading activation, inhibition), as well as the operations
12 that map from abstract representations to articulation and from acoustics to abstract representations.
13 Processes are directional: so, for example, the process that retrieves a phonological representation
14 given an activated semantic representation is not the same as the process that retrieves a semantic
15 representation given an activated phonological representation. Below, we first discuss sharing with
16 regard to representations (*Representational parity*), and then we turn to theories that posit common
17 processes (*Linked processes*).

18

19 **Representational parity**

20 Most theorists assume that some of the representations that are accessed during production
21 are the same as the representations accessed during comprehension. At the single word level, the
22 most influential theory of lexical access in production assumes conceptual (semantic), lemma
23 (syntactic), and word-form (sound-based) representations, and proposes the network for production
24 and the network for comprehension “coincide from the lemma level upwards” (i.e., concept and
25 lemma nodes are shared between production and comprehension; Levelt, Roelofs, & Meyer, 1999;
26 p. 7). Pickering and Garrod (2004) also assume shared representations (which they term the *parity*
27 *hypothesis*), but extend the scope of this assumption by positing that representations used in
28 comprehension are the same as representations used in production at all linguistic levels, from the
29 situation model (i.e., a representation of the situation being discussed, including time, space, causal
30 relations, intentionality, and individuals involved; Zwaan & Radvansky, 1998) to phonology and
31 phonetics. Shared phonological representations are also part of the Node Structure Theory of
32 MacKay (1987). Moreover, parity at the sound level is the central assumption of the Motor Theory

1 of speech perception (Lieberman & Whalen, 2000; see Galantucci, Fowler, & Turvey, 2006), and of
2 the Episodic Theory of speech perception (Goldinger, 1998).

3 Parity at the semantic and lexico-syntactic levels has been confirmed by several studies. The
4 strongest evidence comes from findings of immediate effects of comprehension on production.
5 First, silent reading of words semantically and associatively related to the name of a target picture
6 affects naming times for the picture (e.g., Schriefers, et al., 1990; Alario, Segui, & Ferrand, 2000).
7 Second, silent reading of sentences such as *A rock star sold an undercover agent some cocaine*
8 (double object, DO) or *A rock star sold some cocaine to an undercover agent* (prepositional object,
9 PO) influences what sentence structure (DO or PO) is used to describe a target scene (depicting an
10 unrelated event, such as a man reading a book to a boy; Bock, Dell, Chang, & Onishi, 2007). And,
11 similarly, the syntactic choices of their interlocutor influence affect speakers' syntactic choices in
12 dialogue (Branigan, Pickering, & Cleland, 2000; Levelt & Kelter, 1982; see Pickering & Ferreira,
13 2008 for a review). In addition, interlocutors align their lexical choices (Brennan & Clark, 1996;
14 Garrod & Anderson, 1987).

15 As well as behavioural evidence, there is growing evidence for lexico-syntactic parity at the
16 neural level. Two fMRI studies showed that the same neural populations are recruited during
17 comprehension and production of sentences (Menenti, Gierhan, Segaert, & Hagoort, 2011; Segaert,
18 Menenti, Weber, Petersson, & Hagoort, 2012). They identified brain areas that show decreased
19 activation while producing (or comprehending) a given sentence structure, when the participant had
20 just processed a sentence with the same structure, compared to a sentence with a different structure.
21 This phenomenon is called repetition suppression, and it is used to localize neural areas that are
22 sensitive to a given property of the stimulus (in this case, structure). Importantly, the areas
23 identified were the same regardless of whether prior processing of the same structure had taken
24 place in production or comprehension.

25 Regarding parity at the phonological level, it is known that silent reading of, or passive
26 listening to, distractor words phonologically related to the name of a target picture speeds up
27 naming times for the picture (e.g., Schriefers, et al., 1990; Damian & Martin, 1999). This is usually
28 taken as evidence that comprehension of distractor words pre-activates phonological representations
29 they share with the target, so that those representations are subsequently easier to access in
30 production. Moreover, Kerzel and Bekkering (2000) found that participants pronounced a printed
31 syllable while watching a video of a mouth producing the same syllable more quickly than when the
32 mouth produced a different syllable (see also Jarick & Jones, 2008). In addition, Galantucci,
33 Fowler, and Goldstein (2009) showed that speakers are faster to produce a syllable (e.g., /ba/) if

1 they have just listened to the same syllable than to a syllable with a different onset (e.g., /da/) (see
2 also Fowler, Brown, Sabadini, & Weihing, 2003).

3 There is also much evidence demonstrating motor activation during the perception of
4 speech. Such evidence suggests that speech production and speech perception make use of
5 overlapping neural representations. Several studies have found activation of motor areas in the brain
6 during audiovisual speech perception (e.g., Skipper, Nusbaum, & Small, 2005; Skipper, van
7 Wassenhove, Nusbaum, & Small, 2007), and also during passive listening to speech (e.g., Wilson,
8 Saygin, Sereno, & Iacoboni, 2004). Importantly, motor activation during passive listening is
9 articulator-specific: for example, listening to labial consonants is associated with activation of the
10 lip representation area in motor cortex (Pulvermüller et al., 2006; see Pulvermüller & Fadiga, 2010
11 for a review). Further, listening to speech modulates the excitability of the speech muscles that are
12 involved in the production of the perceived sound (e.g., Fadiga, Craighero, Buccino, & Rizzolatti,
13 2002). Accordingly, listening to a phoneme also affects concurrent articulation of a different
14 phoneme; for example the palatal sound /k/ was produced with greater contact between the tip pf
15 the tongue and the alveolar ridge when participants were listening to the alveolar sound /t/ (Yuen,
16 Davis, Brysbaert, & Rastle, 2010).

17 This body of evidence supports the assumption of shared representations at the phonological
18 level at least. However, recent findings suggest that motor activation during speech perception
19 might occur primarily or exclusively when the task is difficult (e.g., when speech is degraded;
20 Adank, 2012; D’Ausilio, Bufalari, Salmas, & Fadiga, 2012). Moreover, it may be that motor
21 activation under normal listening conditions reflects listeners’ tracking of the speaker’s speech rate
22 and preparation for speech in anticipation of the end of the speaker’s utterance, rather than retrieval
23 of shared content-specific phonological representations (S. K. Scott, McGettigan, & Eisner, 2009).

24

25

INSERT FIGURE 1 ABOUT HERE

26

27 Figure 1A is intended as a schematic summary of the overview of the literature on
28 representational parity presented in this section. It depicts what we take to be the consensus view on
29 the issue of representational parity across levels of linguistic representations. First of all, it
30 illustrates the fact that there is substantial consensus on parity at the semantic and syntactic level
31 (grey *sem* and *syn* representations). Phonological representations, instead, are depicted as

1 overlapping but not identical (partially superimposed black and white *phon* representations) to
2 account for the fact that evidence for parity at this level might be restricted to particular task
3 demands (as just discussed). Finally, in Figure 1 representations at the phonetic level are labelled as
4 speech percepts (comprehension) and speech motor commands (production) and are assumed to be
5 separate (i.e., white speech percepts are separate from black motor command representations).

6 Some researchers assume substantial overlap at the phonetic level as well, but parity at this
7 level is particularly controversial. On one hand, speakers can converge towards a model speaker at
8 the level of low-level phonetic features that do not imply phonological distinctions (e.g., vowel
9 duration, F0), therefore providing support for the hypothesis that phonetic representations are
10 shared between comprehension and production (e.g., Goldinger, 1998; Pardo, 2006; see Chapter 6
11 in this volume). However, other studies failed to find evidence that listening to a phonetic variant
12 (e.g., alveolar /r/) facilitates subsequent production of the same variant compared to listening to an
13 alternative variant (e.g., uvular /r/) that is phonologically equivalent (Mitterer & Ernestus, 2008;
14 Mitterer & Müsseler, 2013).

15 Moreover, despite some indication that adaptation to an accent in comprehension correlates
16 with adaptation to the same accent in production at the level of an individual speaker (Evans &
17 Iverson, 2007), there are also asymmetries between people's production and comprehension
18 abilities in the processing of regional variability in speech. For example, Sumner and Samuel
19 (2009) argued that listeners who have long-term perceptual experience with a dialectal phonetic
20 variant can achieve native-like perception of that variant despite lacking native-like production
21 representations (see also Kraljic, Brennan, & Samuel, 2008). To sum up, some findings in the
22 literature suggest comprehension and production phonetic representations are shared or
23 overlapping, but others support the notion of distinct comprehension and production representations
24 at this level. Overall, the evidence for separation is stronger at the phonetic than at the phonological
25 level. In Figure 1A, we capture this by drawing separate (rather than partially overlapping) phonetic
26 representations, but it is still unclear how much separation should be assumed at this level.

27

28 **Linked processes**

29 Figure 1 does not only depict representations, but also processes. Traditionally, any process
30 that takes place during an act of comprehension (i.e., while reading or listening) has been
31 considered a comprehension process and, conversely, any process that takes place during an act of
32 production (i.e., while writing or speaking), a production process. Within this tradition, the debate

1 has focussed on whether processes that take place during production always map from semantics to
2 syntax and from syntax to phonology (i.e., white arrows on black background, flowing from left to
3 right in Figure 1A), or whether they can also map in the opposite direction (i.e., black arrows on
4 white background, flowing from right to left in Figure 1A). Processes that go “backwards” have
5 been termed feedback processes and models that incorporate them (e.g., Dell, 1986) have been
6 labelled as interactive (as opposed to purely feed-forward models; Levelt, et al., 1999). Similar
7 issues have been discussed in the comprehension literature, where left-to-right processes (see Figure
8 1A) have been called top-down and right-to-left processes have been called bottom-up (e.g.,
9 Marslen-Wilson, 1987). Within the traditional view, researchers do not typically ask whether
10 production processes can take place during comprehension or whether comprehension processes
11 can take place during production. Instead, they tend to label any process that takes place during
12 production as a “production process” and any process that takes place during comprehension as a
13 “comprehension process”, regardless of the direction in which it flows.

14 But on an alternative view, a process is classed as a production process if it maps from
15 representations that are higher in the linguistic hierarchy (e.g., semantics) to representations that are
16 lower (e.g., phonology), that is from left to right in Figure 1A. Conversely, a process is classed as a
17 comprehension process if it maps from lower to higher representations (e.g., from phonology to
18 semantics), that is from right to left in Figure 1A. According to this definition, which we will follow
19 in the remainder of this chapter, both production and comprehension processes could potentially be
20 employed during any act of production, as they could during any act of comprehension (Pickering
21 & Garrod, 2013).

22 Note that this difference is not merely terminological. Rather, it reflects a substantial
23 theoretical distinction between the traditional and the alternative view, which could be tested
24 experimentally. Should we conceptualize a processing flow that goes from phonology to syntax
25 during an act of production as a production process (because it takes place during an act of
26 production, as per the traditional view), or as a comprehension process (because it flows from right
27 to left, as per the alternative view)? One way of answering this question would be by examining the
28 neural pathways involved. For example, if we could show that the same neural pathway is involved
29 during an act of production that implies reliance on feedback flow of information, as well as during
30 an act of comprehension, then we would have empirical evidence for the alternative view. But if
31 feedback during production and comprehension engage separate pathways despite a common
32 direction in the flow of information, then the evidence would be more compatible with the
33 traditional view.

1 Unfortunately, progress towards establishing how much overlap there is between production
2 and comprehension processes has been hindered by the division between sub-disciplines within
3 psycholinguistics. Comprehension researchers often use a production measure (e.g., word naming
4 time) as their dependent variable, but do not interpret the production processes themselves (the
5 “mind-in-the-mouth” assumption; Bock, 1996). Similarly, production researchers presumably
6 realize that a task such as picture-word interference involves comprehension processes but tend to
7 ignore them.

8 For example, production researchers concerned with picture-word interference have
9 assumed that word form and phoneme representations activated by distractor words (in
10 comprehension) send activation to related word forms and phonemes in the production network;
11 Levelt, et al., 1999). But they do not ask what processes are involved in comprehension of the
12 distractor words, focussing instead only on the end result of those processes (i.e., that some
13 representation gets activated). For example, Damian and Martin (1999) showed that the time course
14 of semantic and phonological effects in picture-word interference differed for visually presented
15 distractors compared to auditorily presented distractor words because of the longer presentation
16 times used for visual distractors (in previous PWI studies). They did not consider the possibility that
17 lexical co-activation (in comprehension) might have a different time course depending on modality
18 (visual or auditory), and instead assumed that different presentation times led to different effects
19 because the distractors interacted with different stages of production of the target picture name.

20 However, production-comprehension links have not been entirely overlooked. In fact, both
21 feed-forward and feedback links have long been identified as a crucial component of neuro-
22 computational theories of speech motor control (Tourville & Guenther, 2011; Hickok, 2012) and
23 learning (Guenther & Vladusich, 2012; see also Plaut & Kello, 1999). Separately, the
24 psycholinguistic literature on language production has also given ample consideration to this topic,
25 albeit under the specific heading of self-monitoring. A long-standing psycholinguistic account of
26 self-monitoring, the Perceptual Loop Theory, equates the self-monitoring system (active during acts
27 of production) with the comprehension system (Levelt, 1983; 1989).

28 We first briefly present two neuro-computational models of speech motor control (Tourville
29 & Guenther, 2011; Hickok, 2012). Then, we describe the Perceptual Loop Theory and discuss some
30 criticisms of it. In the subsequent section, we introduce an integrated framework for language
31 comprehension and language production (Pickering & Garrod, 2013), which includes an alternative
32 account of self-monitoring (Pickering & Garrod, 2014), and also posits that production processes
33 take place during acts of comprehension (and not just that comprehension processes take place

1 during acts of production, as in self-monitoring). We then consider the P-chain framework (Dell &
2 Chang, 2014), which makes a related proposal. Finally, we discuss proposals that place the link
3 between production and comprehension outside specific acts of comprehension or production, but
4 instead in the long-term experience that speakers and listeners have with language (e.g.,
5 MacDonald, 2013).

6

7 *Neuro-computational models of speech motor control*

8 In neuro-computational models of speech motor control (the Directions Into Velocities of
9 the Articulators, or DIVA, model, see Tourville & Guenther, 2011; the Hierarchical State Feedback
10 Control, or HSFC, model, see Hickok, 2012, 2014), forward models map from motor commands
11 sent to the articulators to the sensory (i.e., auditory or somatosensory) consequences of executing
12 those commands (the upward dotted vertical arrow from motor commands to speech percepts in
13 Figure 1B). Forward models therefore instantiate a relatively low-level mapping between
14 production and comprehension representations and can be considered as internal models of the
15 language system (that is, models of the processes that cause the articulation of speech sounds during
16 acts of production). The inverse mapping corresponds to feedback-based correction of speech
17 movements (downward dotted vertical arrow from speech percepts to motor commands in Figure
18 1B).

19 Evidence that forward models are implicated in speech production comes from the finding
20 that auditory responses to speech sounds are suppressed during speaking compared to listening
21 (e.g., M100 suppression, as reported using magneto-encephalography in the study of Houde,
22 Nagarajan, Sekihara, & Merzenich, 2002). This is thought to occur because forward models can be
23 used during production to anticipate sensory stimulation and cancel it out (in a way that could be
24 useful in distinguishing between self-generated and externally-generated sounds). In support of this
25 claim, auditory responses are suppressed in a stimulus-specific manner: suppression occurs during
26 covert rehearsal compared with a control task, but only when the rehearsed stimulus matches (part
27 of) the perceived stimulus (Ylinen et al., 2014). In addition, enhancement rather than suppression
28 takes place when auditory feedback is altered unexpectedly during speaking, for example by
29 shifting pitch upwards or downwards in real-time, so that the predicted stimulation ceases to match
30 actual stimulation (e.g., Chang, Niziolek, Knight, Nagarajan, & Houde, 2013).

31 All of these studies are compatible with forward-model predictions operating at the level of
32 fine-grained phonetic features. But there is also some indication that such predictions might be

1 phonological in nature. Niziolek, Nagarjan, and Houde (2013) showed the degree of suppression is
2 larger for sounds that are closer to a given speaker's median productions, suggesting that
3 predictions could be computed on the basis of somewhat abstract representations. In other words,
4 when the speaker selects a motor command to execute, the anticipated sensory consequences might
5 correspond to an abstract phonological target (i.e., what it should sound like) rather than to a
6 detailed phonetic target (i.e., what it is going to sound like on this particular instance).

7 This finding provides support for the HSFC model (Hickok 2012; 2014). In this model,
8 forward model predictions operate at two hierarchically organized levels: phonemes and syllables.
9 Motor programs (corresponding to planned syllables and planned phonemes) inhibit sensory areas
10 where perceptual targets are represented. These same areas are activated via feedback from the
11 movements of the vocal tract and from the resulting speech output (i.e., when the speaker perceives
12 her own productions). In addition, they can receive activation from concepts and lemmas. The
13 discrepancy between the expected activation (propagated in the form of inhibitory connections from
14 the motor targets) and the actual activation constitutes a prediction error, which is propagated back
15 to the motor target areas and used for online corrections of motor programs (and learning of more
16 accurate motor-to-sensory mappings).

17 The inhibitory connections therefore implement a form of prediction that maps from motor
18 commands to expected sensory consequences of executing those commands. The excitatory
19 backward connections, instead, implement a form of inverse correction, which maps from sensory
20 prediction errors to changes in the motor commands needed to compensate for those errors.
21 Evidence for a fast-cycling loop at the phonetic level, in which motor representations are rapidly
22 mapped onto sensory representations and *vice versa*, comes from several demonstrations that
23 speakers compensate very quickly for perturbed auditory feedback (e.g., Houde & Jordan, 1998;
24 Jones & Munhall, 2002; Tourville, Reilly, & Guenther, 2008).

25 The HSFC model is closely related to the DIVA/GODIVA model proposed by Guenther and
26 colleagues (see Tourville & Guenther, 2011). This model also incorporates the notion that
27 somatosensory and auditory target areas are activated via forward-model predictions as well as via
28 processing of sensory input, and that prediction errors are used for online correction (as well as for
29 learning the mappings between movements and their sensory consequences). Importantly, both
30 models incorporate what we might call an account of self-monitoring. They assume that a process
31 that maps from motor areas to sensory areas (and *vice versa*) is essential for online control during
32 speech production (see Plaut & Kello, 1999 for another computational model that instantiates this
33 idea).

1 Crucially, unlike psycholinguistic theories of self-monitoring (see Sections 3.2 and 3.3),
2 these neuro-computational models focus on sound-level representations and processes, and say very
3 little about other linguistic levels. Hickok (2012, 2014) argued for the importance of integrating
4 psycholinguistic theories of language production with models of speech production, and integrated
5 lemma and conceptual representations within his HSFC. However, he did not explicitly extend the
6 forward-model architecture to these levels. In terms of Figure 1B, his model assumes that dotted
7 arrows flow in both directions between all levels, indicating that both comprehension and
8 production processes take place during language production. But the HSFC model includes a fast-
9 cycling within-level loop (recursive dotted arrows), which is responsible for fast error correction
10 during production, at the phonological and phonetic levels only. No such loop is explicitly assumed
11 at the lemma and conceptual levels.

12

13 *An early model linking production and comprehension: the Perceptual Loop Theory of self-*
14 *monitoring*

15 According to the Perceptual Loop Theory (Levelt, 1983; 1989), production errors are
16 detected via comprehension of speech output (the external loop), and also via comprehension of
17 phonological representations (the internal loop). The comparison process takes place at the level of
18 communicative intentions (messages): If the message reconstructed by the comprehension system
19 does not match the message originally intended, the monitor flags up an error. This comprehension-
20 production loop is depicted in Figure 1B using a solid black line. This loop links comprehension
21 representations at the phonological (phonological comprehension representations) and phonetic
22 level (the speech percepts formed during comprehension of the speech output) to semantic
23 representations (that are shared between comprehension and production).

24 Crucially, the Perceptual Loop Theory is open to criticism because it posits a relatively
25 slow-cycling loop. First, the speech signal must be analyzed by comprehension processes to recover
26 speech percepts (if using the external loop), or phonological representations retrieved by production
27 processes have to be analyzed by comprehension processes to activate corresponding phonological
28 representations in the comprehension network (if using the internal loop). Additional
29 comprehension processes then map from sound-based comprehension representations to a semantic
30 comprehension representation. Finally, the activated semantic representation in the comprehension
31 network is compared to the semantic representation that was originally activated in the production
32 network (the latter process is facilitated by shared representations at the semantic level). In addition,

1 if a discrepancy is detected, production of the current utterance must be stopped before production
2 of a replacement can start.

3 Oomen and Poostma (2002) found that limiting participants' processing resources by having
4 them engage in a concurrent task while speaking caused them to stop speaking more quickly after
5 the onset of an error (Oomen & Postma, 2002). If the time it takes to stop were attributable to a
6 comprehension-based loop, then one would have expected that drawing attention away from the
7 speech signal (as in a dual task condition) would have led to longer, not shorter stopping times.

8 Hartsuiker and Kolk (2001) criticized the Perceptual Loop Theory assumption that
9 production of the erroneous utterance must stop before planning of the replacement begins. Instead,
10 they proposed that stopping the current utterance and preparing a replacement can proceed in
11 parallel. Indeed, speakers can often resume very quickly following an interruption (in less than
12 100ms; Blackmer & Mitton, 1991), which suggests that they start planning the replacements before
13 they stop articulation. More direct evidence comes from Hartsuiker, Catchpole, de Jong, and
14 Pickering (2008; see also Gambi, Cop, & Pickering, in press), who showed that the time it takes to
15 stop a word depends on how difficult it is to prepare a replacement word.

16 However, Hartsuiker and Kolk (2001) also assume that the monitor needs to detect an error
17 in the phonological representation before sending a signal to stop production. Interestingly, there
18 are also psycholinguistic theories of self-monitoring that posit a purely production-based monitor
19 (see Postma, 2000 for discussion). For example, Nozari, Dell, and Schwartz (2011) proposed that
20 error detection is based on the amount of noise associated with production processes. One argument
21 in favor of production-based accounts is that they allow for very rapid error detection at all levels of
22 the linguistic hierarchy. Below, we introduce Pickering and Garrod's (2013; 2014) comprehension-
23 based theory of self-monitoring theory which addresses this issue by allowing the monitor to
24 compare expected and actual comprehension representations at all linguistic levels, as soon as these
25 representations become available.

26

27 *Prediction during production and comprehension: the integrated theory of language production*
28 *and comprehension*

29 Pickering and Garrod (2013) described an integrated theory of language production and
30 comprehension that is based on the notion of forward models. This notion of internal models is
31 derived from the motor control literature (e.g., Wolpert, 1997) and is also part of the models

1 reviewed in *Neuro-computational models of speech motor control*. Crucially, Pickering and Garrod
2 generalize it, assuming that forward models are computed at all levels of the linguistic hierarchy,
3 and that they are involved not only in speech production but also in speech comprehension. Below,
4 we first describe how forward models are implicated in self-monitoring, and then how they are
5 implicated in prediction during comprehension.

6 During an act of production, the speaker forms a communicative intention (production
7 command), which corresponds to the pre-linguistic message that the speaker intends to convey. The
8 production command is sent to the production system (or, in Pickering and Garrod's terminology,
9 the production implementer), and it triggers the retrieval of a set of production representations
10 (semantics, syntax, and phonology). For example, if a speaker sees a kite and forms the intention to
11 name this object, production processes would cause the retrieval of the corresponding concept
12 (KITE), lemma (*kite*) and phonological form (/kaɪt/). Importantly, it takes several hundred
13 milliseconds to retrieve such representations (see Indefrey & Levelt, 2004, for estimates). Once
14 production representations have been retrieved, they can be processed by the comprehension system
15 (or, in Pickering and Garrod's terminology, the comprehension implementer)ⁱ. Crucially, the theory
16 assumes that the comprehension implementer has immediate access to production representations at
17 all levels; so, for example, the semantic representation retrieved during production can be
18 immediately comprehended, even before a phonological representation is built. In this respect, the
19 proposal differs from the Perceptual Loop Theory of self-monitoring (Levelt, 1983).

20 In addition to retrieval of representations within the production and comprehension
21 implementers, during an act of production a copy of the production command is sent to a forward
22 model, which maps from the production command to the predicted comprehension representations
23 that are about to be retrieved as a consequence of executing that production command. To return to
24 our example of a speaker intending to name the picture of a kite, a forward model of this process
25 could compute a prediction of aspects of the semantics (it's a flyable object), of the syntax (it's a
26 noun)ⁱⁱ, and the phonology (it starts with a consonant), *before* the corresponding production
27 representations are retrieved from memory. Therefore, predicted representations are typically ready
28 before actual (implemented) representations. The process of self-monitoring constitutes the
29 comparison between predicted and actual comprehension representations within the comparator (at
30 any linguistic level). The resulting difference (the prediction error in motor control terms; Wolpert,
31 1997) can be used to drive online corrections (and learning), just as it can in the models described in
32 section *Neuro-computational models of speech motor control*.

1 In sum, the account of self-monitoring proposed by Pickering and Garrod (2013; 2014)
2 differs from the Perceptual Loop Theory (Levelt, 1983) in that it posits loops between production
3 and comprehension at all levels of the linguistic hierarchy, and both within and between levels (not
4 just from phonetics and phonology to semantics; see dotted arrows in Figure 1B). Moreover, such
5 loops are faster than the loops assumed by the Perceptual Loop Theory, because they are based on
6 comparisons between predicted and actual comprehension representations, with predicted
7 comprehension representations being the outcome of production processes (i.e., left-to-right dotted
8 arrows in Figure 1B).

9 With regard to acts of comprehension, Pickering and Garrod (2007) proposed that the collection of
10 cognitive mechanisms underlying prediction during language comprehension coincides with the
11 language production system. Federmeier (2007) made a similar proposal based on evidence that the
12 left hemisphere is more sensitive to predictability of upcoming words than the right hemisphere
13 (and the neural substrate for language production is predominantly left-lateralized in Broca's area),
14 and Dell and Chang (2014) have recently reinstated this idea as the core principle of their P-chain
15 framework (see *The P-chain framework*, this chapter).

16 An earlier proposal (Kempen, 2000, 2014) argued that grammatical encoding (production)
17 and grammatical decoding (comprehension) are performed by the same processing architecture.
18 Parallels between sentence comprehension and sentence production (e.g., similar patterns of errors
19 occur during subject-verb agreement in both production and comprehension; Bock & Miller, 1991;
20 Pearlmuter, Garnsey, & Bock, 1999), as well as evidence from structural priming from
21 comprehension to production (Bock, et al., 2007; Branigan, et al., 2000) are consistent with this
22 proposal. However, such evidence is indirect and, can be explained by shared representations
23 without shared processes. In addition, it is clear how production and comprehension could share
24 some processes (e.g., retrieving syntactic frames) but some differences in processes are necessary in
25 order to explain the different start- and end-points. Note that the proposal that production processes
26 are related to only a subset of comprehension processes, namely those involved in prediction during
27 acts of comprehension, is not subject to this criticism.

28 But is there evidence for this hypothesis? Some evidence that production processes might be
29 used during syntactic aspects of comprehension comes from a study by Kempen, Olsthoorn, and
30 Sprenger (2012). They asked Dutch participants to paraphrase sentences from direct (e.g., *De*
31 *lottowinnaar/ zei: / "Ik / heb besloten / een rode auto / te kopen / voor mezelf"*, The lottery winner
32 said: "I have decided to buy a red car for myself") into indirect speech (e.g., *De lottowinnaar zei dat*
33 *hij had besloten een rode auto te kopen voor zichzelf*, The lottery winner said that he had decided to

1 buy a red car for himself) as they read them (i.e., fragment by fragment, as marked in the example).
2 When the sentence contained an ungrammatical reflexive pronoun (e.g., the third-person reflexive
3 pronoun in the sentence *De lottowinnaar zei: "Ik heb besloten een rode auto te kopen voor*
4 *zichzelf"*), participants were faster producing the paraphrase (which contained the same third-
5 person pronoun) than when the sentence contained a grammatical reflexive (i.e., *mezelf*), despite the
6 fact that the ungrammaticality should have led to a processing delay in comprehension. One
7 interpretation of these findings is that participants' expectations generated during the
8 comprehension of the input sentences were replaced, on-line, by the expectations generated during
9 concurrent encoding of the paraphrase (in which the same pronoun was grammatical).

10 Moreover, Federmeier, Kutas, and Schul (2010) showed that a late prefrontal positivity
11 induced by plausible but unexpected nouns (which is thought to index the updating of disconfirmed
12 predictions after an unexpected word has been encountered; Federmeier, Wlotko, De Ochoa-
13 Dewald, & Kutas, 2007) is greatly reduced in older adults (compared to younger adults) and,
14 importantly, the magnitude of this component in the older group correlated with production
15 measures of verbal fluency. Similarly, Mani and Huettig (2012) found that 2-year-olds with larger
16 production (but not comprehension) vocabularies were more likely to predict upcoming referents
17 (as indexed by looks to corresponding pictures in the so-called visual world paradigm; cf. Altmann
18 & Kamide, 1999). More recently, a similar correlation between verbal fluency and prediction
19 abilities during language comprehension (again, measured using the visual world paradigm) was
20 reported for young adults as well, but only when listeners could preview pictures in the visual
21 display (and presumably started retrieving their names; Hintz, Meyer, & Huettig, 2014). These
22 studies suggest that the ability to predict during language comprehension is correlated with
23 language production abilities at least in some task contexts.

24 In accordance with this and related evidence, Pickering and Garrod (2013) proposed that
25 production processes underline comprehenders' ability to predict what another is about to produce.
26 This route to comprehension is termed prediction-by-simulation. It starts with the comprehender
27 covertly imitating the producer: this means that, based on the initial part of the producer's utterance,
28 or on contextual information (i.e., what he assumes about the producer from previous interactions,
29 or from background knowledge), the comprehender recovers the most likely intention (production
30 command) underlying the utterance at time *t*. He can then run this command through the production
31 implementer. If he does that, he will end up imitating the producer. This mechanism therefore
32 explains alignment (Pickering & Garrod, 2004; see *Representatioal parity*).

1 In addition, the comprehender can run ahead the command that he recovered at time t , thus
2 predicting what he would be likely to utter next if he were in the producer's shoes. If he runs this
3 new command through the production implementer, he will be able to complete the producer's
4 utterance (see *Dialogue*). If he runs this new command through the forward production model, the
5 comprehender may generate the predicted semantics, syntax, and phonology at time $t+1$. When the
6 producer continues his utterance, the comprehender builds comprehension representations for the
7 actual utterance at $t+1$ and can compare them to the representations he had predicted. He can then
8 use the resulting discrepancy to adjust the recovered production command, thus revising his
9 understanding of the intention underlying the producer's utterance.

10 In addition to the correlational evidence cited above, one study established a causal link
11 between production processes and prediction during language comprehension (Lesage, Morgan,
12 Olson, Meyer, & Miall, 2012). This study applied repetitive Transcranial Magnetic Stimulation
13 (rTMS) to the right cerebellum. In rTMS, as in other types of TMS, a magnetic coil is used to
14 induce small electric currents in a particular area of the brain; in particular, several pulses are
15 delivered at a low-frequency, which is known to suppress neural activity for some time after
16 stimulation has ended. Importantly, evidence suggests that forward model computations related to
17 motor execution take place in the cerebellum (e.g., Wolpert, Miall, & Kawato, 1998), and some
18 have linked it to the computation of internal models in general (e.g., Ito, 2008). Disrupting activity
19 in the right cerebellum caused participants in this study to delay their eye-movements to predictable
20 visual referents during sentence comprehension (but not to unpredictable visual referents).
21 Crucially, other conditions with no stimulation or stimulation to a control site did not show the
22 same selective effect. Therefore, this study suggests that forward model computations might
23 support prediction during comprehension.

24 Note that, because the forward model is functionally distinct from the production
25 implementer, Pickering and Garrod's (2013) account does not claim that full activation of the
26 production implementer will be observed whenever prediction-by-simulation is used. For example,
27 the account does not predict that activation of language production areas in the brain will be always
28 observed during language comprehension. Rather, such activation is most likely to occur under
29 conditions in which prediction-by-simulation is relied upon more. According to Pickering and
30 Garrod, this is the case when comprehension is difficult (e.g., in a noisy environment; see Adank,
31 2012).

32 But in addition, there is another route to prediction available in comprehension, which they
33 termed prediction-by-association. This route does not involve production processes (i.e., forward

1 models or the production implementer), and could be used whenever covert imitation fails. This
2 route to prediction in comprehension makes use of regularities in the input to the process of
3 comprehension. Unlike prediction-by-simulation, it does not rely on knowledge of how we produce
4 language. Instead, it relies on our ability to learn regular patterns of perceptual events, which
5 applies equally to domains in which we have the ability to generate the patterns through action and
6 domains in which we lack this ability (e.g., predicting the sound of leaves moved by the wind).

7 In sum, Pickering and Garrod's (2013) account allows for the existence of processes that are
8 not (usually) shared between acts of comprehension and acts of production. In other words, there
9 are some production processes that do not always operate during acts of comprehension (e.g.,
10 processes involved in retrieving articulatory programs; prediction-by-simulation via forward model
11 computations), and there are comprehension processes that do not operate during acts of production
12 (e.g., the prediction-by-association route).

13

14 *The P-chain framework*

15 The P-chain framework (Dell & Chang, 2014) claims that the process responsible for
16 prediction during acts of comprehension is the same process that is used during acts of production.
17 Therefore, although it does not claim that all processes are shared between comprehension and
18 production, it posits that there is a single cognitive architecture subserving both tasks.

19 This assumption stems from the architecture of Chang, Dell, and Bock's (2006) Dual Path
20 model of sentence acquisition (in children) and structural priming (in children and adults). This
21 model is a recurrent neural network; during training, the model learns to predict the next word in
22 the input (as in Elman, 1990). Prediction errors are generated by comparing the predicted with the
23 actual comprehended input, and are used to change the weights between units in the network, so
24 that the model learns to correctly predict grammatical word sequences in the future. Sometimes the
25 model uses meaning (inferred from context) to help in this prediction process and the ability to do
26 prediction from meaning is the same mechanism that the model uses for production. Thus,
27 prediction from meaning (production) and prediction without meaning (comprehending other's
28 utterances) involve the same mechanismsⁱⁱⁱ.

29 Dell and Chang (2014) proposed that the model's architecture instantiates a set of principles
30 that govern the functioning of the cognitive system for language. They termed this collection of
31 principles the *P-chain framework*. The framework highlights the tight links existing between

1 language comprehension (which they term *processing*) and *production*. Such links are organized in
2 a chain, or loop, of cause-effect relations. In a nutshell, the use of production-based prediction
3 mechanisms during language comprehension generates prediction errors, which in turn drive
4 changes in the language system (i.e., they make it more likely to generate predictions in line with
5 previous input), thus providing an explanation for structural priming effects, that is for the fact that
6 comprehending a given sentence structure makes it more likely that the same structure will be
7 selected in a subsequent act of production. When these changes build up over time, they can explain
8 acquisition of structural representations for different languages (English: Twomey, Chang, &
9 Ambridge, 2014; Japanese: Chang, 2009; German: Chang, Baumann, Pappert, & Fitz, in press).
10 Finally, input regularities, on which comprehension is tuned, are themselves the output of the
11 mechanism responsible for language production (in other speakers); therefore, there is also a slow-
12 cycling loop through which the production processes of other speakers provide the input that trains
13 comprehension processes. This final link is inspired by the Production-Distribution-Comprehension
14 account (MacDonald, 2013) that is examined in the next section.

15

16 *Frameworks that posit linked preferences*

17 Several theorists have appealed to the idea that regular patterns in language use emerge as a
18 consequence of the constraints imposed by communication, and that such patterns in turn affect
19 how speakers and listeners process language. This approach corresponds to positing a long-term
20 loop (dashed arrow in Figure 1B) that is external to the language production and comprehension
21 architecture (i.e., outside the mind/brain of individual language users).

22 One version of this idea is that speaker choices in production are constrained by ease-of-
23 comprehension principles. For example, the Hyper- And Hypo-Articulation model of speech
24 production (Lindblom, 1990) claims that speakers' tendency to reduce articulation (and therefore
25 their own effort) is constrained by the necessity for listeners to recover the intended message. This
26 leads speakers to counteract the tendency to hypo-articulate (i.e., to produce forms that are reduced
27 in duration and/or intensity), precisely in those contexts in which the listener cannot draw on other
28 sources of information (i.e., other than the speech signal) to infer meaning. There are other versions
29 of this idea in phonetics (e.g., the Smooth Signal Redundancy hypothesis, Aylett & Turk, 2004).

30 Similarly, the Uniform Information Density hypothesis (UID; Levy & Jaeger, 2007; Jaeger,
31 2010) claims that producers strive to keep information transfer rate within the range of the
32 comprehender's processing rate (i.e., channel capacity); in this way, they avoid conveying too much

1 information or too little information per unit (word, phoneme, etc.). This can also be phrased in
2 terms of surprisal, which is the predictability of a unit in context. High surprisal means that a unit is
3 unpredictable based on previous context, and therefore adds information in that context, whereas
4 low surprisal means that a unit is highly predictable and adds little information. UID claims that
5 when given a choice speakers will tend to use a structure that keeps surprisal relatively constant
6 across units. Production preferences are therefore explained as stemming from the limitations of the
7 comprehension system. Interestingly, these preferences may be shaped by learning: Jaeger and
8 Snider (2013) provide evidence that the higher the surprisal of a structural alternative in
9 comprehension, the more likely that alternative is to be subsequently preferred in production.

10 The idea that production preferences can be explained with reference to comprehension is
11 also related to the Audience Design Hypothesis: the notion that producers take into account their
12 addressee's knowledge when planning their utterances (e.g., Brown-Schmidt, 2009; Clark, 1996). A
13 review of this literature is beyond the scope of this chapter. However, we note that experimental
14 evidence for the extent to which audience design affects production is mixed. In particular, there is
15 controversy over the rapidity with which the addressee's knowledge can affect production. Keysar
16 and colleagues have argued that producers are egocentric (e.g., Horton & Keysar, 1996), and take
17 into account what their addressee can or cannot know only when given sufficient time and during a
18 relatively late stage of production. In addition, it has been suggested that while speakers might
19 adapt at the level of lexical choices, they in fact do not do so at the phonetic level (Bard et al., 2000;
20 but see Galati & Brennan, 2010 for criticism, and Arnold, Kahn, & Pancani, 2012 for some
21 evidence that speakers might adapt at least at the level of production speed). Finally, addressees are
22 clearly facilitated when speakers adopt to previously established referential labels, but we do not
23 know whether such facilitation occurs because listeners are sensitive to mutual knowledge between
24 them and the speaker (Brown-Schmidt, 2009) or simply because repetition increases availability
25 (Barr & Keysar, 2002).

26 Another related view is the Production-Distribution-Comprehension account (MacDonald,
27 2013), which assumes that the relevant constraints shaping patterns of language use over time relate
28 to production rather than to comprehension. In particular, it assumes three principles: (i) Easy First:
29 Words that are more easily retrieved are produced first (e.g., Bock & Warren, 1985); (ii) Plan
30 Reuse: Utterance plans that have been recently used tend to be reused (e.g., Bock, 1986); and (iii)
31 Reduce Interference: Elements that are more similar to one another (and therefore tend to interfere
32 in memory) are placed farther apart (Gennari, Mirković, & MacDonald, 2012 for semantic
33 similarity; Jaeger, Furth, & Hilliard, 2012 for phonological similarity). The claim, then, is that these

1 constraints on production lead to distributional regularities to which comprehenders adapt as they
2 accumulate linguistic experience. Therefore, linguistic forms that are easier to produce become
3 easier to comprehend as well. This account thus explains both why certain structures are easier to
4 comprehend than others and cross-linguistic patterns of language variation (i.e., typology). We refer
5 the reader to Chapter 3 in this volume for an in-depth discussion of the evidence in favour and
6 against the frameworks briefly introduced in this section.

7

8 **Dialogue**

9 As mentioned in the Introduction, the nature of language use in dialogue (i.e., conversation)
10 is one key motivation for positing links between comprehension and production. First, each
11 participant in a dialogue regularly has to switch between acts of production and acts of
12 comprehension. Such switches do not only occur between dialogue turns, but also within a turn, as
13 listeners produce backchannels (e.g., *Yes*, *OK*, or *eh?*) to provide continuous feedback to the
14 speaker. Moreover, such switches occur rapidly, as long intervals between turns are rare (Stivers et
15 al., 2009). Finally, such switches can occur at any point within an utterance, with listeners taking
16 over from speakers even after single words or incomplete constituents, and sometimes producing
17 grammatical and pragmatically appropriate completions to these fragments (e.g., Clark & Wilkes-
18 Gibbs, 1986; Lerner, 1991).

19 These phenomena demonstrate that the output of comprehension processes can rapidly affect
20 production processes. For example, understanding the speaker's utterance leads to rapid
21 backchannel responses from the listener and such backchannels can be quickly acted upon by the
22 speaker. This suggests that loops must exist between comprehension processes and production
23 processes, and that these loops must operate at a relatively fast rate. Moreover, the phenomenon of
24 collaborative turn completions also suggests continuity between production and comprehension
25 processes. Take the excerpt below (from Kurtić, Brown, & Wells, 2013, p. 726). B produces his
26 utterance as a completion to the first part of A's utterance (*so I'm not sure whether they'll still be so*
27 *willing to volunteer but I'll*) and it is so well-timed that it overlaps with the end of A's own turn
28 (brackets indicate the start and end of speech produced in overlap by A and B). In turn, A shows
29 evidence of having understood (and accepting) B's completion, despite it overlapping with her own
30 turn; in fact, she goes as far as repeating B's utterance word by word.

31 A: ...so I'm not sure whether they'll still be so willing to volunteer but I'll [send them an email and
32 ask]

1 B: [tell them about the free lunch]

2 A: I'll tell them about the free lunch

3 Finally, inter-turn intervals tend to cluster around a value that varies between 0 and 200ms (across
4 languages; Stivers et al., 2009), with both long gaps and long overlaps being comparatively rare.
5 This further suggests close links between production and comprehension, and has prompted the
6 suggestion that comprehenders might be able to anticipate turn ends (de Ruiter, Mitterer, & Enfield,
7 2006; Magyari & de Ruiter, 2012).

8

9 **Summary**

10 In this chapter, we have described several models that posit explicit links between
11 production and comprehension. It is generally agreed that information about concepts, lemmas, and
12 syntactic frames is shared between production and comprehension processes. But opinions diverge
13 on the degree of sharing of phonological information, and most theorists assume that phonetic
14 representations are separate (despite some dissent). Both the language production and the language
15 comprehension literatures have internal debates about the directionality of processes, but such
16 debates have not been framed as debates about the sharing of processes between production and
17 comprehension until quite recently.

18 In Figure 1A, we assumed that any process that maps from “higher” linguistic levels
19 (semantics) to “lower” linguistic levels (phonology) should be named a production process (left-to-
20 right arrows), and that every process that maps in the inverse direction (right-to-left arrows) should
21 be named a comprehension process. Based on this definition, we identified three accounts that
22 assume comprehension processes take place during acts of production, in the form of self-
23 monitoring: Levelt’s (1989) Perceptual Loop theory (solid lines in Figure 1B), neuro-computational
24 models of speech motor control (such as Hickok, 2012), and Pickering and Garrod’s (2013)
25 integrated account of language production and comprehension (dotted lines in Figure 1B). Such
26 accounts differ in terms of the nature and speed of the loops they assume exist between production
27 and comprehension.

28 We presented two accounts that assume that production processes take place during acts of
29 comprehension to support prediction: Pickering and Garrod’s integrated account, and the P-chain
30 framework. In addition, we briefly described a number of frameworks that posit slower-cycling
31 loops between production and comprehension; that is, loops that are mediated by long-term

1 experience with language and that can explain the development of linguistic preferences (dashed
2 lines in Figure 1B). Overall, many researchers assume some degree of sharing of processes, but the
3 range of views on this issue is far wider than on the issue of shared representations. Finally, we
4 noted that the assumption of links between language production and language comprehension is
5 also motivated by language use in dialogue. We believe that more explicit theorizing on the
6 relations between production and comprehension processes, in both monologue and dialogue,
7 would benefit the field.

8

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11

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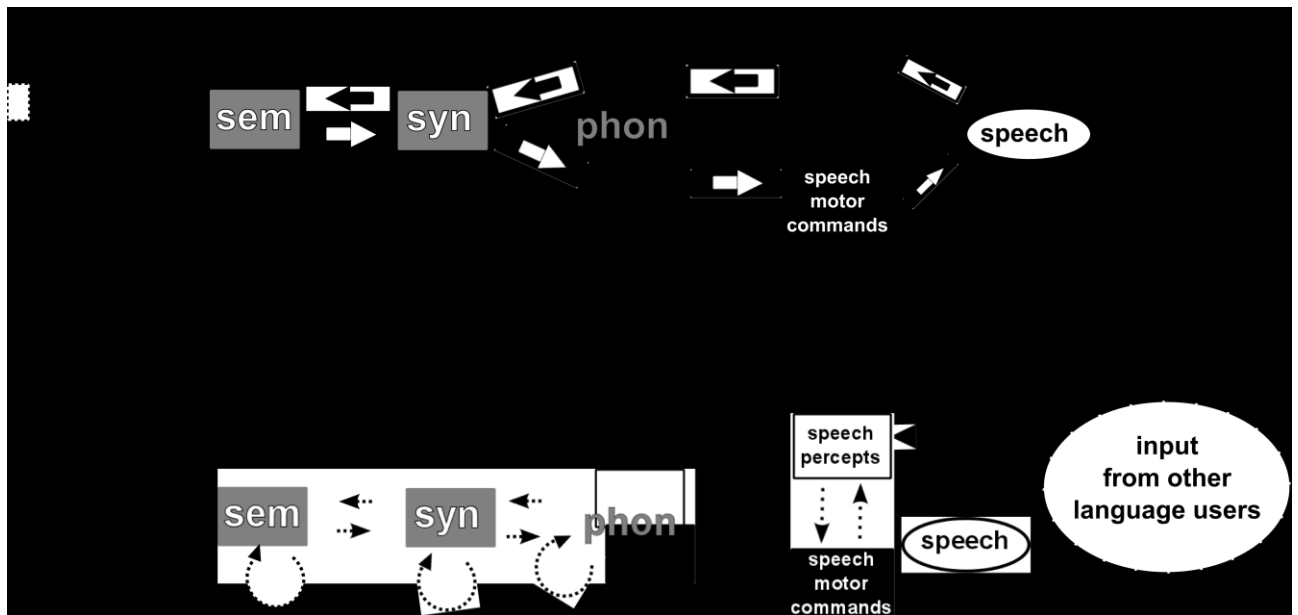
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1 Figure 1 – Panel A shows production processes (white arrows on black background) and
 2 comprehension processes (black arrows on white background); Panel B shows loops: the solid line
 3 is Levelt’s (1989) Perceptual Loop; the dotted arrows are Pickering and Garrod’s (2013) fast loops
 4 between and within levels; the dashed arrows are external loops that include long-term effects of
 5 exposure to distributional regularities in linguistic input (see *The P-chain framework*, and
 6 *Frameworks that posit linked preferences*).



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ⁱ Note that the description provided by Pickering and Garrod (2013), and summarized here, appears to imply separate production and comprehension representations at all levels. In practice, the theory is consistent with the idea that the same representations are accessed during production as well as during comprehension. The two sets of representations they assume correspond to the output stage of production and comprehension processes respectively, but such processes may have access to the same pool of representations.

ⁱⁱ In the example, we focus on single word retrieval. However, Pickering and Garrod (2013) have also discussed this process in relation to constituent ordering (p. 339).

ⁱⁱⁱ Note that within this single cognitive architecture, the Dual path model incorporates separate weights for the word-to-syntax (“comprehension”) and syntax-to-word (“production”) directions, but both of these representations are hypothesized to be used in both comprehension and production tasks.