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1 2 3 4 5	Postural control and gait measures derived from wearable inertial measurement unit devices in Huntington's disease: recommendations for clinical outcomes			
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30 31 32 33 34 35 36 37 38 39 40 41	Corresponding Author: Lori Quinn, PT, EdD, FAPTA Neurorehabilitation Research Laboratory Teachers College of Columbia University 525 W. 125 th Street, Thorndike 1051, Box 199 New York City, NY 10027. USA Email: <u>lq2165@tc.columbia.edu</u> Abstract Word Count: 241 Main Text Word Count: 3253			

43 44

45 Background

Abstract

46 Postural control impairments begin early in Huntington's disease yet measures most sensitive to
47 progression have not been identified. The aims of this study were to: 1) evaluate postural control
48 and gait in people with and without Huntington's disease using wearable sensors; and 2) identify
49 measures related to diagnosis and clinical severity.

50

51 *Methods*

41 individuals with Huntington's disease and 14 age-matched peers performed standing with feet together and feet apart, sitting, and walking with wearable inertial sensors. One-way analysis of variance determined differences in measures of postural control and gait between early and middisease stage, and age-matched peers. A random forest analysis identified Features of Importance for Huntington's disease diagnosis. Stepwise and ordinal regressions were used to determine predictors of clinical chorea and tandem walking scores respectively.

58

59 Findings

There was a significant main effect for all postural control and gait measures comparing early stage, mid stage and age-matched peers, except for gait cycle duration and step duration. Total sway, root mean square and mean velocity during sitting, as well as gait speed had the greatest importance in classifying disease status. Stepwise regression showed that root mean square during standing with feet apart significantly predicted clinical measure of chorea, and ordinal regression model showed that root mean square and total sway standing feet together significantly predicted clinical measure of tandem walking.

67	
68	Interpretations
69	Root mean square measures obtained in sitting and standing using wearable sensors have the
70	greatest potential to serve as biomarkers of postural control impairments in Huntington's disease.
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72	Highlights
73	• Sensor-derived postural control measures are discriminative in Huntington's disease
74	• Root mean square measures predict disease status and correlate to clinical measures
75	• Root mean square during sitting and standing are potential disease biomarkers
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Introduction

84

85	Huntington's disease (HD) is a genetic neurodegenerative disorder marked by a triad of
86	motor, behavioral and cognitive manifestations. (Bunner and Rebec, 2016; Tian et al., 2012) As
87	a result of degeneration of the striatum, HD elicits hallmark motor deficits including impaired
88	postural control from early in the disease process. Postural control deficits in HD are
89	characterized by mis-scaling of accelerations and durations, and excessive excursions in both
90	static and dynamic contexts, (Delval et al., 2011; Moisello et al., 2011; Salomonczyk et al.,
91	2010) that interfere with stability. Although existing clinician-rated measures, such as items on
92	the United Huntington's Disease Rating Scale-Total Motor Score (UHDRS-TMS), (Kieburtz,
93	1996) can provide insight into general balance performance (e.g. tandem walking and
94	retropulsion pull tests), there remains a need for objective measures to accurately assess non-
95	observable aspects of postural control. Objective markers of postural control provide insight into
96	functional independence, and factor into important aspects of clinical decision making in HD,
97	such as fall risk and the likelihood of nursing home admission.(Wheelock et al., 2003)
98	Ultimately, precise and reliable measures can elucidate postural control impairments in HD and
99	function as a marker for disease progression. (Salomonczyk et al., 2010).
100	Postural control encompasses the ability of an individual to maintain equilibrium during
101	both static and dynamic tasks. (Dunsky et al., 2017; Lazarotto et al., 2020) During static tasks,
102	which include sitting and standing, the motor system prioritizes maintaining the center of mass
103	within the base of support to maintain stability. Dynamic tasks, such as walking and reaching,

104 challenge the system to integrate the modulation of center of mass within the constraints of a

105 volitional movement. Under both circumstances, the motor system aims to minimize the risk of

106 falls. In non-HD populations, properties of an individual's postural control, such as total sway 107 and trunk velocity and acceleration, are tempered and scaled to the demands of a task. (Horak, 108 2006) Previous work in HD demonstrated an inability to appropriately scale postural control in 109 the context of dynamic movements such as gait and reaching, (Delval et al., 2007; Mann et al., 110 2012) which can ultimately contribute to an increase in fall risk. (Grimbergen et al., 2008) 111 Deficits in postural control are apparent early in HD and worsen with progressive striatal 112 degeneration, which both directly and indirectly influence the output of the reticulospinal, 113 vestibulospinal, and corticospinal tracts needed for voluntary postural control. (Jacobs and 114 Horak, 2007) A deeper understanding of specific properties of postural control that are most 115 impaired in persons with HD will lead to targeted rehabilitation programs for motor deficits that 116 negatively affect function and contribute to fall risk (Grimbergen et al., 2008).

117 The presence of involuntary movements, such as chorea, creates a further challenge in 118 measuring postural control in individuals with HD. Chorea consists of writhing involuntary 119 movements of the face, neck, upper extremities, lower extremities, or trunk, and can cause a shift 120 to the center of mass affecting postural control. (Berardelli et al., 1999) Chorea and postural 121 control are typically assessed using subjective clinical ratings from the UHDRS-TMS. This test 122 is inherently subjective, and ratings are typically non-linear, which limits the use of sensitive 123 parametric statistical methods. Clinical rating scales also only provide a brief 'snapshot' into any 124 disease, which remains problematic given the amount of heterogeneity of people with HD. 125 Quantitative analysis of movement has traditionally involved use of marker-based motion

126 capture camera systems or use of force plates to measure spatiotemporal features of gait and
127 postural control.(Miller et al., 2016) However, marker-based systems are costly, require an
128 extensive setup time, and often require advanced programming skills for data processing. More

129 recently, wearable sensors have been shown to be capable of providing reliable and valid 130 measurements of motor impairments, including postural control.(Kobsar et al., 2020; Simoes, 2011; Washabaugh et al., 2017) The benefits and utility of wearables has been demonstrated in 131 132 people with neurodegenerative diseases such as Parkinson's disease (PD) to measure tremor, 133 gait, and postural control. (Horak and Mancini, 2013; Washabaugh et al., 2017) Several recent 134 studies have also demonstrated their clinical utility in individuals with HD. (Dalton et al., 2013; 135 Porciuncula et al., 2020; Purcell et al., 2020; Tortelli et al., 2021; Trojaniello et al., 2015) IMUs 136 can measure discrete biomechanical properties of postural control quality and impairments, such 137 as jerk, total sway, and acceleration values, which may be more sensitive to motor impairments 138 than current clinical measures. (Adams et al., 2017; Andrzejewski et al., 2016) 139 In order to address this need for quantitative measures of postural control, we analyzed 140 postural control in sitting and standing conditions. The aims of this study were to 1) evaluate 141 differences in postural control and gait between non-HD individuals and those with HD from 142 wearable sensors; and 2) identify measures related to diagnosis and clinical measures of manifest 143 HD. The aims addressed in this study will ultimately provide recommendations for candidate 144 measures for use as clinical biomarkers. 145 146 Methods 147 148 Study Design 149 This cross-sectional study evaluated participants during one session at three sites (George 150 Huntington Institute, Munster, Germany; Teachers College, Columbia University, New York, 151 USA and Wayne State University, Detroit, Michigan, USA). The study was approved by the

152	Ethics or Institutional Review Boards at each site. Cardiff University was the study sponsor and
153	the Wales Research Ethics Committee also approved the study protocol. The data presented here
154	was part of a larger study integrating wearable technologies to quantify meaningful activity in
155	Huntington's disease (iWEAR-HD).
156	
157	Participants
158	Participants were included if they met the following inclusion criteria: 1) genetically
159	confirmed diagnosis of HD; 2) Total Functional Capacity (TFC) score \geq 7; 3) 18 years of age or
160	older; and 4) able to walk 10 meters independently without assistance devices. Participants were
161	excluded if they had: 1) A diagnosis of juvenile onset HD; 2) history of comorbid neurological
162	conditions such as stroke or multiple sclerosis; 3) acute orthopedic conditions; and 4) the
163	inability or unwillingness of participant or legal guardian to give written informed consent.
164	Demographics of all participants are listed in Table 1.
165	TABLE 1 HERE
166	
167	Procedures
168	UHDRS (TMS and TFC) (Kieburtz, 1996) were collected within three months of their
169	study visit. If this was not available, the UHDRS was administered as a part of the study visit.
170	The UHDRS TFC is a measure of functional ability, with scores ranging from 0 to 13, where
171	higher scores indicate greater functioning. HD1 (early stage) manifest-HD was categorized as
172	TFC scores of 11-13 while HD2 (mid stage) was TFC scores 7-10. These classifications were
173	based on previous research that aimed to identify imaging measures as clinical outcome
174	measures within HD. (Tabrizi et al., 2013) The UHDRS-TMS ranges in scores from 0 to 120,

175 with higher scores indicating a greater level of motor impairment. Each item is rated on a 0-4176 scale with 0 = Absent, 1 = Slight/Intermittent, 2 = Mild/Common or Moderate/Intermittent, 3 =177 Moderate/ Common, 4 = Marked/ Prolonged. The UHDRS chorea sub score was calculated from 178 the UHDRS-TMS by summing trunk and extremities chorea scores (5 items). The UHDRS 179 chorea sub score ranges from 0-20, with lower scores indicating little to no chorea and higher 180 scores indicating greater chorea. Face and bucco-oral-lingual chorea scores were removed due to 181 their lack of association with the postural measures of interest. Chorea sub scores were used to 182 identify postural control measures that could best predict chorea. Clinical balance measures in 183 this study were represented by UHDRS tandem walking scores. Tandem walking is rated on a 0-184 4 scale, where 0 indicates normal heel-to-toe walking for 10 steps and a score of 4 indicates an 185 inability to attempt the motor task.

186 Participants were fitted with six Opal V2 IMUs (Ambulatory Parkinson's Disease 187 Monitoring (APDM) opal sensors (ERT, Portland, OR, USA). Opal sensors have triaxial 188 accelerometers that measure linear acceleration, a gyroscope to measure angular velocity, and a 189 magnetometer for positional orientation.(Horak and Mancini, 2013). Data were processed using Mobility Lab 2.0[©] software (2015). Postural measures included total sway area, root mean 190 191 square (RMS) of sway, mean velocity and jerk. Total sway area signifies the extent of movement 192 around the center of gravity. RMS of sway is a time-domain measure, representing 193 the average variance. Mean velocity is the average rate of change in position during a certain 194 period of time. Jerk is a derivative of acceleration that reflects smoothness of movement. The 195 wearable sensors captured movement as participants sat quietly for 30 seconds in an armless 196 chair with their feet flat on the floor, hands resting in their lap, and their lower back away from 197 the back of the seat. Participants also stood quietly for 45 seconds with their feet hip width apart

198 (standardized using the APDM foot plate) and 45 seconds with their feet together. During the

199 gait task, participants walked 7 meters to a marking on the floor, turned around and returned to

200 the initial position. Gait variables that were extracted from Mobility Lab included gait speed,

201 percentage of time spent in stance and double support, and stride length.

202 Data Analysis

Statistical analyses were performed using R (Version 4.02; R Foundation for Statistical
Computing, 498 Vienna, AT). Two methods were used to determine the most sensitive measures
of dysfunction in postural control between individuals with HD and non-HD peers: Standardized
Mean Difference (*SMD*) and Random Forest. The *SMD* is a measure of effect size determined by
the following two equations:

 $SMD = \frac{\overline{X_1} - \overline{X_2}}{S}$

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- 211

212	$S = \left(\frac{SD_1^2}{n_1} + \frac{SD_2^2}{n_2}\right)$	$\times \left(\frac{n_1 \times n_2}{n_1 + n_2} \right)$
213	· · · · · ·	

where X_1 and X_2 are the means of the HD and non-HD groups, respectively. *S* is the pooled standard deviation of the groups, where SD_1 , n_1 , SD_2 , and n_2 are the standard deviation and sample size of the HD group and the non-HD peer group, respectively. *SMD* values of >0.50 were retained as sensitive measures of UHDRS chorea sub score.

A Pearson correlation matrix was computed for participants with HD, which determined associations between all postural control and gait variables, in addition to TMS, TFC, UHDRS chorea subscore, and tandem walking score. A second Pearson correlation matrix was computed for non-HD peers, which included all postural control and gait variables. Furthermore, betweengroup differences in all postural control and gait variables were tested in the non-HD peer, HD1 (TFC<11), and HD2 (TFC 11-13) groups, using one-way analysis of variance (ANOVA). Post-
hoc differences were assessed using Tukey's test.

225 The random forest model was conducted by using the 'randomForest' package on R. The 226 random forest model is a machine learning approach that creates an ensemble of classification 227 and regression trees using a training dataset. In this experiment, a classification tree was 228 constructed using 80% of the total data. Once constructed, the remaining 20% of the data was 229 used to test the error rate of the classification tree. The random forest yields a variable ranking 230 metric termed 'mean decrease in Gini', which was used to represent features of importance of 231 predictor variables and was compared to SMDs. Mean decrease in Gini was also used for feature 232 selection to find a significant ordinal regression model to predict UHDRS tandem walking 233 scores.

234 Finally, we wanted to determine which measures derived from IMUs were best able to 235 predict clinical HD measures of chorea (UHDRS-TMS chorea subscore) and dynamic balance 236 (UHDRS-TMS tandem walking). To determine wearable measures capable of predicting chorea, 237 variables from the wearables (i.e., jerk, total sway area, RMS, mean velocity, gait speed, gait 238 stride length) of all postural control and gait conditions were entered into a forward stepwise 239 regression model, as chorea sub scores were treated as ratio data. Variables with 240 multicollinearity (VIF \geq 10) were removed from the stepwise regression. Lowest Akaike 241 information criterion (AIC) was used for model comparison to determine the final regression 242 model. To determine measures capable of predicting UHDRS tandem walking scores, the 243 aforementioned variables of postural control and gait were entered into a random forest model. 244 The parameters with the highest mean decrease index of Gini were entered into an ordinal 245 regression model. Significance level was set at P < 0.05.

246	Results
247	
248	There was a significant main effect for all postural control and gait measures comparing
249	HD1 and HD2 and non-HD peers, except for gait cycle duration and step duration ($P > .05$)
250	(Table 2). Post-hoc comparisons revealed a significant difference between the HD2 and non-HD
251	peers for all measures, except jerk feet together ($P > .05$). Post-hoc comparisons between HD1
252	and non-HD peers revealed differences in RMS sitting ($P = .022$). Further, there were significant
253	differences between HD1 and HD2 groups in RMS feet apart, RMS feet together, jerk feet apart,
254	jerk sitting, and gait speed (Table 2).
255	
256	INSERT TABLE 2 HERE
257	
258	SMDs that compared differences between each HD group to non-HD peers are shown in
259	Table 3. The highest SMDs found for both HD groups occurred in RMS feet apart (HD2: 19.94,
260	HD1: 5.58), RMS feet together (HD2: 19.65, HD1: 6.36), and step duration (HD2: 6.44, HD1:
261	5.87).
262	INSERT TABLE 3 HERE
263	
264	Pearson correlations were calculated for both HD and non-HD peers groups separately
265	and are graphically represented in matrices found in Figure 1a and 1b.
266	INSERT FIGURE 1 HERE
267	

268	Mean decrease in Gini derived from the random forest model showed that total sway
269	sitting (3.57), RMS sitting (2.22), mean velocity sitting (2.09), and gait speed (1.32) had the
270	greatest features of importance for accurate classification of individuals into either the HD or
271	non-HD group.
272	Stepwise regression revealed a significant linear model, shown in Figure 2 in which RMS
273	during standing feet apart (β = 9.19, P < .001) predicted chorea subscore (F (1, 38) = 11.74, P <
274	.0015, $R^2 = 0.216$). The random forest model revealed that RMS feet together (Odds Ratio: 6.74)
275	and total sway feet together (Odds Ratio: -0.002) predicted UHDRS tandem walking scores
276	$(\chi^2(2) = 13.38, P < .001, Nagalkerke R^2 = 0.30).$
277	
278	INSERT FIGURE 2 HERE
279	
280	Discussion
281	Consistent with previous findings, our results indicated significant differences between HD
282	and non-HD peers across most variables of postural control that were measured within and across
283	conditions. (Porciuncula et al., 2020; Salomonczyk et al., 2010; Tian et al., 1991) Individuals with
284	HD performed significantly worse than non-HD peers on variables of postural control including
285	greater sway area, greater acceleration values in static standing and sitting, and greater jerk values
286	during quiet standing and sitting. These differences were more pronounced between non-HD peers
287	and HD individuals with TFC scores below 11 (HD2). We found that RMS during standing feet
288	apart best predicted UHDRS chorea subscore, and RMS and total sway during standing feet
289	together best predicted UHDRS tandem walking scores. RMS, total sway, and mean velocity
200	during sitting were postural measures most associated with an HD diagnosis. Given their ability to

291 predict preexisting clinical measures and HD diagnosis, we identified RMS measures in sitting 292 and standing as candidate biomarkers of postural control. Among RMS measures, we determined 293 that RMS during sitting is a suitable biomarker of postural control for its capacity to discriminate 294 between high TFC groups and non-HD peers, and its feasibility for data collection within in an 295 HD population.

296 RMS is the average composite value of acceleration of sway derived from the lumbar 297 sensor. The SMD of RMS between non-HD and HD groups indicated a moderate effect size across 298 all tasks (above .5) (Table 3). Interestingly, although RMS measures during standing successfully 299 discriminated between HD1 and HD2, RMS during sitting remained the only variable with the 300 discriminative capacity to discern between the HD (higher functioning) and non-HD peers. 301 Although jerk values exhibited acceptable SMD values and differences between low and high TFC 302 groups, within group variability was too large, as represented by large standard deviations, and 303 therefore not included in the random forest tree model.

304 Often HD individuals with higher TFC scores do not exhibit motor symptoms that can be 305 easily identified by clinicians. However, non-observable deficits in motor control are evident in 306 pre-manifest and early-stage HD, (Delval et al., 2011; Salomonczyk et al., 2010) which are more 307 easily captured by inertial sensors. (Andrzejewski et al., 2016; Fusca et al., 2018) Our findings on 308 RMS values during sitting further confirm this and introduce the idea that static sitting may elicit 309 more acceleration-based, measurable responses in force modulation impairments in HD. It is 310 possible that in standing, the motor system prioritizes stability and fall prevention by introducing 311 constraints to limit excessive sway. During sitting, the risk of fall is minimal relative to standing 312 thereby decreasing the demand of constraints needed to prioritize stability. The overall result is 313 that when seated, participants with HD could generate greater movement with less force

315

316 The UHDRS chorea subscore used in this study was comprised of scores assessing the 317 severity of chorea present in the trunk and extremities. Among the IMU-derived measures of 318 postural control our findings indicated that RMS and mean velocity during sitting predicted chorea 319 subscores. Aside from the association between lumbar total sway and visual trunk displacement, 320 it is likely that pronounced chorea in extremities would be associated with greater displacement of 321 the trunk due to postural disturbances and intersegmental dynamics. (Grimbergen et al., 2008; 322 Kegelmeyer et al., 2017) Therefore, RMS and mean velocity during sitting may function as an 323 indirect measure of chorea.

324 From our findings, we propose that RMS during sitting and standing derived from IMUs 325 can serve as clinical outcome measures for postural control in individuals with HD. These 326 measures are recommended due to their ability to predict both HD status and UHDRS tandem 327 walking scores. These measures also had relatively low variability and larger discriminative 328 validity, as determined by SMD values, relative to the remaining measures. Furthermore, the effect 329 sizes of RMS values are consistent with previous findings indicating that larger accelerations and 330 force productions within HD groups occur across motor tasks. (Moisello et al., 2011; Reilmann 331 and Schubert, 2017) Our results show that IMU sensors can capture force modulation impairments, 332 as represented by larger acceleration values, that are characteristic in HD. This further confirms 333 the notion that IMU wearable devices can detect subtle differences in postural control that cannot 334 be captured by clinical scales. The subjective nature of the UHDRS tandem walking score makes 335 it unlikely that this clinical measure could detect more subtle changes in postural control in HD. 336 Wearable-derived candidate measures of postural control were both associated with the

aforementioned clinical scales and captured non-observable and reliable measures of posture specific to HD as compared to non-HD peers, and characteristic of the disease. The wearablederived outcome measures of postural control identified in this study can ultimately allow for the ability to discriminate between disease stages and potentially to evaluate intervention effectiveness as clinical endpoints.

342 Some limitations that can be addressed for future studies include the use of a single vs 343 multiple trials. Results from our study are from a single trial of each task across participants. This 344 may limit the generalizability as multiple trials can improve sensitivity of each measure. Future 345 work should also address the reliability of these measures over the course of HD, including a pre-346 manifest HD group, where postural impairments are more subtle. Lastly, future work can 347 determine whether these postural measures are sensitive to intervention. Identifying response to 348 time with HD and intervention are integral next steps for evaluating the usability of these measures 349 in clinical trials.

- 350
- 351 352

Conclusion

RMS measures derived from IMUs during sitting and standing were most related to HD status and severity and have the potential to serve as clinical outcome measures for postural control in HD. Measures of total sway area of FA and sitting are likely influenced by choreic movements, whereas RMS FT, jerk FA and RMS sitting are likely to best reflect postural control impairments. Differences in postural control variables were more pronounced between non-HD peers and HD individuals with TFC scores below 11. Future studies can determine sensitivity to time and intervention in these postural control measures.

360

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- 370

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Table 1. Participant Characteristics

	All Participants with HD (n=43)	TFC 7 -10 (n=28)	TFC 11-13 (n=15)	Non-HD peers (n=15)
Age(years)	56.9 (11.7)	55.9 (9.6)	50.9 (14.2)	53.1 (13.3)
Sex (M/F)	25/19	14/14	11/4	7/7
Height (cm)	173.6 (9.6)	172.3(9.4)	175.7 (9.5)	169.2 (10.8)
Weight(kg)	75.0 (14.8)	76.4(16.3)	73.2 (12.1)	79.6 (12.1)
UHDRS TMS	40.6 (16.2)	48 (12)	27 (14)	NA
UHDRS SDMT	27.5 (12)	22 (9)	37.5 (11)	NA
UHDRS Chorea	10 (5)	12 (5)	9 (5)	NA
Subscore				
UHDRS FA	22 (3)	20 (3)	24 (1)	NA
UHDRS Ind.	84 (9)	80 (10)	90 (6)	NA
# of Fallers	24	19	5	NA

Table 1: Demographics of all participants are represented as means(SD) except sex, which is

reported number of participants. Unified Huntington's Disease Rating Scale (UHDRS) total

motor score (TMS) is a sum of all sub scores rated on a 0-4 scale, where 0 represents an absence

of impairment and 4 represents a pronounced impairment. UHDRS Symbol Digit Modalities

Test (SDMT) measure executive functioning as represented by values correct from 0 to 110.

UHDRS Chorea sub score is a sum of sub scores of 0-4, where 0 represents an absence of chorea

and 4 represents pronounced presence, totaling in 28 points. UHDRS Functional Assessment

(FA) scores are out of 25, where larger values represent higher functioning, and independence

(Ind) scores, where higher scores represent greater independence, are rated 0-100.

Table 2: Raw mean values, standard deviations, and coefficient of variation for all postural control

and gait variables in persons with HD and non-HD peers. Standardized mean difference is a
 measure of effect size

Feet Apart Feet Together 0.10(0.04) 0.21(0.19) 0.33(0.17) 5.58 19.94 RMS Feet Together Sitting 0.06(0.05) 0.25(0.19) 0.39(0.18) 6.36 19.65 Sitting 0.06(0.05) 0.54(0.47) 0.63(0.60) 4.40 4.44 Feet Apart 1.50(1.06) 22.0(37.6) 70.5(80.8) 0.029 0.030 Jerk Feet Together 3.42(4.3) 19.6(25.4) 114.0(183) 0.049 0.0094 Sitting 1.15(1.60) 36.7(31.8) 92.7(97.41) 0.070 0.028 Mean Feet Together 0.32(0.15) 0.61(0.58) 0.80 (0.49) 1.22 3.40 Feet Apart 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Sitting 0.11(0.11) 0.80 (0.71) 1.21 (1.24) 2.71 2.02 Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sway </th <th></th> <th></th> <th>Non-HD Peers</th> <th>HD (TFC11-13)</th> <th>HD (TFC<11)</th> <th><i>SMD</i> (TFC11- 13)</th> <th>SMD (TFC<11)</th>			Non-HD Peers	HD (TFC11-13)	HD (TFC<11)	<i>SMD</i> (TFC11- 13)	SMD (TFC<11)
RMS Feet Together 0.12(0.05) 0.25(0.19) 0.39(0.18) 6.36 19.65 Sitting 0.06(0.05) 0.54(0.47) 0.63(0.60) 4.40 4.44 Feet Apart 1.50(1.06) 22.0(37.6) 70.5(80.8) 0.029 0.030 Jerk Feet Together 3.42(4.3) 19.6(25.4) 114.0(183) 0.049 0.0094 Sitting 1.15(1.60) 36.7(31.8) 92.7(97.41) 0.070 0.028 Mean Feet Apart 0.33(0.18) 0.45(0.41) 0.68 (0.49) 1.22 3.40 Vel. Feet Together 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Sitting 0.11(0.11) 0.80 (0.71) 1.21 (1.24) 2.71 2.02 Total Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Sway Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sway Stiting 0.29 (0.37) 56.9 (66.8) 79.9(105)		Feet Apart	0.10(0.04)	0.21(0.19)	0.33(0.17)	5.58	19.94
Sitting 0.06(0.05) 0.54(0.47) 0.63(0.60) 4.40 4.44 Feet Apart 1.50(1.06) 22.0(37.6) 70.5(80.8) 0.029 0.030 Jerk Feet Together 3.42(4.3) 19.6(25.4) 114.0(183) 0.049 0.0094 Sitting 1.15(1.60) 36.7(31.8) 92.7(97.41) 0.070 0.028 Mean Feet Apart 0.33(0.18) 0.45(0.41) 0.68 (0.49) 1.22 3.40 Feet Together 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Sitting 0.11(0.11) 0.80 (0.71) 1.21 (1.24) 2.71 2.02 Total Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Sway Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Gait Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 </td <td>RMS</td> <td>Feet Together</td> <td>0.12(0.05)</td> <td>0.25(0.19)</td> <td>0.39(0.18)</td> <td>6.36</td> <td>19.65</td>	RMS	Feet Together	0.12(0.05)	0.25(0.19)	0.39(0.18)	6.36	19.65
Jerk Feet Apart 1.50(1.06) 22.0(37.6) 70.5(80.8) 0.029 0.030 Sitting 1.15(1.60) 36.7(31.8) 92.7(97.41) 0.070 0.028 Mean Feet Apart 0.33(0.18) 0.45(0.41) 0.68 (0.49) 1.22 3.40 Feet Together 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Sitting 0.11(0.11) 0.80 (0.71) 1.21 (1.24) 2.71 2.02 Total Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sway Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Gait Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13 <td></td> <td>Sitting</td> <td>0.06(0.05)</td> <td>0.54(0.47)</td> <td>0.63(0.60)</td> <td>4.40</td> <td>4.44</td>		Sitting	0.06(0.05)	0.54(0.47)	0.63(0.60)	4.40	4.44
Jerk Feet Together Sitting 3.42(4.3) 19.6(25.4) 114.0(183) 0.049 0.0094 Mean Vel. Feet Apart 0.33(0.18) 0.45(0.41) 0.68 (0.49) 1.22 3.40 Mean Vel. Feet Together 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Sitting 0.11(0.11) 0.80 (0.71) 1.21 (1.24) 2.71 2.02 Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Gait Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13		Feet Apart	1.50(1.06)	22.0(37.6)	70.5(80.8)	0.029	0.030
Sitting 1.15(1.60) 36.7(31.8) 92.7(97.41) 0.070 0.028 Mean Vel. Feet Apart 0.33(0.18) 0.45(0.41) 0.68 (0.49) 1.22 3.40 Feet Together 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Sitting 0.11(0.11) 0.80 (0.71) 1.21 (1.24) 2.71 2.02 Total Sway Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Gait Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sway Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Cycle Duration 1.06(0.12) 1.09(0.09) 1.10(0.13) 3.18 3.70 Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13	Jerk	Feet Together	3.42(4.3)	19.6(25.4)	114.0(183)	0.049	0.0094
Mean Vel. Feet Apart Feet Together 0.33(0.18) 0.45(0.41) 0.68 (0.49) 1.22 3.40 Sitting 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Total Sway Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Gait Cycle Duration 1.06(0.12) 1.09(0.09) 1.10(0.13) 3.18 3.70 Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13		Sitting	1.15(1.60)	36.7(31.8)	92.7(97.41)	0.070	0.028
Vel. Feet Together Sitting 0.32(0.15) 0.61(0.58) 0.80 (0.58) 1.59 3.63 Total Sway Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Cycle Duration 1.06(0.12) 1.09(0.09) 1.10(0.13) 3.18 3.70 Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13		Feet Apart	0.33(0.18)	0.45(0.41)	0.68 (0.49)	1.22	3.40
Vet. Sitting 0.11(0.11) 0.80 (0.71) 1.21 (1.24) 2.71 2.02 Total Sway Feet Apart 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Sway Feet Together 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Gait Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13	viean	Feet Together	0.32(0.15)	0.61(0.58)	0.80 (0.58)	1.59	3.63
Total Sway Feet Apart Feet Together 1.80 (1.8) 14.8 (24.8) 36.6 (39.8) 0.042 0.062 Sway Feet Together Sitting 0.29 (0.37) 56.9 (66.8) 79.9 (105) 0.025 0.021 Gait Cycle Duration 1.06(0.12) 1.09 (0.09) 1.10 (0.13) 3.18 3.70 Speed 1.32 (0.26) 1.22 (0.20) 1.04 (0.21) -1.84 -4.66 Step Duration 0.53 (0.06) 0.55 (0.04) 0.56 (0.07) 5.87 6.44 Stride Length 1.37 (0.19) 1.31 (0.15) 1.14 (0.19) -1.76 -6.13	vei.	Sitting	0.11(0.11)	0.80 (0.71)	1.21 (1.24)	2.71	2.02
Total Sway Feet Together Sitting 4.06(4.0) 20.4(27.0) 46.4 (51.7) 0.044 0.045 Gait Cycle Duration 1.06(0.12) 1.09(0.09) 1.10(0.13) 3.18 3.70 Gait Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13	T-4-1	Feet Apart	1.80 (1.8)	14.8 (24.8)	36.6 (39.8)	0.042	0.062
Sway Sitting 0.29 (0.37) 56.9 (66.8) 79.9(105) 0.025 0.021 Gait Cycle Duration 1.06(0.12) 1.09(0.09) 1.10(0.13) 3.18 3.70 Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13	lotal	Feet Together	4.06(4.0)	20.4(27.0)	46.4 (51.7)	0.044	0.045
Gait Cycle Duration 1.06(0.12) 1.09(0.09) 1.10(0.13) 3.18 3.70 Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13	Sway	Sitting	0.29 (0.37)	56.9 (66.8)	79.9(105)	0.025	0.021
Gait Speed 1.32(0.26) 1.22(0.20) 1.04(0.21) -1.84 -4.66 Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13		Cycle Duration	1.06(0.12)	1.09(0.09)	1.10(0.13)	3.18	3.70
Gan Step Duration 0.53(0.06) 0.55(0.04) 0.56(0.07) 5.87 6.44 Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13	0-4	Speed	1.32(0.26)	1.22(0.20)	1.04(0.21)	-1.84	-4.66
Stride Length 1.37(0.19) 1.31(0.15) 1.14(0.19) -1.76 -6.13	Galt	Step Duration	0.53(0.06)	0.55(0.04)	0.56(0.07)	5.87	6.44
		Stride Length	1.37(0.19)	1.31(0.15)	1.14(0.19)	-1.76	-6.13

Table 3. Comparison of postural control and gait variables between Low TFC (LTFC; TFC <11),

560	High TFC (HTFC; TFC \geq 11) and non-HD peer, using ANOVA and Tukey post-hoc pairwise	
561	comparison. * Denotes a main significant effect of group. Only significant pairwise post-hoc	

301	comparison. * Denotes a	nam significant effect of	group.	Omy	significant	pairwise	po
567	tasts reported in table DI	- Degrees of Freedom					

		D.F.	F-value	<i>p</i> -value	Tukey post-hoc
	Feet Apart	(2,54)	11.13	<.001*	HD 2-HD 1: <i>p</i> = .04
					HD 2-Non HD: <i>p</i> <.001
DMC	Feet Together	(2,54)	13.24	<.001*	HD 2-HD 1: <i>p</i> = .027
KMS					HD 2-Non HD: <i>p</i> < .001
	Sitting	(2,55)	7.036	.0019*	HD 2-HD 1: <i>p</i> = .0016
					HD 1-Non HD: $p = .022$
	Feet Apart	(2,54)	7.457	.0014*	HD 2-HD 1: <i>p</i> = .036
					HD 2-Non HD: <i>p</i> =.0018
Jerk	Feet Together	(2,54)	4.593	.014*	HD 2-Non HD: $p = .026$
	Sitting	(2,55)	8.974	<.001*	HD 2-HD 1: <i>p</i> = .041
					HD 2-Non HD: <i>p</i> < .001
	Feet Apart	(2,54)	3.93	.026*	HD 2-Non HD: $p = .027$
Mean Vel.	Feet Together	(2,54)	4.355	.0018*	HD 2-Non HD: $p = .013$
	Sitting	(2,55)	6.44	.0026*	HD 2-Non HD: <i>p</i> =.0017
	Feet Apart	(2,54)	6.845	.0022*	HD 2-Non HD: <i>p</i> =.0022
Total Sway	Feet Together	(2,54)	6.289	.0035*	HD 2-Non HD: <i>p</i> =.0034
-	Sitting	(2,55)	4.742	.0126*	HD 2-Non HD: <i>p</i> =.0091
	Cycle	(2,54)	1.014	0.37	<u> </u>
	Duration				_
0-4	Speed	(2,54)	8.271	<.001*	HD 2-HD 1: <i>p</i> = .04
Galt					HD 2-Non HD: <i>p</i> <.001
	Step Duration	(2,54)	0.862	.428	_
	Stride Length	(2,54)	8.881	<.001*	HD 2-Non HD: <i>p</i> <.001

tests reported in table. D.F = Degrees of Freedom.

Figure 1. a) Pearson correlation tables of all IMU derived postural control and gait, in addition to clinical measures, and UHDRS chorea subscores for patients with HD. b) Pearson correlation tables of all IMU derived postural control and gait for non-HD peers.



590 Figure 2: Linear regression plot indicating significant model, where UHDRS Chorea sub score is

591 592 predicted by Root Mean Square (RMS) Feet Apart.

