# GEOMETRIC STRUCTURES ON THE ORBITS OF LOOP DIFFEOMORPHISM GROUPS AND RELATED HEAVENLY-TYPE HAMILTONIAN SYSTEMS. II 

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#### Abstract

We present a review of differential-geometric and Lie-algebraic approaches to the study of a broad class of nonlinear integrable differential systems of "heavenly" type associated with Hamiltonian flows on the spaces conjugated to the loop Lie algebras of vector fields on the tori. These flows are generated by the corresponding orbits of the coadjoint action of the diffeomorphism loop group and satisfy the Lax-Sato-type vector-field compatibility conditions. The corresponding hierarchies of conservation laws and their relationships with Casimir invariants are analyzed. We consider typical examples of these systems and establish their complete integrability by using the developed Lie-algebraic construction. We also describe new generalizations of the integrable dispersion-free systems of heavenly type for which the corresponding generating elements of the orbits have factorized structures, which allows their extension to the multidimensional case.


## 1. Multidimensional Systems of the Heavenly Type: Modified Lie-Algebraic Scheme

Let $\widetilde{\text { Diff }} \pm\left(\mathbb{T}^{n}\right), n \in \mathbb{Z}_{+}$, be subgroups of the diffeomorphism loop group

$$
\widetilde{\operatorname{Diff}}\left(\mathbb{T}^{n}\right):=\left\{\mathbb{C} \supset \mathbb{S}^{1} \rightarrow \operatorname{Diff}\left(\mathbb{T}^{n}\right)\right\}
$$

holomorphically extended to the interior $\mathbb{D}_{+}^{1} \subset \mathbb{C}$ and exterior $\mathbb{D}_{-}^{1} \subset \mathbb{C}$ of the central unit disk $\mathbb{D}^{1} \subset \mathbb{C}^{1}$, respectively, so that

$$
\tilde{g}(\infty)=1 \in \operatorname{Diff}\left(\mathbb{T}^{n}\right)
$$

for any $\tilde{g}(\lambda) \in \widetilde{\text { Diff }_{-}}\left(\mathbb{T}^{n}\right), \lambda \in \mathbb{D}_{-}^{1}$. The corresponding Lie subalgebras

$$
\widetilde{\operatorname{diff}}_{ \pm}\left(\mathbb{T}^{n}\right) \simeq \widetilde{\operatorname{Vect}}_{ \pm}\left(\mathbb{T}^{n}\right)
$$

of the diffeomorphism loop subgroups $\widetilde{\text { Diff }}_{ \pm}\left(\mathbb{T}^{n}\right)$ form vector fields on $\mathbb{T}^{n}$ that are holomorphic on the domains $\mathbb{D}_{ \pm}^{1} \subset \mathbb{C}^{1}$, respectively, where, for any $\tilde{a}(\lambda) \in \widetilde{\text { diff }}-\left(\mathbb{T}^{n}\right)$, we have $\tilde{a}(\infty)=0$.

The Lie algebra $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)$ can be split into the direct sum of two Lie subalgebras:

$$
\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)=\widetilde{\operatorname{diff}}+\left(\mathbb{T}^{n}\right) \oplus \widetilde{\operatorname{diff}}-\left(\mathbb{T}^{n}\right)
$$

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Its regular adjoint space $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}$ with respect to the convolution:

$$
\begin{equation*}
(\tilde{l} \mid \tilde{a}):=\underset{\lambda \in \mathbb{C}}{\operatorname{res}}(l(x ; \lambda) \mid a(x ; \lambda))_{H^{0}}, \tag{1.1}
\end{equation*}
$$

where

$$
(l(x ; \lambda) \mid a(x ; \lambda))_{H^{0}}:=\int_{\mathbb{T}^{n}} d x\langle l(x ; \lambda), a(x ; \lambda)\rangle
$$

is the ordinary scalar product in the Hilbert space $H^{0}:=L_{2}\left(\mathbb{T}^{n} ; \mathbb{R}^{n}\right)$ for any elements $\tilde{l} \in \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}$ and $\tilde{a} \in$ diff $\left(\mathbb{T}^{n}\right)$ of the form

$$
\begin{gathered}
\tilde{a}=\sum_{j=1}^{n} a^{(j)}(x ; \lambda) \frac{\partial}{\partial x_{j}}:=\left\langle a(x ; \lambda), \frac{\partial}{\partial x}\right\rangle, \\
\tilde{l}=\sum_{j=1}^{n} l_{j}(x ; \lambda) d x_{j}:=\langle l(x ; \lambda), d x\rangle,
\end{gathered}
$$

can be identified with the Lie algebra $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}$. Here,

$$
\frac{\partial}{\partial x}:=\left(\frac{\partial}{\partial x_{1}}, \frac{\partial}{\partial x_{2}}, \ldots, \frac{\partial}{\partial x_{n}}\right)^{\top}
$$

denotes the operator of gradient in the Euclidean space $\left(\mathbb{E}^{n} ;\langle\cdot, \cdot\rangle\right)$. The Lie commutator of any vector fields $\tilde{a}, \tilde{b} \in \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)$ can be found according to the rule

$$
\begin{aligned}
{[\tilde{a}, \tilde{b}] } & =\tilde{a} \tilde{b}-\tilde{b} \tilde{a} \\
& =\left\langle\left\langle a(x ; \lambda), \frac{\partial}{\partial x}\right\rangle b(x ; \lambda), \frac{\partial}{\partial x}\right\rangle-\left\langle\left\langle b(x ; \lambda), \frac{\partial}{\partial x}\right\rangle a(x ; \lambda), \frac{\partial}{\partial x}\right\rangle .
\end{aligned}
$$

In addition, we have the following identification of regular adjoint subspaces:

$$
\widetilde{\operatorname{diff}}_{+}\left(\mathbb{T}^{n}\right)^{*} \simeq \widetilde{\operatorname{diff}}_{-}\left(\mathbb{T}^{n}\right), \quad \widetilde{\operatorname{diff}}_{-}\left(\mathbb{T}^{n}\right)^{*} \simeq \widetilde{\operatorname{diff}}_{+}\left(\mathbb{T}^{n}\right),
$$

where any $\tilde{l}(\lambda) \in \widetilde{\operatorname{diff}}_{-}\left(\mathbb{T}^{n}\right)^{*}$ satisfies the condition $\tilde{l}(0)=0$.
We now construct the loop Lie algebra

$$
\tilde{\mathcal{G}}:=\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right) \ltimes \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}
$$

as the semidirect sum of the Lie algebra $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)$ and its regular adjoint space $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}$ on which the Lie commutator, for any pair of elements $\left(\tilde{a}_{1} \ltimes \tilde{l}_{1}\right),\left(\tilde{a}_{2} \ltimes \tilde{l}_{2}\right) \in \tilde{\mathcal{G}}$, is given by the rule

$$
\begin{equation*}
\left[\tilde{a}_{1} \ltimes \tilde{l}_{1}, \tilde{a}_{2} \ltimes \tilde{l}_{2}\right]:=\left[\tilde{a}_{1}, \tilde{a}_{2}\right] \ltimes\left(a d_{\tilde{a}_{2}}^{*} \tilde{l}_{1}-a d_{\tilde{a}_{1}}^{*} \tilde{2}_{1}\right), \tag{1.2}
\end{equation*}
$$

where

$$
\begin{gathered}
a d_{\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)}^{*}: \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*} \rightarrow \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}, \\
\left(a d_{\tilde{a}}^{*} \tilde{l} \mid \tilde{b}\right):=(\tilde{l} \mid[\tilde{a}, \tilde{b}]) \quad \text { for } \quad \tilde{l} \in \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*} \quad \text { and any } \quad \tilde{a}, \tilde{b} \in \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right),
\end{gathered}
$$

is a standard coadjoint mapping of the Lie algebra $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)$ on its regular adjoint space $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}$ with respect to convolution (1.1). On the Lie algebra $\tilde{\mathcal{G}}$, we can introduce an $a d$-invariant nondegenerate scalar product in the form

$$
\begin{equation*}
\left(\tilde{a}_{1} \ltimes \tilde{l}_{1} \mid \tilde{a}_{2} \ltimes \tilde{l}_{2}\right):=\left(\tilde{l}_{2} \mid \tilde{a}_{1}\right)+\left(\tilde{l}_{1} \mid \tilde{a}_{2}\right), \tag{1.3}
\end{equation*}
$$

where $\tilde{a}_{1} \ltimes \tilde{l}_{1}$ and $\tilde{a}_{2} \ltimes \tilde{l}_{2} \in \tilde{\mathcal{G}}$, which enables one to identify the regular adjoint space $\tilde{\mathcal{G}}^{*}$ with respect to (1.3) for the algebra $\tilde{\mathcal{G}}$ with this Lie algebra, i.e., $\tilde{\mathcal{G}}^{*} \simeq \tilde{\mathcal{G}}$.

We can split the Lie algebra $\tilde{\mathcal{G}}$ into the direct sum of two subalgebras [1-3]: $\tilde{\mathcal{G}}=\tilde{\mathcal{G}}_{+} \oplus \tilde{\mathcal{G}}_{-}$, where

$$
\tilde{\mathcal{G}}_{+}:=\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)_{+} \ltimes \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)_{-}^{*}, \quad \tilde{\mathcal{G}}_{-}:=\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)_{-} \ltimes \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)_{+}^{*} .
$$

This enables us to introduce a new Lie commutator on $\tilde{\mathcal{G}}$ in the form

$$
\left[\tilde{w}_{1}, \tilde{w}_{2}\right]_{\mathcal{R}}:=\left[\mathcal{R} \tilde{w}_{1}, \tilde{w}_{2}\right]+\left[\tilde{w}_{1}, \mathcal{R} \tilde{w}_{2}\right],
$$

where $\tilde{w}_{1}, \tilde{w}_{2} \in \tilde{\mathcal{G}}, \mathcal{R}:=\left(P_{+}-P_{-}\right) / 2$ is the standard $\mathcal{R}$-operator homomorphism [10, 11, 15] on $\tilde{\mathcal{G}}$ and, by definition, $P_{ \pm}: \tilde{\mathcal{G}} \rightarrow \tilde{\mathcal{G}}_{ \pm} \subset \tilde{\mathcal{G}}$. Thus, we can apply the classical AKS (Adler-Konstant-Symes) theory to the Lie algebra $\tilde{\mathcal{G}}$ in order to construct Hamiltonian systems on the regular adjoint space $\tilde{\mathcal{G}}^{*} \simeq \tilde{\mathcal{G}}$ with the use of hierarchies of Casimir invariants for the base Lie commutator (1.2).

To describe the corresponding Lie-algebraic scheme in detail, we determine the Casimir invariants $h \in I\left(\tilde{\mathcal{G}}^{*}\right)$. By definition, these invariants satisfy the relation

$$
a d_{\nabla h(\tilde{l} ; \tilde{a})}^{*}(\tilde{l} ; \tilde{a})=0,
$$

which can be rewritten in the commutator form as follows:

$$
\begin{equation*}
[\nabla h(\tilde{l} ; \tilde{a}), \tilde{a} \ltimes \tilde{l}]=0, \tag{1.4}
\end{equation*}
$$

where

$$
\nabla h(\tilde{l} ; \tilde{a}):=\nabla h_{\tilde{l}} \ltimes \nabla h_{\tilde{a}} \in \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right) \ltimes \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}=\tilde{\mathcal{G}}
$$

is the gradient of the Casimir invariant $h \in I\left(\tilde{\mathcal{G}}^{*}\right)$ at the point $(\tilde{l} ; \tilde{a}) \in \tilde{\mathcal{G}}^{*} \simeq \tilde{\mathcal{G}}$. Relation (1.4) is equivalent to the system of differential-algebraic equations

$$
\begin{gathered}
{\left[\nabla h_{\tilde{l}} ; \tilde{a}\right]=0,} \\
a d_{\nabla h_{\tilde{l}}^{*}}^{*} \tilde{l}-a d_{\tilde{a}}^{*} \nabla h_{\tilde{a}}=0 .
\end{gathered}
$$

In the explicit form, these equations can be rewritten as follows:

$$
\begin{gather*}
\left\langle\nabla h_{l}, \partial / \partial x\right\rangle a-\langle a, \partial / \partial x\rangle \nabla h_{l}=0 \\
\left.\left\langle\partial / \partial x, \nabla h_{l}\right\rangle l+\left\langle l,(\partial / \partial x) \nabla h_{l}\right)\right\rangle-\langle\partial / \partial x, a\rangle \nabla h_{a}-\left\langle\nabla h_{a},(\partial / \partial x) a\right\rangle=0 \tag{1.5}
\end{gather*}
$$

where

$$
\begin{gathered}
\nabla h_{\tilde{l}}:=\left\langle\nabla h_{l}, \partial / \partial x\right\rangle, \quad \tilde{l}:=\langle l, d x\rangle \\
\nabla h_{\tilde{a}}:=\left\langle\nabla h_{a}, d x\right\rangle, \quad \tilde{a}:=\langle a, \partial / \partial x\rangle .
\end{gathered}
$$

The system of linear equations (1.5) for a given element $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}$, which is singular as $|\lambda| \rightarrow \infty$, can be solved by using the asymptotic expansions

$$
\begin{equation*}
\nabla h_{l} \sim \sum_{j \in \mathbb{Z}_{+}} \nabla h_{l}^{(j)} \lambda^{-j}, \quad \nabla h_{a} \sim \sum_{j \in \mathbb{Z}_{+}} \nabla h_{a}^{(j)} \lambda^{-j} \tag{1.6}
\end{equation*}
$$

which enable us to get the infinite hierarchy of gradients

$$
\nabla h^{(p)}(\tilde{l} ; \tilde{a})=\lambda^{p} \nabla h(\tilde{l} ; \tilde{a}) \in \tilde{\mathcal{G}}, \quad p \in \mathbb{Z}_{+}
$$

for the corresponding Casimir invariants $h^{(p)} \in I\left(\tilde{\mathcal{G}}^{*}\right), p \in \mathbb{Z}_{+}$. If the given element $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}$ is singular as $|\lambda| \rightarrow 0$, then the system of linear equations (1.5) can be solved by using the asymptotic expansions

$$
\begin{equation*}
\nabla h_{l} \sim \sum_{j \in \mathbb{Z}_{+}} \nabla h_{l}^{(j)} \lambda^{j}, \quad \nabla h_{a} \sim \sum_{j \in \mathbb{Z}_{+}} \nabla h_{a}^{(j)} \lambda^{j} \tag{1.7}
\end{equation*}
$$

which enable us to construct an infinite hierarchy of gradients

$$
\nabla h^{(p)}(\tilde{l} ; \tilde{a})=\lambda^{-p} \nabla h(\tilde{a}, \tilde{l}) \in \tilde{\mathcal{G}}, \quad p \in \mathbb{Z}_{+}
$$

for the corresponding Casimir invariants $h^{(p)} \in I\left(\tilde{\mathcal{G}}^{*}\right), p \in \mathbb{Z}_{+}$.
Further, we assume that the gradients

$$
\nabla h^{(y)}(\tilde{a} ; \tilde{l}):=\lambda^{p_{y}} \nabla h^{(1)}(\tilde{a}, \tilde{l}) \quad \text { and } \quad \nabla h^{(t)}(\tilde{a} ; \tilde{l}):=\lambda^{p_{y}} \nabla h^{(2)}(\tilde{a} ; \tilde{l}) \in \tilde{\mathcal{G}}
$$

are found for two Casimir invariants $h^{(1)}, h^{(2)} \in I\left(\tilde{\mathcal{G}}^{*}\right)$ (not necessarily different) with some integer $p_{y}, p_{t} \in \mathbb{Z}$ satisfying Eq. (1.5). By using the classical AKS theory, we construct two commuting flows for the evolutionary parameters $y, t \in \mathbb{R}$ in the regular adjoint space $\tilde{\mathcal{G}}^{*} \simeq \tilde{\mathcal{G}}:$

$$
\begin{equation*}
\frac{\partial}{\partial y} \tilde{a}=-\left[\nabla h_{\tilde{l},+}^{(y)}, \tilde{a}\right], \quad \frac{\partial}{\partial t} \tilde{a}=-\left[\nabla h_{\tilde{l},+}^{(t)}, \tilde{a}\right] \tag{1.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\partial}{\partial y} \tilde{l}=-a d_{\nabla h_{\tilde{l},+}^{(y)}}^{*} \tilde{l}+a d_{\tilde{a}}^{*}\left(\nabla h_{\tilde{a},+}^{(y)}\right), \quad \frac{\partial}{\partial t} \tilde{l}=-a d_{\nabla h_{\tilde{l},+}^{(t)}}^{*} \tilde{l}+a d_{\tilde{a}}^{*}\left(\nabla h_{\tilde{a},+}^{(t)}\right) \tag{1.9}
\end{equation*}
$$

where

$$
\left(\nabla h_{\tilde{l},+}^{(y)} \ltimes \nabla h_{\tilde{a},+}^{(y)}\right):=P_{+} \nabla h^{(y)}(\tilde{a} ; \tilde{l}) \in \tilde{\mathcal{G}}_{+} \quad \text { and } \quad\left(\nabla h_{\tilde{l},+}^{(t)} \ltimes \nabla h_{\tilde{a},+}^{(t)}\right):=P_{+} \nabla h^{(t)}(\tilde{a} ; \tilde{l}) \in \tilde{\mathcal{G}}_{+}
$$

are the projections of the corresponding asymptotic expansions (1.6) and (1.7). For the chosen element $\tilde{a} \ltimes \tilde{l} \in$ $\tilde{\mathcal{G}}^{*} \simeq \tilde{\mathcal{G}}$, flows (1.8) and (1.9) are caused by the Hamiltonian flows

$$
\begin{equation*}
\frac{\partial}{\partial y}(\tilde{a} \ltimes \tilde{l})=\left\{\tilde{a} \ltimes \tilde{l}, h^{(y)}\right\}_{\mathcal{R}}, \quad \frac{\partial}{\partial t}(\tilde{a} \ltimes \tilde{l})=\left\{\tilde{a} \ltimes \tilde{l}, h^{(t)}\right\}_{\mathcal{R}} \tag{1.10}
\end{equation*}
$$

generated by the $\mathcal{R}$-deformed Lie-Poisson bracket [10-12, 15]:

$$
\begin{equation*}
\{h, f\}_{\mathcal{R}}:=\left(\tilde{a} \ltimes \tilde{l},[\nabla h(\tilde{l} ; \tilde{a}), \nabla f(\tilde{l}, \tilde{a})]_{\mathcal{R}}\right) \tag{1.11}
\end{equation*}
$$

in the regular adjoint space $\tilde{\mathcal{G}}^{*} \simeq \tilde{\mathcal{G}}$. Here, $h, f \in D\left(\tilde{\mathcal{G}}^{*}\right)$ are Fréchet-smooth functionals. The condition of commutativity of these flows is equivalent to the following system of two equations:

$$
\begin{equation*}
\left[\nabla h_{\tilde{l},+}^{(y)}, \nabla h_{\tilde{l},+}^{(t)}\right]-\frac{\partial}{\partial t} \nabla h_{\tilde{l},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\tilde{l},+}^{(t)}=0 \tag{1.12}
\end{equation*}
$$

and

$$
\begin{gathered}
a d_{\tilde{a}}^{*} \tilde{P}=0, \\
\tilde{P}=a d_{\nabla h_{\tilde{i},+}^{(y)}}^{*}\left(\nabla h_{\tilde{a},+}^{(t)}\right)-a d_{\nabla h_{\tilde{l},+}^{(t)}}^{*}\left(\nabla h_{\tilde{a},+}^{(y)}\right)-\frac{\partial}{\partial t} \nabla h_{\tilde{a},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\tilde{a},+}^{(t)}
\end{gathered}
$$

for any element $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}$.
Thus, the following statement is true:
Proposition 1.1. Hamiltonian flows (1.10) in a regular adjoint space $\tilde{\mathcal{G}}^{*} \simeq \tilde{\mathcal{G}}$ generate the systems of commuting evolutionary equations (1.8) and (1.9). The commutativity condition for the evolutionary equations (1.8) is equivalent to the Lax-Sato compatibility condition (1.12) for a certain system of nonlinear partial differential equations of the heavenly type.

We generalize the described scheme of construction of Hamiltonian flows in the regular adjoint space $\tilde{\mathcal{G}}^{*}$ as follows:

We parametrize the Lie algebra $\tilde{\mathcal{G}}$ by using the point product $\tilde{\mathcal{G}}^{\mathbb{S}^{1}}:=\prod_{z \in \mathbb{S}^{1}} \tilde{\mathcal{G}}$ and consider its central extension by the Maurer-Cartan 2-cocycle $\tilde{\omega}_{2}: \tilde{\mathcal{G}} \times \tilde{\mathcal{G}} \rightarrow \mathbb{C}$ :

$$
\tilde{\omega}_{2}\left(\tilde{a}_{1} \ltimes \tilde{l}_{1}, \tilde{a}_{2} \ltimes \tilde{l}_{2}\right):=\int_{\mathbb{S}^{1}}\left[\left(l_{1}, \partial \tilde{a}_{2} / \partial z\right)-\left(l_{2}, \partial \tilde{a}_{1} / \partial z\right)\right],
$$

where $\tilde{a}_{1} \ltimes \tilde{l}_{1}, \tilde{a}_{2} \ltimes \tilde{l}_{2} \in \tilde{\mathcal{G}}$. On the central extension $\tilde{\mathfrak{G}}:=\tilde{\mathcal{G}} \oplus \mathbb{C}$, the commutator is given by the rule

$$
\left[\left(\tilde{a}_{1} \ltimes \tilde{l}_{1} ; \alpha_{1}\right),\left(\tilde{a}_{2} \ltimes \tilde{l}_{2} ; \alpha_{1}\right)\right]:=\left(\left[\tilde{a}_{1}, a_{2}\right] \ltimes\left(a d_{\tilde{a}_{1}}^{*} \tilde{l}_{2}-a d_{\tilde{a}_{2}}^{*} \tilde{l}_{1}\right) ; \tilde{\omega}_{2}\left(\tilde{a}_{1} \ltimes \tilde{l}_{1}, \tilde{a}_{2} \ltimes \tilde{l}_{2}\right)\right)
$$

for any pair of elements $\left(\tilde{a}_{1} \ltimes \tilde{l}_{1} ; \alpha_{1}\right),\left(\tilde{a}_{2} \ltimes \tilde{l}_{2} ; \alpha_{1}\right) \in \tilde{\mathfrak{G}}$.

For any smooth functionals $h, f \in D\left(\mathfrak{G}^{*}\right)$, the $\mathcal{R}$-deformed Lie-Poisson bracket (1.11) in the regular adjoint space $\tilde{\mathfrak{G}}^{*}$ has the form

$$
\begin{align*}
\{h, f\}_{\mathcal{R}}:= & \left(\tilde{a} \ltimes \tilde{l},[\nabla h(\tilde{l} ; \tilde{a}), \nabla f(\tilde{l} ; \tilde{a})]_{\mathcal{R}}\right) \\
& +\tilde{\omega}_{2}(\mathcal{R} \nabla h(\tilde{l} ; \tilde{a}), \nabla f(\tilde{l}, \tilde{a}))+\tilde{\omega}_{2}(\nabla h(\tilde{l} ; \tilde{a}), \mathcal{R} \nabla f(\tilde{l} ; \tilde{a})) . \tag{1.13}
\end{align*}
$$

The corresponding Casimir invariants $h^{(p)} \in I\left(\tilde{\mathfrak{G}}^{*}\right), p \in \mathbb{Z}_{+}$, are determined by the standard Lie-Poisson bracket as follows:

$$
\begin{gather*}
\left\{h^{(p)}, f\right\}=0, \\
\left(\tilde{a} \ltimes \tilde{l},\left[\nabla h^{(p)}(\tilde{l}, \tilde{a}), \nabla f(\tilde{a}, \tilde{l})\right]\right)+\tilde{\omega}_{2}\left(\nabla h^{(p)}(\tilde{a}, \tilde{l}), \nabla f(\tilde{a}, \tilde{l})\right), \tag{1.14}
\end{gather*}
$$

for all smooth functionals $f \in D\left(\tilde{\mathfrak{G}}^{*}\right)$. By using equality (1.14), we conclude that the gradients $\nabla h^{(p)} \in \tilde{\mathfrak{G}}$ of the Casimir invariants $h^{(p)} \in I\left(\tilde{\mathfrak{G}}^{*}\right), p \in \mathbb{Z}_{+}$, satisfy the equations

$$
\left[\nabla h_{\tilde{l}} \tilde{a}\right]-\frac{\partial}{\partial z} \nabla h_{\tilde{l}}=0, \quad a d_{\nabla h_{\tilde{l}}}^{*} \tilde{l}-a d_{\tilde{a}}^{*} \nabla h_{\tilde{a}}-\frac{\partial}{\partial z} \nabla h_{\tilde{a}}=0
$$

for any chosen element $\tilde{a} \ltimes \tilde{l} \in \overline{\mathcal{G}}^{*}$. By using some of the obtained Casimir invariants $h^{(y)}, h^{(t)} \in I\left(\tilde{\mathfrak{G}}^{*}\right)$ and relation (1.13), we construct the following commuting Hamiltonian flows in the regular adjoint space $\tilde{\mathfrak{G}}^{*}$ :

$$
\begin{equation*}
\frac{\partial}{\partial y}(\tilde{a} \ltimes \tilde{l})=\left\{\tilde{a} \ltimes \tilde{l}, h^{(y)}\right\}_{\mathcal{R}}, \quad \frac{\partial}{\partial t}(\tilde{a} \ltimes \tilde{l})=\left\{\tilde{a} \ltimes \tilde{l}, h^{(t)}\right\}_{\mathcal{R}}, \tag{1.15}
\end{equation*}
$$

which are equivalent to the system of evolutionary equations

$$
\begin{equation*}
\frac{\partial}{\partial y} \tilde{a}=-\left[\nabla h_{\tilde{l},+}^{(y)}, \tilde{a}\right]+\frac{\partial}{\partial z} \nabla h_{\tilde{l},+}^{(y)}, \quad \frac{\partial}{\partial t} \tilde{a}=-\left[\nabla h_{\tilde{l},+}^{(t)}, \tilde{a}\right]+\frac{\partial}{\partial z} \nabla h_{\tilde{l},+}^{(t)}, \tag{1.16}
\end{equation*}
$$

and

$$
\begin{align*}
& \frac{\partial}{\partial y} \tilde{l}=-a d_{\nabla h_{\tilde{l},+}^{(y)}}^{*} \tilde{l}+a d_{\tilde{a}}^{*}\left(\nabla h_{\tilde{a},+}^{(y)}\right)+\frac{\partial}{\partial z} \nabla h_{\tilde{a},+}^{(y)}, \\
& \frac{\partial}{\partial t} \tilde{l}=-a d_{\nabla h_{\tilde{l},+}^{(t)}}^{*(t)} \tilde{l}+a d_{\tilde{a}}^{*}\left(\nabla h_{\tilde{a},+}^{(t)}\right)+\frac{\partial}{\partial z} \nabla h_{\tilde{a},+}^{(t)} . \tag{1.17}
\end{align*}
$$

The condition of commutativity of these flows is given by the following system of two equations:

$$
\left[\nabla h_{\tilde{l},+}^{(y)}, \nabla h_{\tilde{l},+}^{(t)}\right]-\frac{\partial}{\partial t} \nabla h_{\tilde{l},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\tilde{l},+}^{(t)}=0
$$

and

$$
\begin{gathered}
\frac{\partial \tilde{P}}{\partial z}+a d_{\tilde{a}}^{*} \tilde{P}=0 \\
\tilde{P}=a d_{\nabla h_{\tilde{l},+}^{(y)}}^{*}\left(\nabla h_{\tilde{a},+}^{(t)}\right)-a d_{\nabla h_{\tilde{l},+}^{(t)}}^{*}\left(\nabla h_{\tilde{a},+}^{(y)}\right)-\frac{\partial}{\partial t} \nabla h_{\tilde{a},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\tilde{a},+}^{(t)}
\end{gathered}
$$

for any $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}$. The first of these equations can be regarded as the Lax-type compatibility condition for the evolutionary equations (1.16). As a consequence, we can formulate the following statement:

Proposition 1.2. The Hamiltonian flows (1.15) in the regular adjoint space $\tilde{\mathfrak{G}}^{*} \simeq \tilde{\mathfrak{G}}$ generate systems of commuting evolutionary equations (1.16) and (1.17). The commutativity condition for the evolutionary equations (1.16) is, in fact, the compatibility condition for the set of linear vector-field equations

$$
\begin{equation*}
\partial \psi / \partial y+\nabla h_{\tilde{l},+}^{(y)} \psi=0, \quad \partial \psi / \partial z+\tilde{a} \psi=0, \quad \partial \psi / \partial t+\nabla h_{\tilde{l},+}^{(t)} \psi=0 \tag{1.18}
\end{equation*}
$$

for all $(y, t ; \lambda, z, x) \in \mathbb{R}^{2} \times\left(\mathbb{C} \times \mathbb{S}^{1} \times \mathbb{T}^{n}\right)$ and the function $\psi \in C^{2}\left(\mathbb{R}^{2} \times\left(\mathbb{C} \times \mathbb{S}^{1} \times \mathbb{T}^{n}\right) ; \mathbb{C}\right) ;$ moreover, on the orbits of coadjoint action of the Lie algebra $\tilde{\mathfrak{G}}$ it is reduced to a system of nonlinear partial differential equations of heavenly type.

According to the Lie-algebraic approach described above, every Casimir invariant $h^{(j)} \in I\left(\mathfrak{G}^{*}\right), j \in \mathbb{Z}_{+}$, for the element $\tilde{a} \ltimes \tilde{l} \in \mathfrak{G}^{*}$ generates, in the regular adjoint space $\mathfrak{G}^{*}$, the following hierarchy of commuting Hamiltonian flows:

$$
\begin{gather*}
\frac{d}{d t_{j}} \tilde{a}=-\left[\nabla h_{\tilde{l},+}^{(j)}, \tilde{a}\right]+\frac{\partial}{\partial z} \nabla h_{\tilde{l},+}^{(j)},  \tag{1.19}\\
\frac{d}{d t_{j}} \tilde{l}=-a d_{\nabla h_{\tilde{l},+}^{(j)}}^{*} \tilde{l}+a d_{\tilde{a}}^{*}\left(\nabla h_{\tilde{a}++}^{(j)}\right)+\frac{\partial}{\partial z} \nabla h_{\tilde{a},++}^{(j)} .
\end{gather*}
$$

The hierarchy of flows (1.19) can be represented with the help of a generating vector field

$$
\frac{\partial}{\partial t}:=\sum_{j \in \mathbb{Z}_{+}} \mu^{-j} \frac{\partial}{\partial t_{j}}
$$

as follows:

$$
\begin{equation*}
\frac{d}{d t} \tilde{a}(\lambda)=-\frac{\mu}{\mu-\lambda}\left[\nabla h_{\tilde{l}}(\mu), \tilde{a}(\lambda) \left\lvert\,+\frac{\mu}{\mu-\lambda} \frac{\partial}{\partial z} \nabla h_{\tilde{l}}(\mu)\right.\right. \tag{1.20}
\end{equation*}
$$

and

$$
\begin{align*}
\frac{d}{d t}(\tilde{l}(\lambda) \mid \tilde{Y}(\lambda))= & \left.\frac{\mu}{\mu-\lambda}\left(\tilde{l}(\lambda) \mid\left[\nabla h_{\tilde{l}}(\mu)\right), \tilde{Y}(\lambda)\right]\right) \\
& +\frac{\mu}{\mu-\lambda}\left(\nabla h_{\tilde{a}}(\lambda) \mid[\tilde{a}(\mu), \tilde{Y}(\lambda)]\right)-\frac{\mu}{\mu-\lambda}\left(\left.\frac{\partial}{\partial z} \nabla h_{\tilde{l}}(\mu) \right\rvert\, \tilde{Y}(\lambda)\right) \\
= & \left(i_{\mu-\lambda}^{\mu-\lambda} \nabla h_{\tilde{f}}(\mu) d \tilde{l}(\lambda) \mid \tilde{Y}(\lambda)\right)+\left(\left.d i_{\frac{\mu}{\mu-\lambda} \nabla h_{\tilde{\imath}}(\mu)}^{\tilde{l}}(\lambda) \right\rvert\, \tilde{Y}(\lambda)\right) \\
& -\frac{\mu}{\mu-\lambda}\left(\left\langle d / d x, \nabla h_{\tilde{l}}(\mu)\right) \tilde{l}(\lambda) \mid \tilde{Y}(\lambda)\right)-\frac{\mu}{\mu-\lambda}\left(\left.\frac{\partial}{\partial z} \nabla h_{\tilde{a}}(\mu) \right\rvert\, \tilde{Y}(\lambda)\right) \\
& -\left(\left.i_{\frac{\mu}{\mu-\lambda} \tilde{a}(\mu)} d \nabla h_{\tilde{a}}(\lambda) \right\rvert\, \tilde{Y}(\lambda)\right)+\left(\left.d i_{\frac{\mu}{\mu-\lambda} \tilde{a}(\mu)} \nabla h_{\tilde{a}}(\lambda) \right\rvert\, \tilde{Y}(\lambda)\right), \tag{1.21}
\end{align*}
$$

where $\tilde{Y}(\lambda) \in \mathfrak{G}$ and $\mu \in \mathbb{C}$ is such that $|\lambda / \mu|<1$ as $|\lambda|,|\mu| \rightarrow \infty$. Here,

$$
\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right) \simeq \tilde{\Gamma}\left(\mathbb{T}^{n}\right) \quad \text { and } \quad \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*} \simeq \tilde{\Lambda}^{1}\left(\mathbb{T}^{n}\right)
$$

For the generating element $\tilde{a}(\lambda) \ltimes \tilde{l}(\lambda) \in \tilde{\Gamma}\left(\mathbb{T}^{n}\right) \ltimes \tilde{\Lambda}^{1}\left(\mathbb{T}^{n}\right)$, relations (1.20) and (1.21) can be rewritten in the form

$$
\begin{equation*}
\frac{d}{d t} \tilde{a}(\lambda)=\frac{\partial}{\partial z} \tilde{K}(\mu, \lambda) \tag{1.22}
\end{equation*}
$$

and

$$
\begin{align*}
\frac{d}{d t} \tilde{l}(\lambda) & =\frac{\mu}{\mu-\lambda}\left\langle d / d x, \nabla h_{l}(\mu)\right\rangle \tilde{l}(\lambda)+L_{\tilde{A}(\mu, \lambda)} \nabla h_{\tilde{a}}(\mu)+\frac{\partial}{\partial z} \nabla h_{\tilde{a}}(\mu) \\
& :=\operatorname{div} \tilde{K}(\mu, \lambda) \tilde{l}(\lambda)+\frac{d}{d z} \nabla h_{\tilde{a}}(\mu), \tag{1.23}
\end{align*}
$$

where

$$
d / d t:=\partial / \partial t+L_{\tilde{K}(\mu, \lambda)}, \quad d / d z:=\frac{\mu}{\mu-\lambda} \partial / \partial z+L_{\tilde{A}(\mu, \lambda)},
$$

and also

$$
L_{\tilde{K}(\mu, \lambda)}=i_{\tilde{K}(\mu, \lambda)} d+d i_{\tilde{K}(\mu, \lambda)} \quad \text { and } \quad L_{\tilde{A}(\mu, \lambda)}=i_{\tilde{A}(\mu, \lambda))} d+d i_{\tilde{A}(\mu, \lambda)}
$$

are the Cartan expressions [11, 13, 14] for the derivatives along the vector fields

$$
\tilde{K}(\mu, \lambda):=\frac{\mu}{\mu-\lambda} \nabla h_{\tilde{l}}(\mu)=\frac{\mu}{\mu-\lambda}\left\langle\nabla h_{l}(\mu), \frac{d}{d x}\right\rangle
$$

and

$$
\tilde{A}(\mu, \lambda):=\frac{\mu}{\mu-\lambda} \tilde{a}(\mu)=\frac{\mu}{\mu-\lambda}\left\langle a(\mu), \frac{d}{d x}\right\rangle,
$$

respectively, where $|\lambda / \mu|<1$ as $|\mu|,|\lambda| \rightarrow \infty$, which are equivalent to the hierarchies of the Lax-Sato equations [ $5,6,8,9,16-18]$ for the generating flows (1.23) and (1.22). These flows can be interpreted by using the classical Lagrange-d'Alembert principle [13] in exactly the same way as in [4].

The proposed Lie-algebraic scheme can be used to construct a broad class of integrable multidimensional systems of heavenly type on function spaces.
1.1. Example: New Modified Mikhalev-Pavlov Equation in the Four-Dimensional Space. If the generating element $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}^{*}$ of Hamiltonian flows in the regular adjoint space $\tilde{\mathfrak{G}}^{*}$ is chosen in the form

$$
\begin{equation*}
\tilde{a} \ltimes \tilde{l}=\left(\left(u_{x}+v_{x} \lambda-\lambda^{2}\right) \partial / \partial x \ltimes\left(w_{x}+\zeta_{x} \lambda\right) d x\right), \tag{1.24}
\end{equation*}
$$

where $u, v, w, \zeta \in C^{2}\left(\mathbb{R}^{2} \times \mathbb{S}^{1} \times \mathbb{T}^{1} ; \mathbb{R}\right)$, then the asymptotic expansions of coordinates of the gradient of the corresponding unique functionally independent Casimir invariant $h \in I\left(\tilde{\mathfrak{G}}^{*}\right)$ as $|\lambda| \rightarrow \infty$ can be represented in the form

$$
\begin{aligned}
\nabla h_{\tilde{l}} \simeq 1 & -v_{x} \lambda^{-1}-u_{x} \lambda^{-2}-v_{z} \lambda^{-3}-\left(u_{z}+v_{x} v_{z}-2\left(\partial_{x}^{-1} v_{x x} v_{z}\right)\right) \lambda^{-4} \\
& +v_{y} \lambda^{-5}-\left(-u_{y}-v_{x} v_{y}+2\left(\partial_{x}^{-1} v_{x x} v_{y}\right)\right) \lambda^{-6}+\ldots,
\end{aligned}
$$

$$
\begin{aligned}
& \nabla h_{\tilde{a}} \simeq-\zeta_{x} \lambda^{-1}-w_{x} \lambda^{-2}-\zeta_{z} \lambda^{-3}-\left(w_{z}-\zeta_{x} v_{z}+2 v_{x} \zeta_{z}+\left(\partial_{x}^{-1} v_{x} \zeta_{x}\right)_{z}\right) \lambda^{-4} \\
& +\zeta_{y} \lambda^{-5}-\left(-w_{y}+\zeta_{x} v_{y}-2 v_{x} \zeta_{y}+\left(\partial_{x}^{-1} v_{x} \zeta_{x}\right)_{y}\right) \lambda^{-6}+\ldots .
\end{aligned}
$$

In the case where

$$
\begin{gathered}
\nabla h_{\tilde{l},+}^{(y)}:=\lambda^{4}-v_{x} \lambda^{3}-u_{x} \lambda^{2}-v_{z} \lambda-\left(u_{z}+v_{x} v_{z}-2\left(\partial_{x}^{-1} v_{x x} v_{z}\right)\right), \\
\nabla h_{\tilde{a},+}^{(y)}:=-\zeta_{x} \lambda^{3}-w_{x} \lambda^{2}-\zeta_{z} \lambda-\left(w_{z}-\zeta_{x} v_{z}+2 v_{x} \zeta_{z}-\left(\partial_{x}^{-1} v_{x} \zeta_{x}\right)_{z}\right)
\end{gathered}
$$

and

$$
\begin{aligned}
\nabla h_{\tilde{l},+}^{(t)}:= & \lambda^{6}-v_{x} \lambda^{5}-u_{x} \lambda^{4}-v_{z} \lambda^{3}-\left(u_{z}+v_{x} v_{z}-2\left(\partial_{x}^{-1} v_{x x} v_{z}\right)\right) \lambda^{2} \\
& +v_{y} \lambda-\left(-u_{y}-v_{x} v_{y}+2\left(\partial_{x}^{-1} v_{x x} v_{y}\right)\right), \\
\nabla h_{\tilde{a},+}^{(t)}:= & -\zeta_{x} \lambda^{5}-w_{x} \lambda^{4}-\zeta_{z} \lambda^{3}-\left(w_{z}-\zeta_{x} v_{z}+2 v_{x} \zeta_{z}-\left(\partial_{x}^{-1} v_{x} \zeta_{x}\right)_{z}\right) \lambda^{2} \\
& +\zeta_{y} \lambda-\left(-w_{y}+\zeta_{x} v_{y}-2 v_{x} \zeta_{y}+\left(\partial_{x}^{-1} v_{x} \zeta_{x}\right)_{y}\right)
\end{aligned}
$$

the commutativity condition for the Hamiltonian flows (1.15) is reduced to the following system of equations:

$$
\begin{align*}
& u_{z t}+u_{y y}=-u_{y} u_{x z}+u_{z} u_{x y}-v_{y} v_{x y}+v_{z} v_{x t}-u_{z} v_{y} v_{x x}+u_{y} v_{z} v_{x x} \\
& -v_{x}^{2} v_{z} v_{x y}+v_{x}^{2} v_{y} v_{x z}-2 e u_{x y}-2 s u_{x z}+2 e_{t}-2 s_{y}+2 e v_{y} v_{x x}+2 s v_{z} v_{x x}, \\
& v_{z t}+v_{y y}=-u_{y} v_{x z}+u_{z} v_{x y}-v_{y} u_{x z}+v_{z} u_{x y} \\
& -2 e v_{x y}-2 s v_{x z}-2 v_{x} v_{y} v_{x z}+2 v_{x} v_{z} v_{x y}, \\
& -u_{x y}-u_{z z}=u_{x} u_{x z}-u_{z} u_{x x}-u_{x x} v_{x} v_{z} \\
& +u_{x} v_{x z} v_{x}-u_{x} v_{x x} v_{z}+\left(v_{x} v_{z}\right)_{z}+2 u_{x x} e-2 e_{z},  \tag{1.25}\\
& -v_{x y}-v_{z z}=u_{x z} v_{x}-u_{z} v_{x x}-u_{x x} v_{z}+u_{x} v_{x z}-2 v_{x x} v_{x} v_{z}+v_{x}^{2} v_{x z}+2 v_{x x} e, \\
& -u_{x t}+u_{y z}=-u_{x} u_{x y}+u_{y} u_{x x}+u_{x x} v_{x} v_{y} \\
& -u_{x} v_{x y} v_{x}+u_{x} v_{x x} v_{y}-\left(v_{x} v_{y}\right)_{z}+2 u_{x x} s-2 s_{z}, \\
& -v_{x t}+v_{y z}=-u_{x y} v_{x}+u_{y} v_{x x}+u_{x x} v_{y} \\
& -u_{x} v_{x y}+2 v_{x x} v_{x} v_{y}-v_{x}^{2} v_{x y}+2 v_{x x} s, \\
& e_{x}=v_{x x} v_{z}, \quad s_{x}=-v_{x x} v_{y} .
\end{align*}
$$

As a result of the reduction $v=0$, we get a collection of independent differential relations obtained in [18-20], namely, two four-dimensional (in the space variables) equations

$$
\begin{equation*}
u_{z t}+u_{y y}=-u_{y} u_{x z}+u_{z} u_{x y} \tag{1.26}
\end{equation*}
$$

and

$$
\begin{equation*}
-u_{x t}+u_{y z}=-u_{x} u_{x y}+u_{y} u_{x x} \tag{1.27}
\end{equation*}
$$

and one three-dimensional (in the space variables) equation

$$
\begin{equation*}
-u_{x y}-u_{z z}=u_{x} u_{x z}-u_{z} u_{x x} . \tag{1.28}
\end{equation*}
$$

In particular, in the case of reduction of independent space variables $x \rightarrow y \in \mathbb{R}, t \rightarrow z \in \mathbb{R}$, Eq. (1.27) becomes trivial, while Eqs. (1.26) and (1.28) are reduced to the Mikhalev-Pavlov-type equation

$$
\begin{equation*}
u_{z z}+u_{y y}=-u_{y} u_{y z}+u_{z} u_{y y} . \tag{1.29}
\end{equation*}
$$

Proposition 1.3. The modified system of Mikhalev-Pavlov equations (1.25) admits a vector-field Lax-Sato representation with a "spectral" parameter $\lambda \in \mathbb{C}$ and the generating element $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}^{*}$ of the form (1.24).

The generating element (1.24) can be rewritten in the form

$$
\begin{equation*}
\tilde{a} \ltimes \tilde{l}:=\frac{\partial \tilde{\eta}}{\partial x} \frac{\partial}{\partial x} \ltimes d \tilde{\rho}, \quad \tilde{\eta}=u+v \lambda-\lambda^{2} x, \quad \tilde{\rho}=w+\zeta \lambda, \tag{1.30}
\end{equation*}
$$

which is explicitly connected with the space of moduli of gauge connectedness for the coadjoint action of the corresponding Casimir invariants. This enables one to construct multidimensional generalizations of system (1.30) by choosing the generating element in the form

$$
\begin{equation*}
\tilde{a} \ltimes \tilde{l}:=\langle\nabla \tilde{\eta}, \nabla\rangle \ltimes d \tilde{\rho}, \tag{1.31}
\end{equation*}
$$

where $\tilde{\eta}, \tilde{\rho} \in \Omega^{0}\left(\mathbb{T}^{n}\right) \otimes \mathbb{C}, n \in \mathbb{N}$. Case (1.31) will be analyzed elsewhere.
1.2. Example: New Modified Martínez-Alonso-Shabat Equation in the Five-Dimensional Space. For a generating element $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}^{*}$ of the form

$$
\begin{align*}
& \tilde{a} \ltimes \tilde{l}=\left(\left(\left(u_{x_{1}}+c u_{x_{2}}\right)+c \lambda\right) \partial / \partial x_{1}+\left(\left(v_{x_{1}}+c v_{x_{2}}\right)+c \lambda\right) \partial / \partial x_{2}\right) \\
& \ltimes\left(\left(w_{x_{1}}+c w_{x_{2}}\right) d x_{1}+\left(\zeta_{x_{1}}+c \zeta_{x_{2}}\right) d x_{2}\right), \tag{1.32}
\end{align*}
$$

where $u, v, w, \zeta \in C^{2}\left(\mathbb{R}^{2} \times \mathbb{S}^{1} \times \mathbb{T}^{2} ; \mathbb{R}\right), c \in \mathbb{R} \backslash\{0\}$, we obtain the following asymptotic expansions of coordinates for the gradients of the corresponding two independent Casimir invariants $h^{(1)}, h^{(2)} \in I\left(\tilde{\mathfrak{G}}^{*}\right)$ as $|\lambda| \rightarrow \infty$ :

$$
\nabla h_{\tilde{l}}^{(1)} \simeq\binom{1+\left(u_{x_{1}}+c u_{x_{2}}\right) \lambda^{-1}-u_{z} \lambda^{-2}+\ldots}{c+\left(v_{x_{1}}+c v_{x_{2}}\right) \lambda^{-1}-v_{z} \lambda^{-2}+\ldots},
$$

$$
\nabla h_{\tilde{a}}^{(1)} \simeq\binom{\left(w_{x_{1}}+c w_{x_{2}}\right) \lambda^{-1}-w_{z} \lambda^{-2}+\ldots}{\left(\zeta_{x_{1}}+c \zeta_{x_{2}}\right) \lambda^{-1}-\zeta_{z} \lambda^{-2}+\ldots}
$$

and

$$
\begin{gathered}
\nabla h_{\tilde{l}}^{(2)} \simeq\binom{1+\left(u_{x_{1}}-c u_{x_{2}}\right) \lambda^{-1}+\kappa \lambda^{-2}+\ldots}{-c+\left(v_{x_{1}}-c v_{x_{2}}\right) \lambda^{-1}+\omega \lambda^{-2}+\ldots}, \\
\nabla h_{\tilde{a}}^{(2)} \simeq\binom{\left(w_{x_{1}}-c w_{x_{2}}\right) \lambda^{-1}+\varrho \lambda^{-2}+\ldots}{\left(\zeta_{x_{1}}-c \zeta_{x_{2}}\right) \lambda^{-1}+\chi \lambda^{-2}+\ldots}
\end{gathered}
$$

where

$$
\begin{align*}
\kappa_{x_{1}}+c \kappa_{x_{2}}=- & \left(u_{z x_{1}}-c u_{z x_{2}}\right) \\
& +2 c\left(u_{x_{1}} u_{x_{1} x_{2}}-u_{x_{2}} u_{x_{1} x_{1}}+v_{x_{1}} u_{x_{2} x_{2}}-v_{x_{2}} u_{x_{1} x_{2}}\right)  \tag{1.33}\\
\omega_{x_{1}}+c \omega_{x_{2}}=- & \left(v_{z x_{1}}-c v_{z x_{2}}\right) \\
& +2 c\left(u_{x_{1}} v_{x_{1} x_{2}}-u_{x_{2}} v_{x_{1} x_{1}}+v_{x_{1}} v_{x_{2} x_{2}}-v_{x_{2}} v_{x_{1} x_{2}}\right)
\end{align*}
$$

and

$$
\begin{aligned}
\varrho_{x_{1}}+c \varrho_{x_{2}}=- & \left(w_{z x_{1}}-c w_{z x_{2}}\right) \\
& +2 c\left(u_{x_{1}} w_{x_{1} x_{2}}-u_{x_{2}} w_{x_{1} x_{1}}+2 w_{x_{2}} u_{x_{1} x_{1}}-2 w_{x_{1}} u_{x_{1} x_{2}}\right. \\
& \left.+v_{x_{1}} w_{x_{2} x_{2}}-v_{x_{2}} w_{x_{1} x_{2}}+w_{x_{2}} v_{x_{1} x_{2}}-w_{x_{2}} v_{x_{2} x_{2}}+\zeta_{x_{2}} v_{x_{1} x_{1}}-\zeta_{x_{1}} v_{x_{1} x_{2}}\right), \\
\chi_{x_{1}}+c \chi_{x_{2}}=- & \left(\zeta_{z x_{1}}-c \zeta_{z x_{2}}\right) \\
& +2 c\left(v_{x_{1}} \zeta_{x_{2} x_{2}}-v_{x_{2}} \zeta_{x_{1} x_{2}}+2 \zeta_{x_{2}} v_{x_{1} x_{2}}-2 \zeta_{x_{1}} v_{x_{2} x_{2}}\right. \\
& \left.+u_{x_{1}} \zeta_{x_{1} x_{2}}-u_{x_{2}} \zeta_{x_{1} x_{1}}+\zeta_{x_{2}} u_{x_{1} x_{1}}-\zeta_{x_{1}} u_{x_{1} x_{2}}+w_{x_{2}} u_{x_{1} x_{2}}-w_{x_{1}} u_{x_{2} x_{2}}\right) .
\end{aligned}
$$

If

$$
\nabla h_{\tilde{l},+}^{(y)}:=\binom{\lambda^{2}+\left(u_{x_{1}}+c u_{x_{2}}\right) \lambda-u_{z}}{c \lambda^{2}+\left(v_{x_{1}}+c v_{x_{2}}\right) \lambda-v_{z}}, \quad \nabla h_{\tilde{a},+}^{(y)}:=\binom{\left(w_{x_{1}}+c w_{x_{2}}\right) \lambda-w_{z}}{\left(\zeta_{x_{1}}+c \zeta_{x_{2}}\right) \lambda-\zeta_{z}}
$$

and

$$
\nabla h_{\tilde{l},+}^{(t)}:=\binom{\lambda^{2}+\left(u_{x_{1}}-c u_{x_{2}}\right) \lambda+\kappa}{-c \lambda^{2}+\left(v_{x_{1}}-c v_{x_{2}}\right) \lambda+\omega}, \quad \nabla h_{\tilde{a},+}^{(t)}:=\binom{\left(w_{x_{1}}-c w_{x_{2}}\right) \lambda+\varrho}{\left(\zeta_{x_{1}}-c \zeta_{x_{2}}\right) \lambda+\chi},
$$

then the commutativity condition for the Hamiltonian flows (1.15) is reduced to the following system of equations
of heavenly type:

$$
\begin{gather*}
u_{z t}+\kappa_{y}=-u_{z x_{1}} \kappa-u_{z x_{2}} \omega+u_{z} \kappa_{x_{1}}+v_{z} \kappa_{x_{2}}, \\
v_{z t}+ \\
\omega_{y}=-v_{z x_{1}} \kappa-v_{z x_{2}} \omega+u_{z} \omega_{x_{1}}+v_{z} \omega_{x_{2}}, \\
u_{y x_{1}}+c u_{y x_{2}}=-\left(u_{x_{1}}+c u_{x_{2}}\right) u_{z x_{1}}-\left(v_{x_{1}}+c v_{x_{2}}\right) u_{z x_{2}}  \tag{1.34}\\
\\
+\left(u_{x_{1} x_{1}}+c u_{x_{1} x_{2}}\right) u_{z}+\left(u_{x_{1} x_{2}}+c u_{x_{2} x_{2}}\right) v_{z}-u_{z z}, \\
v_{y x_{1}}+c v_{y x_{2}}=-\left(u_{x_{1}}+c u_{x_{2}}\right) v_{z x_{1}}-\left(v_{x_{1}}+c v_{x_{2}}\right) v_{z x_{2}} \\
\\
\quad+\left(v_{x_{1} x_{1}}+c v_{x_{1} x_{2}}\right) u_{z}+\left(v_{x_{1} x_{2}}+c v_{x_{2} x_{2}}\right) v_{z}-v_{z z}, \\
u_{t x_{1}}+c u_{t x_{2}}=\left(u_{x_{1}}+c u_{x_{2}}\right) \kappa_{x_{1}}+\left(v_{x_{1}}+c v_{x_{2}}\right) \kappa_{x_{2}} \\
\\
\quad-\left(u_{x_{1} x_{1}}+c u_{x_{1} x_{2}}\right) \kappa-\left(u_{x_{1} x_{2}}+c u_{x_{2} x_{2}}\right) \omega+\kappa_{z}, \\
v_{t x_{1}}+c v_{t x_{2}}=
\end{gather*}
$$

Thus, the following assertion is true:
Proposition 1.4. The constructed system of equations of heavenly type (1.34), (1.33) admits a vector-field Lax-Sato representation with "spectral" parameter $\lambda \in \mathbb{C}$, which is connected with the element $\tilde{a} \ltimes \tilde{l} \in \tilde{\mathcal{G}}^{*}$ in the form (1.32).

For $v=u, \omega=\kappa$, and $c=1$, system (1.34), (1.33) can be reduced to the following system:

$$
\begin{gather*}
u_{z t}+\kappa_{y}=-\left(u_{z x_{1}}+u_{z x_{2}}\right) \kappa+u_{z}\left(\kappa_{x_{1}}+\kappa_{x_{2}}\right)  \tag{1.35}\\
\kappa_{x_{1}}+\kappa_{x_{2}}=-\left(u_{z x_{1}}-u_{z x_{2}}\right)-2\left(\left(u_{x_{1}} u_{x_{2}}\right)_{x_{1}}-\left(u_{x_{1}} u_{x_{2}}\right)_{x_{2}}\right)
\end{gather*}
$$

The presence of additional constraints $u_{z}=u_{x_{1}}+u_{x_{2}}$ for Eqs. (1.35) leads to the following system:

$$
\begin{gathered}
\left(u_{\tilde{t} x_{1}}+u_{\tilde{t} x_{2}}\right)-\left(u_{\tilde{y} x_{1}}-u_{\tilde{y} x_{2}}\right)=u_{x_{1} x_{2}}\left(u_{x_{1}}-u_{x_{2}}\right)-u_{x_{1} x_{1}} u_{x_{2}}+u_{x_{2} x_{2}} u_{x_{1}}-u_{x_{1} x_{2}}\left(u_{x_{1}}^{2}-u_{x_{2}}^{2}\right) \\
-u_{x_{1} x_{1}} u_{x_{2}}\left(u_{x_{1}}+u_{x_{2}}\right)+u_{x_{2} x_{2}} u_{x_{1}}\left(u_{x_{1}}+u_{x_{2}}\right) \\
-2 \rho_{\tilde{y}}+\left(u_{x_{1} x_{1}}+2 u_{x_{1} x_{2}}+u_{x_{2} x_{2}}\right) \rho, \\
\rho_{x_{1}}+\rho_{x_{2}}=\left(u_{x_{1}} u_{x_{2}}\right)_{x_{1}}-\left(u_{x_{1}} u_{x_{2}}\right)_{x_{2}},
\end{gathered}
$$

where $\tilde{t}=2 t$ and $\tilde{y}=2 y$, which can be regarded as a modification of the system of Martínez-Alonso-Shabat-type equations of heavenly type [21].

## 2. Multidimensional Systems of "Heavenly" Type: Generalized Lie-Algebraic Structures

For subsequent generalizations of the Lie-algebraic scheme connected with the loop group $\widetilde{\operatorname{Diff}}\left(\mathbb{T}^{n}\right)$ on the torus $\mathbb{T}^{n}, n \in \mathbb{Z}_{+}$, we can use the approach proposed in [5].

Since the Lie algebra $\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)$ is formed by elements of a loop group analytically extended from the circle $\mathbb{S}^{1}:=\partial \mathbb{D}^{1}$, which is the boundary of the central unit disk $\mathbb{D}^{1} \subset \mathbb{C}$, with the help of a complex "spectral" variable $\lambda \in \mathbb{C}$, both to the interior $\mathbb{D}_{+}^{1} \subset \mathbb{C}$ and to the exterior $\mathbb{D}_{-}^{1} \subset \mathbb{C}$ of the disk $\mathbb{D}^{1} \subset \mathbb{C}$, it is analytically invariant under the diffeomorphism group of the circle Diff $\left(\mathbb{S}^{1}\right)$. This property enables one to consider the extended Lie algebra

$$
\operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right)=\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n} \times \mathbb{D}_{+}^{1}\right) \oplus \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n} \times \mathbb{D}_{-}^{1}\right)
$$

of holomorphic vector fields on the Cartesian product $\mathbb{T}_{\mathbb{C}}^{n}:=\mathbb{D}_{ \pm}^{1} \times \mathbb{T}^{n}$ whose elements are vector fields of the form

$$
\bar{a}(x ; \lambda):=a_{0}(x ; \lambda) \frac{\partial}{\partial \lambda}+\left\langle a(x ; \lambda), \frac{\partial}{\partial \mathrm{x}}\right\rangle=\sum_{j=1}^{n} a_{j}(x ; \lambda) \frac{\partial}{\partial x_{j}},
$$

where $x \in \mathbb{T}^{n}, a(\lambda ; x) \in \mathbb{E} \times \mathbb{E}^{n}$ are vectors on $\mathbb{E} \times \mathbb{E}^{n}$ holomorphic in $\lambda \in \mathbb{D}_{ \pm}^{1}$, and in addition,

$$
\frac{\partial}{\partial \mathrm{x}}:=\left(\frac{\partial}{\partial \lambda}, \frac{\partial}{\partial x_{1}}, \frac{\partial}{\partial x_{2}}, \ldots, \frac{\partial}{\partial x_{n}}\right)^{\top}
$$

denotes the gradient operator in the Euclidean space $\mathbb{E} \times\left(\mathbb{E}^{n} ;\langle\cdot, \cdot\rangle\right)$ with respect to the vector variable $\mathrm{x}:=$ $(\lambda, x) \in \mathbb{T}_{\mathbb{C}}^{n}$.

Consider a semidirect sum

$$
\overline{\mathcal{G}}:=\operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right) \ltimes \operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right)^{*}
$$

of the loop Lie algebra diff $\left(\mathbb{T}^{n} \times \mathbb{C}\right)$ and its regular adjoint space $\operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right)^{*}$ with respect to the convolution:

$$
(\bar{l} \mid \bar{a}):=\underset{\lambda \in \mathbb{C}}{\operatorname{res}}(l(\mathrm{x}) \mid a(\mathrm{x}))_{H^{0}}
$$

for any $\bar{l} \in \operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right)^{*}$ and $\bar{a} \in \operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right)$. Here, each element $\bar{l} \in \operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right)^{*}$ has the form

$$
\bar{l}:=\langle l(x ; \lambda), d \mathrm{x}\rangle=l_{0}(x ; \lambda) d \lambda+\sum_{j=1}^{n} l_{j}(x ; \lambda) d x_{j} .
$$

The commutator on the loop Lie algebra $\overline{\mathcal{G}}$ for any its elements $\bar{a}_{1} \ltimes \bar{l}_{1}, \bar{a}_{2} \ltimes \bar{l}_{2} \in \overline{\mathcal{G}}$ is given by the rule

$$
\left[\bar{a}_{1} \ltimes \bar{l}_{1}, \bar{a}_{2} \ltimes \bar{l}_{2}\right]:=\left[\bar{a}_{1}, a_{2}\right] \ltimes a d_{a_{1}}^{*} \bar{l}_{2}-a d_{a_{2}}^{*} \bar{l}_{1} .
$$

By using the decomposition of the Lie algebra $\overline{\mathcal{G}}$ into the direct sum of two Lie subalgebras: $\overline{\mathcal{G}}=\overline{\mathcal{G}}_{+} \oplus \overline{\mathcal{G}}_{-}$, we can construct the $R$-deformed commutator as follows:

$$
\left[\bar{a}_{1} \ltimes \bar{l}_{1}, \bar{a}_{2} \ltimes \bar{l}_{2}\right]_{R}:=\left[R\left(\bar{a}_{1} \ltimes \bar{l}_{1}\right), \bar{a}_{2} \ltimes \bar{l}_{2}\right]+\left[\bar{a}_{1} \ltimes \bar{l}_{1}, R\left(\bar{a}_{2} \ltimes \bar{l}_{2}\right)\right],
$$

where $\bar{a}_{1} \ltimes \bar{l}_{1}, \bar{a}_{2} \ltimes \bar{l}_{2} \in \overline{\mathcal{G}}, R:=\left(P_{+}-P_{-}\right) / 2$, and $P_{ \pm} \overline{\mathcal{G}}:=\overline{\mathcal{G}}_{ \pm} \subset \overline{\mathcal{G}}$.

On the Lie algebra $\overline{\mathcal{G}}$, we can introduce an $a d$-invariant nondegenerate scalar product:

$$
(\bar{a} \ltimes \bar{l} \mid \bar{r} \ltimes \bar{m}):=\underset{\lambda \in \mathbb{C}}{\operatorname{res}}(\bar{a} \ltimes \bar{l} \mid \bar{r} \ltimes \bar{m})_{H^{0}},
$$

where, by definition,

$$
\begin{equation*}
(\bar{a} \ltimes \bar{l} \mid \bar{r} \ltimes \bar{m})_{H^{0}}=(\bar{m} \mid \bar{a})_{H^{0}}+(\bar{l} \mid \bar{r})_{H^{0}} \tag{2.1}
\end{equation*}
$$

for any pair of elements $\bar{a} \ltimes \bar{l}, \bar{r} \ltimes \bar{m} \in \overline{\mathcal{G}}$. By using this product, we can identify its regular adjoint space $\overline{\mathcal{G}}^{*}$ with the Lie algebra: $\overline{\mathcal{G}}^{*} \simeq \overline{\mathcal{G}}$.

For any smooth functionals $f, g \in \mathrm{D}\left(\overline{\mathcal{G}}^{*}\right)$, we can construct the following two Lie-Poisson brackets:

$$
\{f, g\}:=(\bar{a} \ltimes \bar{l} \mid[\nabla f(\bar{l} ; \bar{a}), \nabla g(\bar{l} ; \bar{a})])
$$

and

$$
\begin{equation*}
\{f, g\}_{R}:=\left(\bar{a} \ltimes \bar{l} \mid[\nabla f(\bar{l} ; \bar{a}), \nabla g(\bar{l} ; \bar{a})]_{R}\right), \tag{2.2}
\end{equation*}
$$

where

$$
\nabla f(\bar{l} ; \bar{a}):=\nabla f_{\bar{l}} \ltimes \nabla f_{\bar{a}} \simeq\left\langle\nabla f(l ; a),(\partial / \partial \mathrm{x}, d \mathrm{x})^{\top}\right\rangle \in \overline{\mathcal{G}}
$$

and

$$
\nabla g(\bar{l} ; \bar{a}):=\nabla g_{\bar{l}} \ltimes \nabla g_{\bar{a}} \simeq\left\langle\nabla g(l ; a),(\partial / \partial \mathrm{x}, d \mathrm{x})^{\top}\right\rangle \in \overline{\mathcal{G}}^{*}
$$

are the gradients of the functionals $f, g \in \mathrm{D}\left(\overline{\mathcal{G}}^{*}\right)$ with respect to the scalar product (2.1) at the point $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*} \simeq \overline{\mathcal{G}}$. Here,

$$
\nabla f_{\bar{l}}=\left\langle\nabla f_{l}, \partial / \partial \mathrm{x}\right\rangle, \quad \nabla f_{\bar{a}}=\left\langle\nabla f_{a}, d \mathrm{x}\right\rangle \quad \text { and } \quad \nabla g_{\bar{l}}=\left\langle\nabla g_{l}, \partial / \partial \mathrm{x}\right\rangle, \quad \nabla g_{\bar{a}}=\left\langle\nabla g_{a}, d \mathrm{x}\right\rangle .
$$

Assume that a smooth functional $h \in I\left(\overline{\mathcal{G}}^{*}\right)$ is the Casimir invariant, i.e.,

$$
\begin{equation*}
a d_{\nabla h(\bar{l}, \bar{a})}^{*}(\bar{a} \ltimes \bar{l})=0 \tag{2.3}
\end{equation*}
$$

for a chosen element $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*} \simeq \overline{\mathcal{G}}$. Since, for any element $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*} \simeq \overline{\mathcal{G}}$ and any smooth functional $f \in \mathrm{D}\left(\overline{\mathcal{G}}^{*}\right)$, the coadjoint map has the form

$$
a d_{\nabla f(\bar{l}, \bar{a})}^{*}(\bar{a} \ltimes \bar{l})=\left(\left[\nabla h_{\tilde{l}}, \tilde{a}\right] \ltimes\left(a d_{\nabla h_{\bar{l}}}^{\tilde{l}}+a d_{\tilde{a}}^{*} \nabla h_{\tilde{a}}\right),\right.
$$

we can rewrite condition (2.3) as follows:

$$
\left[\nabla h_{\tilde{l}}, \tilde{a}\right]=0, \quad a d_{\nabla h_{\bar{l}}}^{*} \tilde{l}-a d_{\tilde{a}}^{*} \nabla h_{\tilde{a}}=0
$$

Moreover, the Casimir invariant $h \in I\left(\overline{\mathcal{G}}^{*}\right)$ satisfies the system of equations

$$
\begin{gather*}
\left\langle\nabla h_{l}, \partial / \partial \mathrm{x}\right\rangle a-\langle a, \partial / \partial \mathrm{x}\rangle \nabla h_{l}=0, \\
\left\langle\partial / \partial \mathrm{x}, \circ \nabla h_{l}\right\rangle l+\left\langle l,\left(\partial / \partial \mathrm{x} \nabla h_{l}\right)\right\rangle+\langle\partial / \partial \mathrm{x}, \circ a\rangle \nabla h_{a}+\left\langle a,\left(\partial / \partial \mathrm{x} \nabla h_{a}\right)\right\rangle=0 . \tag{2.4}
\end{gather*}
$$

For any Casimir invariant $h \in \mathrm{D}\left(\overline{\mathcal{G}}^{*}\right)$, the system of equations (2.4) can be solved analytically. If the element $\bar{l} \ltimes \bar{a} \in \overline{\mathcal{G}}^{*}$ has a singularity as $|\lambda| \rightarrow \infty$, then, for every $p \in \mathbb{Z}_{+}$, we determine this solution by using the asymptotic expansion

$$
\begin{equation*}
\nabla h^{(p)}(l ; a) \sim \lambda^{p} \sum_{j \in \mathbb{Z}_{+}}\left(\nabla h_{l ; j}^{(p)} ; \nabla h_{a ; j}^{(p)}\right) \lambda^{-j} \tag{2.5}
\end{equation*}
$$

and substitute it in the system of equations (2.4). Hence, the asymptotic solutions of system (2.4) can be found with the help of recurrence relations.

Further, we assume that, for some Casimir invariants $h^{(y)}, h^{(t)} \in I\left(\overline{\mathcal{G}}^{*}\right)$ involutive with respect to the LiePoisson bracket (2.2), the generators of Hamiltonian vector fields can be chosen in the form

$$
\begin{equation*}
\nabla h^{(y)}(\bar{l} ; \bar{a})_{+}:=\left(\nabla h^{\left(p_{y}\right)}(\bar{l} ; \bar{a})\right)_{+}, \quad \nabla h^{(t)}(\bar{l} ; \bar{a})_{+}:=\left(\nabla h^{\left(p_{t}\right)}(\bar{l} ; \bar{a})\right)_{+}, \tag{2.6}
\end{equation*}
$$

where

$$
\begin{gathered}
\nabla h^{(y)}(\bar{l} ; \bar{a})_{+}:=\left(\nabla h_{\bar{l},+}^{(y)} \ltimes \nabla h_{\bar{a},+}^{(y)}\right) \in \overline{\mathcal{G}}_{+}, \quad \nabla h^{(t)}(\bar{l} ; \bar{a})_{+}:=\left(\nabla h_{\bar{l},+}^{(t)} \ltimes \nabla h_{\bar{a},+}^{(t)}\right) \in \overline{\mathcal{G}}_{+}, \\
p^{(y)}, p^{(t)} \in \mathbb{Z}_{+} .
\end{gathered}
$$

In view of the Lie-Poisson bracket (2.2), these invariants generate the commuting Hamiltonian flows

$$
\begin{align*}
\frac{\partial}{\partial y}(\bar{a} \ltimes \bar{l}) & =-a d_{\nabla h^{(y)}(\bar{l}, \bar{a})_{+}}^{*}(\bar{a} \ltimes \bar{l}),  \tag{2.7}\\
\frac{\partial}{\partial t}(\bar{a} \ltimes \bar{l}) & =-a d_{\nabla h^{(t)}(\bar{l}, \bar{a})_{+}}^{*}(\bar{a} \ltimes \bar{l})
\end{align*}
$$

for any element $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*} \simeq \overline{\mathcal{G}}$ with respect to the evolutionary parameters $y, t \in \mathbb{R}$. The constructed flows (2.6) can be represented in the form

$$
\begin{gather*}
\partial a / \partial y=-\left\langle\nabla h_{l}^{(y)}, \frac{\partial}{\partial \mathrm{x}}\right\rangle a+\left\langle a, \frac{\partial}{\partial \mathrm{x}}\right\rangle \nabla h_{l}^{(y)},  \tag{2.8}\\
\partial a / \partial t=-\left\langle\nabla h_{l}^{(t)}, \frac{\partial}{\partial \mathrm{x}}\right\rangle a+\left\langle a, \frac{\partial}{\partial \mathrm{x}}\right\rangle \nabla h_{l}^{(t)}
\end{gather*}
$$

and

$$
\begin{align*}
\partial l / \partial y= & -\left\langle\frac{\partial}{\partial \mathrm{x}}, \nabla h_{l}^{(y)}\right\rangle l-\left\langle l,\left(\frac{\partial}{\partial \mathrm{x}} \nabla h_{l}^{(y)}\right)\right\rangle \\
& +\left\langle\frac{\partial}{\partial \mathrm{x}}, a\right\rangle \nabla h_{a}^{(y)}+\left\langle a,\left(\frac{\partial}{\partial \mathrm{x}} \nabla h_{a}^{(y)}\right)\right\rangle, \\
\partial l / \partial t= & -\left\langle\frac{\partial}{\partial \mathrm{x}}, \nabla h_{l}^{(t)}\right\rangle l-\left\langle l,\left(\frac{\partial}{\partial \mathrm{x}} \nabla h_{l}^{(t)}\right)\right\rangle  \tag{2.9}\\
& +\left\langle\frac{\partial}{\partial \mathrm{x}}, a\right\rangle \nabla h_{a}^{(t)}+\left\langle a,\left(\frac{\partial}{\partial x} \nabla h_{a}^{(t)}\right)\right\rangle .
\end{align*}
$$

The commutativity condition for the flows (2.6) is equivalent to the system of equalities

$$
\begin{equation*}
\left[\nabla h_{\bar{l},+}^{(y)}, \nabla h_{\bar{l},+}^{(t)}\right]-\frac{\partial}{\partial t} \nabla h_{\bar{l},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\bar{l},+}^{(t)}=0 \tag{2.10}
\end{equation*}
$$

and

$$
\begin{gathered}
a d_{\bar{a}}^{*} \bar{P}=0, \\
\bar{P}=a d_{\nabla h_{\bar{l},+}^{(y)}}^{*}\left(\nabla h_{\bar{a},+}^{(t)}\right)-a d_{\nabla h_{\bar{l},+}^{*}(t)}^{*}\left(\nabla h_{\bar{a},+}^{(y)}\right)-\frac{\partial}{\partial t} \nabla h_{\bar{a},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\bar{a},+}^{(t)},
\end{gathered}
$$

where $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}$. In addition, equality (2.10) is the compatibility condition for the following three linear vector-field equations:

$$
\begin{equation*}
\frac{\partial \psi}{\partial y}+\nabla h_{\bar{l},+}^{(y)} \psi=0, \quad\langle a, \partial / \partial \mathrm{x}\rangle \psi=0, \quad \frac{\partial \psi}{\partial t}+\nabla h_{\bar{l},+}^{(t)} \psi=0, \tag{2.11}
\end{equation*}
$$

for some function $\psi \in C^{2}\left(\mathbb{R}^{2} \times \mathbb{T}_{\mathbb{C}}^{n} ; \mathbb{C}\right)$, all $y, t \in \mathbb{R}$, and any $\mathrm{x} \in \mathbb{T}_{\mathbb{C}}^{n}$. The obtained results can be formulated as the following statement:

Proposition 2.1. Let $h^{(y)}, h^{(t)} \in I\left(\overline{\mathcal{G}}^{*}\right)$ be Casimir invariants for the loop Lie algebra $\overline{\mathcal{G}}$ with respect to the scalar product $(\cdot, \cdot)$ at a point $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*}$ of the regular adjoint space $\overline{\mathcal{G}}^{*} \simeq \overline{\mathcal{G}}$ of this Lie algebra. Then evolutions (2.7) on $\overline{\mathcal{G}}^{*}$ are commuting Hamiltonian flows equivalent to the system of evolutionary equations (2.8), (2.9). The commutativity condition for the evolutionary equations (2.8) is the condition of compatibility of three linear vector-field equations (2.11).

Note that, in the case where the generating element $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*}$ is singular as $|\lambda| \rightarrow 0$, the asymptotic expansion (2.5) should be replaced by the formula

$$
\nabla h^{(p)}(\bar{l}, \bar{a}) \sim \lambda^{-p} \sum_{j \in \mathbb{Z}_{+}} \nabla h_{j}^{(p)}(\bar{l}, \bar{a}) \lambda^{j}
$$

for every $p \in \mathbb{Z}_{+}$. The corresponding commuting Hamiltonian flows for the chosen integers $p_{y}, p_{t} \in \mathbb{Z}_{+}$have the form

$$
\begin{aligned}
\frac{\partial}{\partial t}(\bar{a} \ltimes \bar{l}) & =a d_{\nabla h^{(t)}(\bar{l}, \bar{a})_{-}}^{*}(\bar{a} \ltimes \bar{l}), \\
\frac{\partial}{\partial y}(\bar{a} \ltimes \bar{l}) & =a d_{\nabla h^{(y)}(\bar{l}, \bar{a})_{-}}^{*}(\bar{a} \ltimes \bar{l}),
\end{aligned}
$$

where

$$
\begin{aligned}
& \nabla h^{(y)}(\bar{l}, \bar{a})_{-}:=\lambda\left(\lambda^{-p_{y}-1} \nabla h^{\left(p_{y}\right)}(\bar{l}, \bar{a})\right)_{-}, \\
& \nabla h^{(t)}(\bar{l}, \bar{a})_{-}:=\lambda\left(\lambda^{-p_{t}-1} \nabla h^{\left(p_{t}\right)}(\bar{l}, \bar{a})\right)_{-},
\end{aligned}
$$

and $y, t \in \mathbb{R}$.

As in Sec. 3, we consider the central extension of the point product $\overline{\mathcal{G}}^{\mathbb{S}^{1}}:=\prod_{z \in \mathbb{S}^{1}} \overline{\mathcal{G}}$ of the holomorphic loop Lie algebra $\overline{\mathcal{G}}$ by the Maurer-Cartan 2-cocycle $\bar{\omega}_{2}: \overline{\mathcal{G}} \times \overline{\mathcal{G}} \rightarrow \mathbb{C}$ of the form

$$
\bar{\omega}_{2}\left(\bar{a}_{1} \ltimes \bar{l}_{1}, \bar{a}_{2} \ltimes \bar{l}_{2}\right):=\int_{\mathbb{S}^{1}}\left[\left(\bar{l}_{1}, \partial \bar{a}_{2} / \partial z\right)_{1}-\left(\bar{l}_{2}, \partial \bar{a}_{1} / \partial z\right)_{1}\right],
$$

where $\bar{a}_{1} \ltimes \bar{l}_{1}, \bar{a}_{2} \ltimes \bar{l}_{2} \in \overline{\mathcal{G}}$.
For any smooth functionals $h, f \in D\left(\overline{\mathfrak{G}}^{*}\right)$ on the regular space $\overline{\mathfrak{G}}^{*}$ adjoint to the centrally extended holomorphic loop algebra $\overline{\mathfrak{G}}:=\overline{\mathcal{G}} \oplus \mathbb{C}$, the $\mathcal{R}$-deformed Lie-Poisson bracket has the form

$$
\begin{align*}
\{h, f\}_{\mathcal{R}}:= & \left(\bar{a} \ltimes \bar{l},[\nabla h(\bar{l}, \bar{a}), \nabla f(\bar{l}, \bar{a})]_{\mathcal{R}}\right) \\
& +\bar{\omega}_{2}(\mathcal{R} \nabla h(\bar{l}, \bar{a}), \nabla f(\bar{l}, \bar{a}))+\bar{\omega}_{2}(\nabla h(\bar{l}, \bar{a}), \mathcal{R} \nabla f(\bar{l}, \bar{a})) \tag{2.12}
\end{align*}
$$

The corresponding Casimir invariants $h^{(p)} \in I\left(\overline{\mathfrak{G}}^{*}\right), p \in \mathbb{Z}_{+}$, are determined by the standard Lie-Poisson bracket as follows:

$$
\left\{h^{(p)}, f\right\}:=\left(\bar{a} \ltimes \bar{l},\left[\nabla h^{(p)}(\bar{l}, \bar{a}), \nabla f(\bar{l}, \bar{a})\right]\right)+\bar{\omega}_{2}\left(\nabla h^{(p)}(\bar{l}, \bar{a}), \nabla f(\bar{l}, \bar{a})\right)=0
$$

for any smooth functional $f \in D\left(\overline{\mathfrak{G}}^{*}\right)$.
It follows from equality (1.18) that the gradients $\nabla h^{(p)} \in \overline{\mathcal{G}}$ of the Casimir invariants $h^{(p)} \in I\left(\overline{\mathfrak{G}}^{*}\right), p \in \mathbb{Z}_{+}$, satisfy the equations

$$
\left[\nabla h_{\bar{l}}, \bar{a}\right]-\frac{\partial}{\partial z} \nabla h_{\bar{l}}=0, \quad a d_{\nabla h_{\bar{l}}}^{*}-a d_{\bar{a}}^{*} \nabla h_{\bar{a}}-\frac{\partial}{\partial z} \nabla h_{\bar{a}}=0
$$

at the point $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*}$.
For some Casimir invariants $h^{(y)}, h^{(t)} \in I\left(\overline{\mathfrak{G}}^{*}\right)$, we use the Lie-Poisson bracket (2.12) to construct the commuting Hamiltonian flows on $\overline{\mathfrak{G}}^{*}$ :

$$
\begin{equation*}
\frac{\partial}{\partial y}(\bar{a} \ltimes \bar{l})=\left\{\bar{a} \ltimes \bar{l}, h^{(y)}\right\}_{\mathcal{R}}, \quad \frac{\partial}{\partial t}(\bar{a} \ltimes \bar{l})=\left\{\bar{a} \ltimes \bar{l}, h^{(t)}\right\}_{\mathcal{R}} . \tag{2.13}
\end{equation*}
$$

These flow are equivalent to the evolutionary equations

$$
\begin{align*}
\frac{\partial}{\partial y} \bar{a} & =-\left[\nabla h_{\bar{l},+}^{(y)}, \bar{a}\right]+\frac{\partial}{\partial z} \nabla h_{\bar{l},+}^{(y)},  \tag{2.14}\\
\frac{\partial}{\partial t} \bar{a} & =-\left[\nabla h_{\bar{l},+}^{(t)}, \bar{a}\right]+\frac{\partial}{\partial z} \nabla h_{\bar{l},+}^{(t)}
\end{align*}
$$

and

$$
\begin{align*}
& \frac{\partial}{\partial y} \bar{l}=-a d_{\nabla h_{\bar{l}+}^{(y)}}^{*} \bar{l}+a d_{\bar{a}}^{*}\left(\nabla h_{\bar{a},+}^{(y)}\right)+\frac{\partial}{\partial z} \nabla h_{\bar{a},+}^{(y)},  \tag{2.15}\\
& \frac{\partial}{\partial t} \bar{l}=-a d_{\nabla h_{l,+}^{(t)}}^{*} \bar{l}+a d_{\bar{a}}^{*}\left(\nabla h_{\bar{a},+}^{(t)}\right)+\frac{\partial}{\partial z} \nabla h_{\bar{a},+}^{(t)} .
\end{align*}
$$

The commutativity condition for these flows is equivalent to the system of equations

$$
\begin{equation*}
\left[\nabla h_{\bar{l},+}^{(y)}, \nabla h_{\bar{l},+}^{(t)}\right]-\frac{\partial}{\partial t} \nabla h_{\bar{l},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\bar{l},+}^{(t)}=0 \tag{2.16}
\end{equation*}
$$

and

$$
\begin{gathered}
\frac{\partial \bar{P}}{\partial z}+a d_{\bar{a}}^{*} \bar{P}=0 \\
\bar{P}=a d_{\nabla h_{\bar{l},+}^{(y)}}^{*}\left(\nabla h_{\bar{a},+}^{(t)}\right)-a d_{\nabla h_{\bar{l},+}^{(t)}}^{*}\left(\nabla h_{\bar{a},+}^{(y)}\right)-\frac{\partial}{\partial t} \nabla h_{\bar{a},+}^{(y)}+\frac{\partial}{\partial y} \nabla h_{\bar{a},+}^{(t)}
\end{gathered}
$$

for any $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}$.
Hence, the following statement is true :
Proposition 2.2. The Hamiltonian flows (2.13) on the regular adjoint space $\overline{\mathfrak{G}}^{*}$ generate systems of commuting evolutionary equations (2.14), (2.15). The commutativity condition for the evolutionary equations (2.14) is equivalent to the Lax-Sato representation (2.16) for some system of nonlinear partial differential equations of the heavenly type and coincides with the condition of compatibility of three linear vector-field equations

$$
\frac{\partial \psi}{\partial y}+\nabla h_{\bar{l},+}^{(y)} \psi=0, \quad \frac{\partial \psi}{\partial z}+\langle a, \partial / \partial \mathrm{x}\rangle \psi=0, \quad \frac{\partial \psi}{\partial t}+\nabla h_{\bar{l},+}^{(t)} \psi=0
$$

for all $(y, t, z ; \mathrm{x}) \in\left(\mathbb{R}^{2} \times \mathbb{S}^{1}\right) \times \mathbb{T}_{\mathbb{C}}^{n}$ and some function $\psi \in C^{2}\left(\left(\mathbb{R}^{2} \times \mathbb{S}^{1}\right) \times \mathbb{T}_{\mathbb{C}}^{n} ; \mathbb{C}\right)$.
2.1. Example: New Generalized Mikhalev-Pavlov Equation in the Four-Dimensional Space. If the generating element $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*}$ has the form

$$
\begin{equation*}
\bar{a} \ltimes \bar{l}=\left(\left(u_{x}-\lambda\right) \partial / \partial x+v_{x} \partial / \partial \lambda\right) \ltimes\left(w_{x} d x+\xi_{x} d \lambda\right), \tag{2.17}
\end{equation*}
$$

where

$$
u, v, w, \xi \in C^{2}\left(\mathbb{R}^{2} \times\left(\mathbb{S}^{1} \times \mathbb{T}^{1}\right) ; \mathbb{R}\right)
$$

then the asymptotic expansions for the coordinates of gradients of the Casimir invariants $h^{(p)} \in I\left(\overline{\mathfrak{G}}^{*}\right), p \in \mathbb{Z}_{+}$, as $|\lambda| \rightarrow \infty$, take the form

$$
\begin{gathered}
\nabla h_{\tilde{l}} \simeq \lambda^{p}\binom{1-u_{x} \lambda^{-1}+\left(-u_{z}+(p-1) v\right) \lambda^{-2}+\left(u_{y}+(p-2)\left(-u_{x} v+\kappa\right)\right) \lambda^{-3}+\ldots}{-v_{x} \lambda^{-1}-v_{z} \lambda^{-2}+\left(v_{y}-(p-2) v_{x} v\right) \lambda^{-3}+\ldots}, \\
\nabla h_{\tilde{a}} \simeq \lambda^{p}\binom{-w_{x} \lambda^{-1}-w_{z} \lambda^{-2}+\left(w_{y}-(p-2)(w v)_{x}\right) \lambda^{-3}+\ldots}{-\xi_{x} \lambda^{-1}-\left(\xi_{z}+(p-1) w\right) \lambda^{-2}+\left(\xi_{y}-(p-2)\left(-u_{x} w+v \xi_{x}+\omega\right)\right) \lambda^{-3}+\ldots},
\end{gathered}
$$

where $p \in \mathbb{Z}_{+}$and, in addition,

$$
\begin{equation*}
\kappa_{x}=v_{z}+u_{x} v_{x}, \quad \omega_{x}=w_{z}-u_{x} w_{x}-v_{x} \xi_{x} . \tag{2.18}
\end{equation*}
$$

In the case where

$$
\begin{gathered}
\nabla h_{\tilde{l},+}^{(y)}:=\binom{\lambda^{2}-u_{x} \lambda+\left(-u_{z}+v\right)}{-v_{x} \lambda-v_{z}}, \\
\nabla h_{\tilde{a},+}^{(y)}:=\binom{-w_{x} \lambda-w_{z}}{-\xi_{x} \lambda-\left(\xi_{z}+w\right)}
\end{gathered}
$$

and

$$
\begin{gathered}
\nabla h_{\tilde{l},+}^{(t)}:=\binom{\lambda^{3}-u_{x} \lambda^{2}+\left(-u_{z}+2 v\right) \lambda+\left(u_{y}-u_{x} v+\kappa\right)}{-v_{x} \lambda^{2}-v_{z} \lambda+\left(v_{y}-v_{x} v\right)}, \\
\nabla h_{\tilde{a},+}^{(t)}:=\binom{-w_{x} \lambda^{2}-w_{z} \lambda+\left(w_{y}-(w v)_{x}\right)}{-\xi_{x} \lambda^{2}-\left(\xi_{z}+2 w\right) \lambda+\left(\xi_{y}+u_{x} w-v \xi_{x}-\omega\right)},
\end{gathered}
$$

the commutativity condition for the Hamiltonian flows (2.13) is reduced to the following system of evolutionary equations:

$$
\begin{gather*}
u_{z t}+u_{y y}=-u_{y} u_{z x}+u_{z} u_{x y}-u_{x y} v-u_{z z} v-\kappa u_{x z}, \\
v_{z t}+v_{y y}=v v_{x}^{2}-v_{z}^{2}-v v_{x y}-v v_{z z}-u_{y} v_{x z}+u_{z} v_{x y}-u_{z} v_{x}^{2}-\kappa v_{x z}, \\
-u_{x y}-u_{z z}=u_{x} u_{x z}-u_{z} u_{x x}+u_{x x} v,  \tag{2.19}\\
-v_{x y}-v_{z z}=v_{x}^{2}+v_{x x} v+u_{x} v_{x z}-u_{z} v_{x x}, \\
-u_{x t}+u_{y z}=-u_{x} u_{x y}+u_{y} u_{x x}+u_{x z} v+u_{x x} \kappa, \\
-v_{x t}+v_{y z}=-u_{x} v_{x y}+u_{y} v_{x x}+u_{x} v_{x}^{2}+v_{x z} v+\kappa v_{x x}+2 v_{x} v_{z} .
\end{gather*}
$$

For $v=0$, we again arrive at system (1.29).
Thus, the following statement is true:
Proposition 2.3. The generalized Mikhalev-Pavlov system (2.19), (2.18) admits a vector-field Lax-Sato representation (2.16) with "spectral" parameter $\lambda \in \mathbb{C}$ generated by an element $\bar{a} \ltimes \bar{l} \in \overline{\mathcal{G}}^{*}$ in the form (2.17).

Element (2.17) can be rewritten in the form

$$
\begin{gathered}
\tilde{a} \ltimes \tilde{l}:=\left(\frac{\partial \tilde{\xi}}{\partial x} \frac{\partial}{\partial x}+\frac{\partial \tilde{\xi}_{0}}{\partial \lambda} \frac{\partial}{\partial \lambda}\right) \ltimes\left(d_{x} \tilde{\rho}+\frac{\partial \tilde{\rho}_{0}}{\partial \lambda}\right), \\
\tilde{\eta}=u-\lambda x, \quad \tilde{\eta}_{0}=\lambda v_{x}, \quad \tilde{\rho}=w, \quad \tilde{\rho}_{0}=\lambda \xi_{x},
\end{gathered}
$$

where $d:=d_{x}+d_{\lambda}$, connected with the geometry of the space of moduli of gauge connectedness corresponding to the coadjoint actions of the Casimir invariants.

By using an element $\tilde{a} \ltimes \tilde{l} \in \overline{\mathcal{G}}^{*}$ of the form

$$
\tilde{a} \ltimes \tilde{l}:=\left(\left\langle\nabla_{x} \tilde{\eta}, \nabla_{x}\right\rangle+\frac{\partial \tilde{\eta}_{0}}{\partial \lambda} \frac{\partial}{\partial \lambda}\right) \ltimes\left(d_{x} \tilde{\rho}+\frac{\partial \tilde{\rho}_{0}}{\partial \lambda}\right),
$$

where $\tilde{\eta}, \tilde{\eta}_{0}, \tilde{\rho}, \tilde{\rho}_{0} \in \Omega^{0}\left(\mathbb{T}^{n}\right) \otimes \mathbb{C}, n \in \mathbb{N}, N>2$, we can get a Lax-Sato integrable multidimensional analog of the generalized Mikhalev-Pavlov system (2.19), (2.18) in the ( $n+3$ )-dimensional space, where $n>2$. This case will be considered elsewhere.

## 3. Conclusions

We present a review of differential-geometric and Lie-algebraic approaches to the construction of Lax-Sato integrable differential systems of equations of heavenly type based on the development of the Adler-KonstantSymes structure and the $R$-operator structures associated with this structure. We propose the generalization of this structure to the case of central extensions of the loop Lie algebras $\tilde{\mathcal{G}}:=\widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right) \ltimes \widetilde{\operatorname{diff}}\left(\mathbb{T}^{n}\right)^{*}$ and their holomorphic extensions

$$
\overline{\mathcal{G}}:=\operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right) \ltimes \operatorname{diff}\left(\mathbb{T}^{n} \times \mathbb{C}\right)^{*}
$$

Within the framework of the developed approach, the corresponding systems of equations of heavenly type follow from the condition of commutativity of two Hamiltonian flows on regular spaces adjoint to these Lie algebras as one-parameter orbits of the coadjoint action of holomorphic group of diffeomorphisms. In particular, in numerous cases, the solutions of these systems can be found by using the corresponding version of the method of inverse scattering problem [7]. The proposed approach enables us to obtain the Lax-Sato integrable modified and generalized heavenly Mikhalev-Pavlov systems in the four-dimensional space, a modified Martínez-AlonsoShabat heavenly system in the five-dimensional space, and the corresponding hierarchies of conservation laws. It becomes also possible to consider the problem of construction of their integrable analogs in the spaces of higher dimensions. In addition, on the basis of the proposed approach, it is possible to find the Hamiltonian representations for the constructed heavenly systems as a result of reduction of the $R$-deformed Lie-Poisson bracket to the phase space of the generating element. This will be done elsewhere.

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