The formation of multiples in small-*N* **subclusters**

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ABSTRACT

We explore the relative percentages of binary systems and higher-order multiples that are formed by pure stellar dynamics, within a small subcluster of N stars. The subcluster is intended to represent the fragmentation products of a single isolated core, after most of the residual gas of the natal core has dispersed. Initially, the stars have random positions, and masses drawn from a lognormal distribution. For low-mass cores spawning multiple systems with Sun-like primaries, the best fit to the observed percentages of singles, binaries, triples, and higher-order systems is obtained if a typical core spawns on average between $N =$ 4.3 and 5.2 stars, specifically a distribution of *N* with mean $\mu_N \sim 4.8$ and standard deviation $\sigma_N \sim 2.4$. This fit is obtained when ∼ 50 per cent of the subcluster's internal kinetic energy is invested in ordered rotation and ∼ 50 per cent in isotropic Maxwellian velocities. There is little dependence on other factors, for example mass segregation or the rotation law. While such high values of *N* are at variance with the lower values often quoted (i.e. $N = 1$ or 2), very similar values ($N = 4.3 \pm 0.4$ and $N = 4.5 \pm 1.9$) have been derived previously by completely independent routes, and seem inescapable when the observed distribution of multiplicities is taken into account.

Key words: celestial mechanics – binaries: close – stars: formation – stars: kinematics and dynamics.

1 INTRODUCTION

Most field stars more massive than the Sun are not single (Whitworth & Lomax [2015;](#page-10-0) Offner et al. [2023\)](#page-9-0). They exist in multiple systems, i.e. gravitationally bound groups in which the individual stars are on more-or-less constant and stable orbits about one another. The most common multiple systems are binaries: two stars orbiting their mutual centre of mass on elliptical orbits. However, there is an increasing recognition that there are also many higher-order multiple systems in the field (and even more in regions of recent star formation; Chen et al. [2013\)](#page-9-0). Stable, long-lived triple systems comprise two stars in a relatively close binary system with a third star on a significantly wider orbit about the binary. Quadruple systems come in two variants: $2 + 2$ ' quadruples comprise two relatively close binary systems on a wide orbit about one another; and 'planetary' quadruples comprise a triple system (as define above) with a fourth star on an even wider orbit about the triple. The highest-order multiples known are septuples. An example of a septuple is 65 UMa (11551+4629), in which a central binary is orbited not only by three companions on planetary orbits, but a distant binary pair as well (see Tokovinin [2021\)](#page-9-0).

A young subcluster comprising *N* stars may evolve into A_N possible end states, where A_N increases rapidly with *N*. For $N \le 10$:

$$
\mathcal{A}_N = \sum_{n=2}^N \left\{ 1 + \sum_{n'=2}^n \left\{ \left[\frac{N-n}{n'} \right] + H(N - (n + n' + 2)) \right. \\ \times \sum_{n''=2}^{n'-1} \left[\frac{N - (n + n')}{n''} \right] \right\} \right\}.
$$
 (1)

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Here, $\vert \vert$ is the floor operator, and *H* is the Heaviside function. Thus, a subcluster with $N = 7$ members can evolve into $A_7 = 14$ different end states, as enumerated in Section [3.1.](#page-5-0) A derivation and explanation of equation (1) is given in Appendix [A.](#page-10-0)

1.1 Observational perspective

Recent advancesin observational technology and capability have lead to the discovery of additional members in known star systems, and thereby greatly increased the inventory of higher-order multiples in the solar neighbourhood. When Duquennoy & Mayor [\(1991\)](#page-9-0) studied the multiplicity of solar-type stars in a 22-pc sample, they found that only 5 per cent hosted triple or higher-order systems. For a 25 pc sample, Raghavan et al. [\(2010\)](#page-9-0) found this percentage to be 13 per cent, and it increased to 17 per cent when Tokovinin [\(2021\)](#page-9-0) and Hirsch et al. [\(2021\)](#page-9-0) studied the sample in 2021.

The Tokovinin [\(2021\)](#page-9-0) statistics for nearby systems with solar-type primaries, in the field (hereafter the T21 sample), are

$$
S: B: T: Q^+ = 54:29:12:5.
$$
 (2)

Here, *S* is the percentage of single stars, *B* the percentage of binaries, *T* the percentage of triples, and Q^+ the percentage of quadruples plus higher-order systems (i.e. quintuples, sextuples, and septuples).

Thus, in this sample, the fraction of stars that are single is

$$
f_{\rm s} = \frac{S}{S + 2B + 3T + 4Q^+} \simeq 32.1 \text{ per cent};
$$
 (3)

the fraction of stars that is in binaries is

$$
f_{\rm B} = \frac{2B}{S + 2B + 3T + 4Q^+} \simeq 34.6 \text{ per cent};
$$
 (4)

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Published by Oxford University Press on behalf of Royal Astronomical Society. This is an Open Access article distributed under the terms of the Creative Commons Attribution License [\(https://creativecommons.org/licenses/by/4.0/\)](https://creativecommons.org/licenses/by/4.0/), which permits unrestricted reuse, distribution, and reproduction in any medium, provided the original work is properly cited. and the fraction that is in triples or higher-order systems is

$$
f_{\text{T}+} = \frac{3T + 4Q^+}{S + 2B + 3T + 4Q^+} \simeq 33.3 \text{ per cent.}
$$
 (5)

These percentages should be qualified with two caveats. First, we have assumed that all the systems contributing to Q^+ are quadruples. If account were taken of the systems that are quintuples, sextuples, and septuples, f_{T^+} would increase slightly, at the expense of f_s and f_{B} . Secondly, although these percentages are uncertain, due to selection effects and observational bias, the expectation must be that in the future they will shift towards higher orders, as additional members of existing systems are discovered. This will reduce f_s , and probably increase both f_B and f_{T+} .

Moreover, we should also note that, by construction, the stars in the T21 sample have masses $M \lesssim M_{\odot}$. Samples with higher-mass primaries tend to have even higher multiplicities than the T21 sample. For example, in the survey by Sana [\(2017\)](#page-9-0) essentially all of the highmass stars are members of higher-order systems. The systems we are considering here are presumed to be the product of low-mass cores of the sort that define the peak of the core mass function (CMF) and are observed in nearby low-mass star formation regions.

We should also be mindful that the multiplicities of stellar systems depend on their age. Reipurth & Zinnecker [\(1993\)](#page-9-0) show that young populations tend to have higher multiplicities than their older counterparts. Indeed, multiplicity begins to decline even in the protostellar phase. Chen et al. (2013) show that the average multiplicity decreases as one progresses from Class 0, through Class I, to Class II protostars.

1.2 Theoretical perspective

We shall assume that usually an observed multiple system with a solar-mass primary has formed from a single prestellar core. There are then two main mechanisms involved: (i) dynamical core collapse and fragmentation and (ii) disc fragmentation. These two mechanisms are not mutually exclusive, rather they tend to be sequential.¹

In the standard paradigm for star formation, molecular clouds are highly turbulent, and in some regions the turbulence produces convergent flows of sufficient strength to produce self-gravitating sheets, filaments, and cores.

Unless it is rapidly dispersed by tidal forces or shear, a selfgravitating core collapses. And, unless it is very spherically symmetric and non-rotating, it is likely to fragment dynamically to produce a small subcluster of stars (e.g. Cha & Whitworth [2003;](#page-9-0) Fisher [2004;](#page-9-0) Goodwin, Whitworth & Ward-Thompson [2004a,](#page-9-0) [b;](#page-9-0) Hennebelle et al. [2004;](#page-9-0) Hubber & Whitworth [2005;](#page-9-0) Stamatellos, Hubber & Whitworth [2007;](#page-9-0) Offner et al. [2010;](#page-9-0) Walch, Whitworth & Girichidis [2012;](#page-10-0) Lomax et al. [2014;](#page-9-0) Lomax, Whitworth & Hubber [2015,](#page-9-0) [2016;](#page-9-0) Rohde et al. [2021;](#page-9-0) Whitworth et al. [2024\)](#page-10-0). This is 'dynamical core collapse and fragmentation'.

The resulting stars are usually attended by accretion discs, comprising material that has too much specific angular momentum to fall directly on to the central star. If such an accretion disc becomes sufficiently massive, extended, and cold, it fragments to produce a secondary star or stars, in orbit around the primary (e.g. Adams, Ruden & Shu [1989;](#page-9-0) Chapman et al. [1992;](#page-9-0) Bonnell & Bate [1994;](#page-9-0) Turner et al. [1995;](#page-9-0) Whitworth et al. [1995;](#page-10-0) Bhattal et al. [1998;](#page-9-0) Boffin et al. [1998;](#page-9-0) Watkins et al. [1998a,](#page-10-0) [b;](#page-10-0) Stamatellos et al. [2007;](#page-9-0)

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Stamatellos & Whitworth [2008;](#page-9-0) Stamatellos & Whitworth [2009a,](#page-9-0) [b;](#page-9-0) Walch et al. [2009,](#page-9-0) [2010;](#page-9-0) Kratter et al. [2010;](#page-9-0) Thies et al. [2010;](#page-9-0) Stamatellos, Whitworth & Hubber [2011,](#page-9-0) [2012;](#page-9-0) Lomax et al. [2015;](#page-9-0) Whitworth & Lomax [2016;](#page-10-0) Di G. Sigalotti et al. [2023\)](#page-9-0). This is 'disc fragmentation'.

Together, these mechanisms have been shown to produce young multiple systems of as many as seven stars (Lomax et al. [2016\)](#page-9-0).

1.3 Previous related theoretical studies

McDonald & Clarke [\(1993\)](#page-9-0) have introduced the concept of dynamical biasing, which is the tendency for the more massive stars in a small-*N* subcluster to form a binary, and for the less massive ones to be ejected, thereby making the binary more tightly bound. In a second paper, McDonald & Clarke (1995) show that, if the stars in a small-*N* subcluster are attended by discs, the increased dissipation during close encounters reduces the effectiveness of dynamical biasing $-$ i.e. the lower-mass stars have a better chance of ending up in a binary. It also increases the tendency to produce higher-order multiples. Kuruwita & Haugbølle [\(2023\)](#page-9-0) have shown that the drag from the gas of the natal cloud can drive the inspiral of forming stars, bringing binaries closer together. This would harden them against dissolution and increase the proportion of higher-order multiples.

Sterzik & Durisen [\(1998\)](#page-9-0) have explored multiplicity in a cold, non-rotating, spherical distribution of $N = 3, 4$, or 5 stars. The stars have masses drawn from a Miller–Scalo distribution, and are evolved for 1000 crossing times, using an *N*-body code. At the end, the multiplicities are

S: B: T = 47:47:6, for
$$
N = 3
$$
;
\nS: B: T: Q = 63:29:6:1, for $N = 4$;
\nS: B: T: Q⁺ = 70:19:9:1, for $N = 5$. (6)

Thus, increasing *N* increases the percentage of singles and reduces the percentage of binaries.

Holman et al.[\(2013\)](#page-9-0) have shown using purely statistical arguments that, if the shape of the stellar initial mass function (IMF) is inherited from the shape of the prestellar CMF, then the observed increase in binary frequency with primary mass (e.g. Offner et al. [2023\)](#page-9-0) requires that a prestellar core must typically spawn a subcluster of 4–5 stars.

1.4 Overview and plan

In this work, we extend the study of Sterzik & Durisen (1998) to larger numbers of stars, and to more general initial conditions. Although circumstellar discs and disc fragmentation are likely to be important, particularly for forming lower mass stars and close orbits, we limit consideration here to subclusters formed purely by dynamical core collapse and fragmentation, and neglect discs. Consequently, our numerical experiments start with single discless stars, and all multiple systems are formed subsequently by energy-conserving gravitational interactions between point masses. The role of discs will be explored in a later paper.

In Section [2,](#page-2-0) we describe our model for a small-*N* subcluster, and the procedures used to follow its evolution and to identify the resulting multiple systems. In Section [3,](#page-4-0) we analyse the results, and by comparing them with observations derive the best-fitting parameters for a subcluster. In Section [4,](#page-9-0) we summarize the main conclusions.

¹We note that in the higher-mass cores that form more massive stars a third mechanism needs to be considered. These higher-mass cores are often fed by filamentary accretion streams that are sufficiently massive to form multiple systems by filament fragmentation. These multiples systems then fall into the monolithic cluster that is forming in the central hub, where they interact with other stars and systems. This is not the scenario we are considering here.

In Appendix [A,](#page-10-0) we derive equation (1) , and in Appendix [B](#page-10-0) we show how the results can be re-scaled to represent subclusters of different initial mass and/or linear extent. In Table 1, we list the parameters used in this paper.

2 METHOD

2.1 Initial conditions

Five physical parameters are required to generate the initial conditions for a subcluster. The first is the number of stars in the subcluster, *N*. We evolve subclusters with $3 \leq N \leq 7$. *N* can also equal 1 or 2, but we do not need to evolve these cases because their multiplicity statistics cannot be changed by pure internal dynamical evolution. Larger values of N ($>$ 7) are not considered because it is prohibitive to keep track of all the different possible outcomes; such large *N* are also likely to be rare.

The remaining four physical parameters, (σ_{ℓ} , $\alpha_{\rm rot}$, $\alpha_{\rm law}$, $\alpha_{\rm seg}$) are termed 'configuration parameters', and regulate – in a statistical sense – the distribution of stellar masses and the initial distribution of stars in phase space. In the remainder of this section, we define the four configuration parameters and explain how they are implemented in setting up the initial conditions. They are also listed in the first section of Table 1, and they are all dimensionless.

The individual stellar masses, *M*, are generated from a lognormal distribution. Specifically, $M = M_{\odot} 10^{\ell}$, where ℓ is a random deviate from a Gaussian distribution with mean μ_{ℓ} and standard deviation σ_{ℓ} . Here, σ_{ℓ} is a configuration parameter, since it regulates the width of the mass distribution, i.e. the mean ratio between the most and least massive stars. We have explored values in the range $0.2 \le$ $\sigma_{\ell} \leq 0.4$, but focus here on results obtained with $\sigma_{\ell} = 0.3$.² μ_{ℓ} is *not* a configuration parameter, since the results can be re-scaled to any median mass, as explained in Appendix [B.](#page-10-0) However, for the purpose of illustration, we set $\mu_{\ell} = -0.6$, so that the median mass is $M_{\text{med}} = 0.25 M_{\odot}$.

In the first instance, the stars are given random positionsin a sphere of radius *R*. Specifically, the position of a star in spherical polars is $[r, \theta, \phi] = [\mathcal{L}_1^{1/3} R, \cos^{-1}(2\mathcal{L}_2 - 1), 2\pi \mathcal{L}_3]$, where $[\mathcal{L}_1, \mathcal{L}_2, \mathcal{L}_3]$ are independent random linear deviates on the interval [0, 1]. The spherical polar coordinates are then converted to Cartesian coordinates. *R* is *not* a configuration parameter, since the results can be re-scaled to any subcluster radius, as explained in Appendix [B.](#page-10-0) However, for the purpose of illustration, we set $R = 10³$ au. With $\mu_{\ell} = -0.6$ and $R = 10^3$ au, the crossing time for the subcluster is *t*cross ∼ 0*.*07 Myr *N*[−]1*/*2.

The last three configuration parameters regulate the kinetic energy of the stars in the subcluster, its shape, and the spatial distribution of the stars. α_{rot} dictates the percentage of kinetic energy that is in ordered rotation, as opposed to random isotropic velocity dispersion. α_{law} dictates the rotation law: solid-body (equation [8,](#page-3-0) SOL) or Keplerian (equation [9,](#page-3-0) KEP). α_{seg} determines whether the subcluster is mass-segregated at the outset. The order in which these parameters are invoked, when setting up the initial conditions, is dictated by computational considerations.

If $\alpha_{\text{seg}} = 1$, the stars are segregated by mass. In other words, the masses and positions are matched so that, for any pair of stars with IDs *n* and *n'*, if $M_n < M_{n'}$, then $r_n > r_{n'}$. Otherwise $\alpha_{\text{seg}} = 0$ and the masses and positions are matched randomly. Once the masses and

Table 1. Parameters and symbols.

²Lower values of σ_ℓ result in too few binaries with low mass ratios, *q*. Higher values result in an IMF that is too much broader than the CMF.

positions are matched, the centre of the Cartesian coordinate system is shifted to the centre of mass, and the initial self-gravitational potential energy,

$$
\Omega = -G \sum_{n=1}^{n=N-1} \sum_{n'=n+1}^{n'=N} \left\{ \frac{M_n M_{n'}}{|\mathbf{r}_n - \mathbf{r}_{n'}|} \right\},\tag{7}
$$

is computed.

At this juncture, the stars are given random isotropic velocities, v_{iso} , drawn from a Maxwellian distribution with zero mean and standard deviation $\sigma_{\text{iso}} = \{ [1 - \alpha_{\text{rot}}] \Omega / 6M_{\text{tot}} \}^{1/2}$, where M_{tot} is the total mass of the subcluster. These velocities are then shifted to the centreof-mass frame, and renormalized so that the total kinetic energy invested in isotropic velocity dispersion is correct.

If $\alpha_{\text{rot}} > 0$, the stars are also given ordered rotation velocities, v_{rot} . If $\alpha_{\text{law}} =$ SOL the rotation is solid-body, with moment of inertia about the *z*-axis, angular speed about the *z*-axis, and velocity given respectively by

$$
I_z = \sum_{n=1}^{n=N} \{M_n | \hat{\boldsymbol{e}}_z \wedge \boldsymbol{r}_n |^2\},
$$

\n
$$
\omega = [\alpha_{\text{rot}} \Omega / I_z]^{1/2},
$$

\n
$$
\boldsymbol{v}_{\text{rot}:n} = \omega \hat{\boldsymbol{e}}_z \wedge \boldsymbol{r}_n,
$$

\n
$$
(8)
$$

here, $\hat{\mathbf{e}}_z$ is the unit vector parallel to the *z*-axis and ∧ denotes a vector product. Alternatively, if $\alpha_{\text{law}} = \text{KEP}$ the rotation is Keplerian, with gravitational potential relative to the *z*-axis, Kepler coefficient, and velocity given respectively by

$$
I'_{z} = \sum_{n=1}^{n=N} \{M_{n} | \hat{\boldsymbol{e}}_{z} \wedge \boldsymbol{r}_{n} |^{-1} \},
$$

\n
$$
\kappa = \left[\alpha_{\text{rot}} \Omega / I'_{z} \right]^{1/2},
$$

\n
$$
\boldsymbol{v}_{\text{rot}:n} = \kappa | \hat{\boldsymbol{e}}_{z} \wedge \boldsymbol{r}_{n} |^{-3/2} \hat{\boldsymbol{e}}_{z} \wedge \boldsymbol{r}_{n},
$$

\n(9)

The net velocities of the stars,

$$
\mathbf{v}_n = \mathbf{v}_{\text{iso}:n} + \mathbf{v}_{\text{rot}:n},\tag{10}
$$

are then computed and shifted (again) to the centre-of-mass frame. Finally, the initial total kinetic energy,

$$
E_{\rm kin} = \sum_{n=1}^{n=N} \left\{ \frac{M_n |v_n|^2}{2} \right\} \tag{11}
$$

is computed, and the velocities are re-scaled to ensure that the subcluster is virialized,

$$
\mathbf{v}_n \longleftarrow \mathbf{v}_n \ \left[-\Omega/2E_{\text{kin}} \right]^{1/2} \ . \tag{12}
$$

We invoke an initially virialized subcluster for two reasons. First, the time-scale on which the subcluster approaches virial equilibrium is likely to be short, compared with the time-scale on which the multiplicity statistics stabilize. Secondly, this reduces the number of free parameters we need to explore.

We introduce the shorthand

$$
\mathcal{C} \equiv [\sigma_{\ell}, \, \alpha_{\text{rot}}, \, \alpha_{\text{law}}, \, \alpha_{\text{seg}}] \tag{13}
$$

to represent a specific set of configuration parameters. Apart from *and* $*C*$ *, the only other variables that distinguish one experiment* from another are the random-number seeds used to generate different realizations of the same *N* and same set of configuration parameters, C.

2.2 Evolving subclusters

Subclusters are evolved using a fourth-order Runge–Kutta integration scheme with an adaptive time-step,

$$
\Delta t = \gamma \text{ MIN} \left\{ \frac{|\mathbf{r}_n - \mathbf{r}_{n'}|}{|\mathbf{v}_n - \mathbf{v}_{n'}|}, \frac{|\mathbf{v}_n - \mathbf{v}_{n'}|}{|\mathbf{a}_n - \mathbf{a}_{n'}|} \right\}_{n \neq n'}.
$$
 (14)

Here, γ is a user-specified parameter determining the accuracy of the integration, a_n is the acceleration of star *n*, and the minimum is over all possible pairs of stars. This formulation ensures that no two stars change their relative position or relative velocity by more than a fraction $\sim \gamma$ in one time-step. The numerical experiments presented in the sequel have been performed with $\gamma = 0.1$.

Each initial system is integrated for a maximum of 1000 crossing times (\sim 70 Myr $N^{-1/2}$), unless all the existing systems become unbound from one another, in which case the integration isterminated in order to save computer time (see Section 2.4). Conservation of linear momentum, angular momentum, and energy is monitored throughout the evolution.

2.3 Identifying multiple systems

At regular intervals, Δt_{MMO} , during the cluster evolution, we identify multiple systems using a multiplicity monitoring operation, hereafter MMO. The MMO selects a random pair of stars in the subcluster. If the stars in this pair [1] are mutual nearest neighbours and [2] have negative energy in their mutual centre of mass frame, they are identified as bound. For the purposes of the MMO, the bound pair is then treated as a single object with the properties (mass, position, and velocity) of its centre of mass. This object is added to the pairing procedure, and its individual constituent stars are removed from consideration for the purpose of this implementation of the MMO. Conversely, if the pair do not meet both criteria [1] and [2], they remain as individual stars, and the MMO checks a different possible pairing. This continues recursively until the full inventory of multiple systems in the subcluster has been determined.

For each identified bound system – including higher-order multiples – the procedure calculates the orbital parameters: semimajor axis (*a*), orbital period (*P*), eccentricity (*e*), and angular momentum vector (which gives the orbital inclination \hat{k}). The MMO is implemented every 33 crossing times (\sim 2.3 Myr $N^{-1/2}$, or \sim 1 Myr for $N = 4$ or 5). Note that, after an MMO implementation, the integration procedure continues to follow all stars as individuals.

2.4 Unbound stars and the stopping condition

During the evolution, a star or system may become unbound from the rest of the subcluster. It is then no longer necessary to track its position, and it is removed from further evolution of the subcluster (and from subsequent MMO implementations). However, during periods of frequent close encounters two stars that are actually bound to one another may not meet condition [1] (i.e. may briefly not be mutual nearest neighbours). This only occurs occasionally, and only ever in the very early lifetime of a subcluster when the dynamics is very chaotic. To avoid inadvertently removing bound stars or systems from the evolution, stars and systems are only removed after the first 200 crossing times, and only if those stars or systems have remained unbound for two consecutive MMOs.

If the MMO finds that the subcluster consists entirely of singles and binaries that are unbound from one another, no further dynamical change can take place and the evolution is halted.

Table 2. The configurations evaluated, and the quality and parameters of the best fit. Column 1, configuration ID; columns 2 through 4, the amount of rotation, the rotation law, and whether there is mass segregation; columns 5 and 6, the *N*-distribution parameters, $(N_D, \Delta N_D)$; columns 7 and 8, the mean and standard deviation of the *N*-distribution; column 9, the quality of the best fit (small for a good fit); columns 10 through 13, the percentages of singles, S, binaries, B, triples, T, and quadruples plus higher orders, Q^+ ; column 14, the total number of systems produced; columns 15 through 18, the multiplicity fraction (MF, equation [23\)](#page-6-0), the triple and higher-order fraction (f_{T+} , equation [5\)](#page-1-0), the companion fraction (CF, equation [24\)](#page-7-0), and the plurality (PL, equation [25\)](#page-7-0). Row 1, the parameter symbols; row 2, the observed statistics from the T21 sample (Tokovinin [2021\)](#page-9-0); rows 3 through 5, the results from Sterzik & Durisen [\(1998\)](#page-9-0) for subclusters with a single $N = 3, 4$, and 5; rows 6 through 10, the results from this work for subclusters with a single $N = 3, 4, 5, 6$, and 7; row 11, the fiducial case (no rotation, no segregation); rows 12 through 15, the solid-body rotation cases; rows 16 and 17, the Keplerian rotation cases; rows 18 through 22, the mass-segregated cases (including the best-fitting case, SEG4).

\mathcal{C}	$\alpha_{\rm rot}$	α_{law}	$\alpha_{\rm seg}$	$N_{\mathcal{D}}$	$\Delta N_{\mathcal{D}}$	μ_{D}	σ_D	$\mathcal{Q}_{\mathcal{CD}}$	S	B	T	Q^+	Sys	MF	$f_{\text{T}}+$	CF	PL
T ₂₁	$\overline{0}$								54	29	12	5		0.46	0.17	0.68	1.13
SD ₃	$\overline{0}$	$\overline{}$	$\mathbf{0}$	3	$\overline{0}$				46.8	46.8	5.5	$\mathbf{0}$	1878	0.53	0.06	0.59	0.82
SD ₄	$\overline{0}$	$\overline{}$	$\mathbf{0}$	4	$\overline{0}$				62.7	29.1	6.0	1.1	2713	0.36	0.07	0.44	0.74
SD ₅	$\overline{0}$	$\overline{}$	$\mathbf{0}$	5	$\overline{0}$				70.1	18.9	9.0	0.9	3475	0.29	0.10	0.40	0.75
$N = 3$	θ	-	Ω	3	Ω	3	Ω	1.71	47.3	47.3	5.45	$\overline{0}$	1614	0.53	0.05	0.58	0.80
$N = 4$	$\overline{0}$	-	$\mathbf{0}$	4	Ω	4	$\mathbf{0}$	0.77	60.2	29.3	9.85	0.73	2194	0.40	0.11	0.51	0.84
$N=5$	Ω	$\overline{}$	Ω	5	Ω	5	Ω	0.65	68.1	19.8	10.5	1.61	2798	0.32	0.12	0.46	0.84
$N=6$	$\overline{0}$	-	$\mathbf{0}$	6	$\overline{0}$	6	$\mathbf{0}$	0.84	74.8	14.3	8.84	1.96	4377	0.25	0.11	0.38	0.76
$N=7$	$\overline{0}$		$\mathbf{0}$	7	$\overline{0}$	7	$\overline{0}$	1.06	78.7	11.7	7.62	2.00	5290	0.21	0.10	0.33	0.70
FID	θ	$\overline{}$	$\mathbf{0}$	4.9	1.0	4.8	0.1	0.64	67.1	21.0	10.4	1.49	16273	0.33	0.12	0.46	0.84
SOL1	0.25	SOL	Ω	5.0	1.0	5.0	0.0	0.57	66.2	21.7	10.4	1.7	17104	0.34	0.12	0.48	0.86
SOL ₂	0.50	SOL	$\overline{0}$	4.3	3.3	4.4	2.1	0.41	62.6	24.3	11.1	2.0	16599	0.37	0.13	0.53	0.91
SOL3	0.75	SOL	$\overline{0}$	4.4	3.4	4.4	2.2	0.49	63.8	23.1	11.3	1.78	16714	0.36	0.13	0.51	0.90
SOL4	0.99	SOL	$\overline{0}$	4.9	1.0	4.8	0.1	1.26	70.3	23.7	5.65	0.38	17829	0.30	0.06	0.36	0.63
KEP1	0.50	KEP	$\overline{0}$	4.4	3.4	4.4	2.2	0.42	63.5	23.6	10.8	2.08	16715	0.36	0.13	0.51	0.90
KEP ₂	0.99	KEP	Ω	5.0	1.0	5.0	0.0	1.22	71.2	21.8	6.57	0.38	17992	0.29	0.07	0.36	0.64
SEG1	$\overline{0}$			5.0	1.0	5.0	0.0	0.63	67.1	20.6	10.8	1.53	16590	0.33	0.12	0.47	0.85
SEG ₂	0.50	SOL		5.3	1.6	5.2	0.5	0.43	66.1	21.0	10.6	2.29	16574	0.34	0.13	0.49	0.89
SEG ₃	0.99	SOL		4.6	1.1	4.6	0.2	1.38	69.5	25.9	4.31	0.33	17869	0.31	0.05	0.36	0.60
SEG4	0.50	KEP		5.4	4.4	4.8	2.4	0.35	63.2	24.1	10.3	2.41	16339	0.27	0.13	0.52	0.91
SEG5	0.99	KEP		4.8	1.0	4.7	0.2	1.33	69.9	25.1	4.59	0.41	17995	0.30	0.05	0.36	0.61

2.5 Comparison with observations

For each set of configuration parameters, C, and number of stars, *N*, we evolve 1000 different realizations and compute the mean number of systems with multiplicity *m* formed per realization, S_{CNm} . We do this for all *N* in $3 \le N \le 7$, for each set of configuration parameters, C, as listed in Table 2, and for all *m* in $1 \le m \le m_{\text{max}} = 4^+$. Because the numbers of quintuples, sextuples, and septuples are small (both in the numerical experiments, and in the observations), they are simply added to the quadruples to give $S_{C N 4^+}$.

To fit the observations, we assume that the probability that a core spawns a subcluster of *N* stars is given by the distribution function

$$
\mathcal{P}_{\mathcal{D}N} = \eta_{\mathcal{D}} \text{MAX}\left(\left\{\Delta N_{\mathcal{D}}^2 - \left[N - N_{\mathcal{D}}\right]^2\right\},\ 0\right),\tag{15}
$$

$$
\eta_{\mathcal{D}} = \Big/ \sum_{N=1}^{N=7} \text{MAX} \left(\left\{ \Delta N_{\mathcal{D}}^2 - \left[N - N_{\mathcal{D}} \right]^2 \right\}, 0 \right), \tag{16}
$$

where $\eta_{\mathcal{D}}$ is a normalization coefficient. Because *N* is not a continuous variable, N_{τ} regulates, but is not exactly, the mean of the *N* distribution; and ΔN_{D} regulates, but is not exactly, the standard deviation of the *N* distribution. The true mean and standard deviation are given by

$$
\mu_{\mathcal{D}} = \sum_{N=1}^{N=7} \{ \mathcal{P}_{\mathcal{D}N} N \}, \qquad (17)
$$

$$
\sigma_{\mathcal{D}}^2 + \mu_{\mathcal{D}}^2 = \sum_{N=1}^{N=7} \left\{ \mathcal{P}_{\mathcal{D}N} N^2 \right\}.
$$
 (18)

The subscript $\mathcal D$ in equations (15) through (18) represents the parameters of the distribution function, i.e.

$$
\mathcal{D} \equiv \left[N_{\mathcal{D}}, \ \Delta N_{\mathcal{D}} \right],\tag{19}
$$

hereafter the *N*-distribution.

The frequency with which a subcluster having configuration parameters C and N -distribution D spawns a multiple system of the order of *m* is

$$
f_{c_{\mathcal{D}m}} = \sum_{N=1}^{N=7} \{ \mathcal{P}_{_{\mathcal{D}N}} \mathcal{S}_{c_{Nm}} \}.
$$
 (20)

Therefore, if the observed number of systems with multiplicity *m* is \mathcal{O}_m , the predicted number is

$$
\mathcal{N}_{c_{\mathcal{D}m}} = f_{c_{\mathcal{D}m}} \sum_{m=1}^{m=4^+} \{ \mathcal{O}_m \} / \sum_{m=1}^{m=4^+} \{ f_{c_{\mathcal{D}m}} \}, \qquad (21)
$$

and the quality of fit for this combination of configuration parameters, C, and *N*-distribution, D, is given by

$$
\mathcal{Q}_{CD} = \sum_{m=1}^{m=4^+} \left\{ \frac{[\mathcal{N}_{CDm} - \mathcal{O}_m]^2}{\mathcal{O}_m^2} \right\}.
$$
 (22)

A lower value of \mathcal{Q}_{CD} represents a better fit.

3 RESULTS AND DISCUSSION

Our numerical experiments suggest that most cores spawn four or five stars. There are cores that spawn three stars, but if they

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Figure 1. Multiplicity distributions for subclusters with $N = 3, 4, 5, 6$, and 7. For each *N*-value, we have evolved 1000 different realizations with the fiducial configuration parameters ($\alpha_{\text{rot}} = 0$, $\alpha_{\text{seg}} = 0$). The dashed line represents the T21 sample. Error bars represent the 3*σ* statistical variance.

were the norm they would produce too many binaries and too few singles, while contributing no quadruples or higher-order systems. Conversely, there are cores that spawn more than five stars, but if they were the norm they would produce too many singles and too few binaries. Although such high-*N* cores are essential to produce the high-order systems, our pure *N*-body model does not produce as many high-order systems as are observed; we find that increasing *N* is more effective at overproducing singles than it is at producing stable higher-order multiples. In Section [4,](#page-9-0) we suggest that forming the observed number of high-order systems probably requires the inclusion of additional physics such as disc drag and disc fragmentation, since this will deliver compact, tightly bound companions that can survive all but the closest interactions with other stars.

3.1 A universal *N* **value**

It is informative to consider the possibility that all cores spawn the same number of stars, i.e. a universal *N* value, although a universal *N* is extremely unlikely. For these experiments, we use the fiducial parameters, i.e. no rotation and no mass-segregation.

An initially bound subcluster with $N=3$ stars has $A_3 = 2$ possible end states: (i) a triple system, or (ii) a binary and a single star. Because the dissolution of a three-star subcluster into a binary and a single is the only way for a binary or a single star to form from such a subcluster, the percentages of single and binary systems must be equal in this case. For the fiducial case, in which the initial subcluster has no ordered rotation or mass segregation, ∼ 90 per cent of threestar subclusters decay into a binary and a single, giving percentages of S:B:T: $Q^+ = 47:47:6:0$, exactly as obtained by Sterzik & Durisen [\(1998\)](#page-9-0).

An initially bound subcluster with $N=4$ stars has $A_4 = 4$ possible end states: (i) a quadruple; (ii) a triple and a single star; (iii) two separate binaries; or (iv) a binary and two single stars. For the fiducial case, $N = 4$ gives $S: B: T: Q^+ = 60:29:10:7$. We note that higher-order multiples may come in different variants. For example, there are $2 + 2$ ' quadruples and planetary quadruples.

Of the quadruple systems produced in the $N=4$ fiductial, $25(\pm 14)$ per cent are '2 + 2' systems and the remainder are planetary. In contrast, in the Tokovinin [2014](#page-9-0) sample ∼ 75 per cent of quadruples are $2 + 2$ ' systems. There are two possible explanations for this discrepancy. First, it is probably easier to detect $2 + 2$ quadruples spectroscopically, in which case they are overrepresented in the observational sample. Secondly, it may be that additional physics that is missing from our numerical experiments – for example, circumstellar accretion discs and disc fragmentation – increases the percentage of $2 + 2$ ' quadruples.

The number of distinguishable end states increases monotonically with *N*. Five-star subclusters have $A_5 = 6$ possible end states, and six-star subclusters have $A_6 = 10$ possible end states. For the fiducial case, $N = 5$ gives $S: B:T:Q^+ = 68:20:10:2$, with 24(± 8) per cent of Q^+ systems composed wholly, or in part, of '2 + 2' configurations; and *N* = 6 gives *S*:*B*:*T*: Q^+ = 75:14:9:2, with 24(\pm 6) per cent of Q^+ systems containing $2 + 2$ configurations.

An initially bound subcluster with $N=7$ stars has $A_7 = 14$ possible end states: (i) a septuple; (ii) a sextuple and a single star, (iii) a quintuple and a binary, (iv) a quintuple and two singles, (v) a quadruple and a triple, (vi) a quadruple, a binary, and a single, (vii) a quadruple and three singles, (viii) two triples and a single, (ix) a triple and two binaries, (x) a triple, a binary, and two singles, (xi) a triple and four singles, (xii) three binaries and a single, (xiii) two binaries and three singles, and (xiv) a binary and five singles. Given the rapid increase in the number of end states with increasing *N* (see equation [1](#page-0-0) and Appendix [A\)](#page-10-0), we limit consideration to $N \le 7$. For the fiducial case, $N=7$ gives $S:B:T:Q^+ = 79:12:8:2$, with $19(\pm 5)$ per cent of Q^+ systems containing '2 + 2' configurations.

Fig. 1 displays the multiplicity distributions for the fiducial case with different values of *N*. The results for $N = 4$ most accurately match the T21 sample, but no value reproduces exactly the observed multiplicities. Increasing *N* does increase the probability of forming higher-order multiples. Indeed, a system with multiplicity $m \geq 3$ can only form if $N > m$. However, this effect is small, and the main effect of increasing N is to increase the percentage of singles at the expense of binaries. These singles are mainly lower-mass stars that have been ejected by the sling-shot mechanism.

For subclusters with a universal *N* value, the multiplicity statistics can be changed quite significantly by introducing rotation. Fig. [2](#page-6-0) shows the effect of different amounts of rotation for subclusters with $N = 4$

Figure 2. Multiplicity distributions for subclusters with $N = 4$, $\alpha_{\text{seg}} = 1$, and different values of $\alpha_{\text{rot}} = 0$, 0.25, 0.5, 0.75, and 0.99. For each α_{rot} value, we have evolved 1000 different realizations. Error bars represent the 3*σ* statistical variance.

3.2 A distribution of *N* **values**

It is unlikely that every prestellar core produces the same number of stars. Therefore, we now consider *N*-distributions, and identify the combinations of configuration parameters, C , and N -distribution, D, that best fit the observations. The *N*-distributions are given by equation [\(15\)](#page-4-0), and we test all combinations of $N_{\text{D}} = 1.0, 1.1, 1.2$, 1.3, ... 6.8, 6.9, 7.0, and $\Delta N_{\text{D}} = 1.0, 1.1, 1.2, 1.3, ...$ 6.8, 6.9, 7.0.

Table 2 lists all the tested configurations C ; for each configuration, the parameters of the *N*-distribution giving the best fit to the T21 sample; and – where they exist – the corresponding parameters from Sterzik & Durisen [\(1998\)](#page-9-0).

3.2.1 The notional absolute-best fit

The notional absolute-best fit is obtained with configuration $C =$ SEG4 ($\alpha_{\text{rot}} = 0.5$, $\alpha_{\text{law}} = \text{KEP}$, $\alpha_{\text{seg}} = 1$) and an *N*-distribution with $(N_{\text{D}}^{\text{}}\, \Delta N_{\text{D}}^{\text{}}) \simeq (5.4, 4.4)$ (corresponding to mean $\mu_{\text{D}}^{\text{}} \simeq 4.8$, and standard deviation $\sigma_p \simeq 2.4$). This delivers percentages *S*:*B*:*T*: $Q^+ = 63$: 24 : 10 : 2.4, with quality factor $Q_{CD} = 0.35$ and 41(\pm 5) per cent of Q^+ systems containing '2 + 2' orbits.

3.2.2 How critical is the N-distribution?

Fig. [3](#page-7-0) is a map of the quality factor, $\mathcal{Q}_{c,D}$, for configuration $\mathcal{C} =$ SEG4 over the full range of *N*-distribution parameters, $(N_{\tau}, \Delta N_{\tau})$. There are two regions of low \mathcal{Q}_{CD} (i.e. good fits, represented by white on Fig. [3\)](#page-7-0). One is centred on the best fit $(N_{\text{D}}^{\text{D}}, \Delta N_{\text{D}}^{\text{D}}) \simeq (5.4, 4.4)$ with an extension to higher and lower values of N_{D} and ΔN_{D} . The other, slightly less-favoured region, is centred on $(N_{\mathcal{D}}, \Delta N_{\mathcal{D}}) \simeq (5.5, 1)$.

Fig. [4](#page-7-0) compares the multiplicities corresponding to the absolutebest fit (black line) and the 50 next-best fits (i.e. SEG4 with slightly different *N*-distributions; cyan shading). These fits correspond to the whitest region on Fig. [3](#page-7-0) (specifically, an area that is ∼1*.*4 per cent of the total area of Fig. [3\)](#page-7-0). They all fall within one standard deviation of the absolute-best fit, so the parameters of the *N*-distribution giving the absolute-best fit are not highly critical.

Notably, but unsurprisingly, a prestellar core producing exactly two stars results in the worst fit, since it only produces binary systems. The corresponding black point in Fig. [3](#page-7-0) is only just visible next to the abscissa.

3.2.3 Which are the critical configuration parameters?

Table [3](#page-7-0) lists the five configurations that produce fits with, $Q_{CD} < 0.5$. Fig. [5](#page-8-0) shows the quality factor, \mathcal{Q}_{CD} , for the four additional configurations and the full range of *N*-distribution parameters, $(N_{\mathcal{D}}, \Delta N_{\mathcal{D}})$. Panels (a) SOL2, (b) SOL3, and (c) KEP1 in Fig. [5](#page-8-0) are very similar to one another, with a single region of high quality, centred on $(N_{\text{D}}$, $\Delta N_{\text{D}}) \simeq (4.4, 3.4)$. Panel (d) SEG2 is more like SEG4 (Fig. [3\)](#page-7-0), with two regions, but the preferred region is now the lower one centred on $(N_{\text{D}}$, $\Delta N_{\text{D}})$ = (5.3, 1.6).

All five configurations involve rotation, four with 50 per cent of the kinetic energy invested in rotation, and one with 75 per cent. We conclude that having comparable amounts of energy in rotation and in random isotropic motions is a critical requirement for producing a good fit.

In contrast, three of the top-five configurations have solid-body rotation, while two have Keplerian rotation. We conclude that the details of the rotation (the rotation law) are not critical. Similarly, three of the top-five configurations have no mass segregation, and two of them do. Therefore, it appears that mass segregation is also not a critical requirement for a good fit.

The mass segregation does appear to have an affect upon the formation of '2 + 2' systems. While the percentage of '2 + 2's is similar for the best-fitting cases with no segregation ($\alpha_{\text{seg}} = 0$), those that begin with segregated masses ($\alpha_{seg} = 1$) have a much higher percentage of $2 + 2$'s (Table [3\)](#page-7-0).

3.3 Metrics of overall multiplicity

Various metrics of overall multiplicity have been proposed, in particular the *multiplicity fraction* (i.e. the fraction of systems that are not single),

$$
MF = \frac{B + T + Q + ...}{S + B + T + Q + ...};
$$
\n(23)

Figure 3. Map of the quality factor, Q_{CD} , for the best-fitting configuration parameters ($\alpha_{rot} = 0.50$, $\alpha_{law} = \text{KEP}$, $\alpha_{seg} = 1$) and the full range of *N*-distribution parameters (1.0 $\leq N_D \leq 7.0$ and 1.0 $\leq \Delta N_D \leq 7.0$). The map encodes $\log_{10}(Q_{CD})$, with the best fit lightest and the worst fit ($N_D = 2$ and $\Delta N_D = 1$) darkest.

Figure 4. Multiplicity distributions. The blue dashed curve represents the T21 sample. The black full line represents the absolute-best-fitting combination of configuration parameters and *N*-distribution parameters (i.e. SEG4, one from bottom row in Table [2\)](#page-4-0). The surrounding shaded region represents fits for the same configuration parameters and the 50 next-best-fits with different *N*-distribution parameters (corresponding to the lightest region in Fig. 3).

Table 3. The parameters of the five best fits, i.e. those with quality factor, \mathcal{Q}_{CD} < 0.5. Reading left to right, the columns give the configuration name, the parameters of the configuration (*α*rot, *α*law, *α*seg), the mean and standard deviation of the distribution of *N* values ($\mu_{\mathcal{D}}$, $\sigma_{\mathcal{D}}$), the quality factor (\mathcal{Q}_{CD}), and the percentage of Q^+ systems that contain '2 + 2' orbits.

C	$\alpha_{\rm rot}$	α_{law}	α_{seg}	μ_{τ}	σ_{τ}	$\mathcal{Q}_{c,n}$	$2 + 2$
SOL ₂	0.50	SOL	0	4.4	2.1	0.41	$25(\pm 06)$
SOL3	0.75	SOL	0	4.4	2.2	0.49	$26(\pm 06)$
KEP1	0.50	KEP	0	4.4	2.2	0.42	$28(\pm 05)$
SEG ₂	0.50	SOL		5.2	0.5	0.43	$44(\pm 07)$
SEG ₄	0.50	KEP		4.8	2.4	0.35	$41(\pm 05)$

the *triple/higher-order fraction* (i.e. the fraction of systems that are triple or higher-order, see equation [5\)](#page-1-0); the *companion fraction* (i.e. the mean number of companions per primary),

$$
CF = \frac{B + 2T + 3Q + \dots}{S + B + T + Q + \dots};
$$
\n(24)

and the *plurality* (i.e. the mean number of companions per star, irrespective of whether it is a primary star),

$$
PL = \frac{2B + 6T + 12Q + \dots}{S + 2B + 3T + 4Q + \dots}.
$$
\n(25)

These metrics are given in the last four columns of Table [2.](#page-4-0) The last one, PL, has the merit that it has a clear physical meaning and

Figure 5. As Fig. [3,](#page-7-0) but for the configuration parameters giving the second through fifth best fits (i.e. the other fits with $Q_{CD} < 0.50$): (a) SOL2 with $Q_{CD} = 0.41$; (b) SOL3 with $Q_{CD} = 0.49$; (c) KEP1 with $Q_{CD} = 0.42$; and (d) SEG2 with $Q_{CD} = 0.43$.

reflects, more strongly than the others, the percentage of higher-order multiples. CF and PL can both be greater than one. Indeed, for the T21 sample, $PL = 1.13$.

3.4 Caveats

3.4.1 Pure N-body dynamics

The numerical experiments reported here involve pure *N*-body dynamics. Consequently – modullo numerical errors – the resulting multiplicities are determined solely by the initial conditions and gravitational interactions between point masses. Phenomena such as dissipation from the cloud or disc, which harden systems against dissolution and act to increase stellar multiplicity, are not considered. We expect the pure *N*-body results of this work to represent a conservative (i.e. low) estimate of the multiplicity which can be achieved from a subcluster of *N* stars.

3.4.2 Isolated subclusters

Each subcluster is evolved in isolation. The subcluster cannot capture outside stars, nor can it be perturbed by stellar flybys. For low-*N* subclusters, capture might increase the multiplicity metrics (e.g. MF, CF, and PL), but for high-*N* subclusters it would probably reduce the multiplicity metrics. Perturbations by stellar flybys would be likely to reduce the multiplicity metrics, for example by disrupting hierarchical triples.

3.4.3 Duration of integration

Subclusters are evolved for a maximum of 1000 crossing times. In practice, most of the final multiple systems are established early in the evolution, within the first 200 crossing times. For the $N = 7$ case, whose systems take the longest to settle into their end states, more than 80 per cent of instantiations achieve their final $1000 t_{\text{cross}}$ multiplicities by 200 t_{cross} , and more than 95 per cent by 600 t_{cross} .

3.4.4 Limited number of stars in subcluster

We do not consider subclusters with $N > 7$. As we increase N , the multiplicity distribution changes at a decreasing rate (see Fig. [1\)](#page-5-0): the percentages of binaries and triples decrease slightly, the percentage of singles increases, and the percentages of higherorder multiples $(m \ge 4)$ increase imperceptibly. For example, in the fiducial case, the multiplicity distributions for $N = 6$ and 7 agree within their 3σ uncertainties (Fig. [1\)](#page-5-0). This is true for all configurations tested. We expect multiplicities for values of $N > 7$ to follow this trend, remaining very similar to the multiplicity values for $N = 7$.

In addition, the complexity of possible end states increases dramatically with *N* (see Appendix [A\)](#page-10-0), making higher-*N* numerical experiments prohibitive from a book-keeping standpoint.

3.4.5 Observational statistics

The T21 observational statistics are probably influenced by selection effects. The likelihood is that, as new and improved techniques and strategies are developed, the multiplicities of the systems in the T21 sample will change, and there will probably be an increase in the proportion of higher-order systems. As the completeness of multiplicity surveysimproves, the analysis presented in this work can easily be reapplied to updated observational statistics. However, the inability of our pure *N*-body model to produce enough higher-order systems is likely to remain a limitation.

4 CONCLUSION

We have used *N*-body numerical experiments to determine the multiplicity statistics that result from small-*N* subclusters of stars that interact only through their mutual gravity. These statistics have then been compared with the T21 sample of nearby systems with solarmass primaries (Tokovinin 2021). The subclusters are presumed to be the product of collapse and fragmentation in a single isolated prestellar core.

To produce an acceptable fit to the observed statistics, prestellar cores must – on average – spawn between 4.3 and 5.2 stars. This seems to be a rather compelling conclusion, in the sense that first it produces by far the best fit to the observations, and secondly a very similar conclusion has been drawn by two other, completely independent studies, *viz*. [1] Holman et al. (2013) using statistical arguments, and [2] Lomax, Whitworth & Hubber (2015) using smoothed particle hydrodynamic simulations. We stress that neither [1] nor [2] involves *N*-body numerical experiments, and they are therefore totally independent of the results reported here.

In the numerical experiments reported in this work, subclusters which begin with roughly half their kinetic energy invested in rotation produce the best fits to the T21 sample. Furthermore, there is a broad range of set-ups that produce very similar fits, but they all have roughly half their kinetic energy invested in rotation. These set-ups do occasionally spawn fewer than four stars, or more than five, but this is relatively rare. The multiplicity statistics appear to be independent of whether the subcluster starts with a solid-body or Keplerian rotation law, and of whether the masses are initially segregated. The orbital statistics of the systems formed in this paper will be presented in a companion paper.

Although the overall fits obtained here are quite good, there are always too few systems with multiplicity $m \geq 4$. We believe that this is because our stars do not have circumstellar discs. Such discs will make close encounters between stars dissipative, thereby increasing the formation of tight orbits and higher-order multiples. Such discs may also fragment to form close companions, some of which will survive interactions with other stars in the subcluster, and again this will promote the formation of higher-order multiples. This refinement will be explored in a future paper.

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DATA AVA IL AB IL IT Y

The data underlying this article will be shared on reasonable request to the corresponding authors.

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APPENDIX A : ENUMERATING END STATES

An initially virialized subcluster of $N > 2$ stars must produce at least one bound multiple system. This component contains *n* stars, where $2 < n \leq N$, and we can assume without loss of generality that *n* is the largest or equal-largest multiplicity of the end state. In the case where this component is the only multiple, all remaining $N - n$ stars are single.

The remaining *N* −*n* stars may also form bound systems. These systems may have any multiplicity *n'*, where $2 < n' \le n$. The number of additional component systems of multiplicity n' for an existing component of multiplicity *n* is given by the number of times n' may be divided wholly into the number of remaining stars. So, end states containing a component system of multiplicity *n* and a component system (or systems) of multiplicity n' are counted with the following equation:

$$
\mathcal{A}_{N\leq 7} = \sum_{n=2}^{N} \left\{ 1 + \sum_{n'=2}^{n} \left\lfloor \frac{N-n}{n'} \right\rfloor \right\}.
$$
 (A1)

This equation will count all possible end states for initially virialized subclusters with $2 < N < 7$.

For $7 < N \leq 10$, it is possible to achieve end states with component systems of multiplicity *n*, *n'*, and *n''*, where $n'' < n'$, i.e. $N = 8$ may end in two separate triples and a binary, $N = 10$ may result in a quadruple, a triple, and a binary. To count these states, we must add an additional level of recursion. For each set of n, n' , there are *N* − (*n* + *n*^{\prime}) remaining stars. If *N* − (*n* + *n*^{\prime}) > 2, the stars may

form a multiple of the order of $2 \le n'' < n'$. $n'' = n'$ systems are counted in the previous sum. The number of components of order *n* is then given by

$$
n_{n''} = \left\lfloor \frac{N - (n + n')}{n''} \right\rfloor \tag{A2}
$$

and the full sum becomes equation [\(1\)](#page-0-0),

$$
\mathcal{A}_N = \sum_{n=2}^N \left\{ 1 + \sum_{n'=2}^n \left\{ \left\lfloor \frac{N-n}{n'} \right\rfloor + H(N - (n + n' + 2)) \right\} \times \sum_{n''=2}^{n'-1} \left\lfloor \frac{N - (n + n')}{n''} \right\rfloor \right\}.
$$

where *H* represents the Heaviside function, i.e.

$$
H(h) = \begin{cases} 1, & \text{if } h \ge 0; \\ 0, & \text{if } h < 0. \end{cases} \tag{A3}
$$

The sum gives the multiplicity of each end component, and differentiates components only on multiplicity, not on the type of system (e.g. there is no discrimination between a quadruple which is planetary versus one which is a $2 + 2$) or on which specific stars occupy which remnant system. Further terms may be added to count end states of $N < 10$.

APPENDIX B: SCALING RELATIONS

The numerical experiments described in the paper are strictly speaking dimensionless, and have only been scaled to $M_{\text{med}} =$ $0.25 M_{\odot}$ ($\mu_{\nu} = -0.6$) and $R = 10^3$ au for the purpose of illustration. To scale a given experiment to a subcluster with a different total mass, M'_{tot} , and/or a different radius, R' , we must multiply all stellar and system masses by $f_M = M'_{\text{tot}}/M_{\text{TOT}}$; all position vectors and orbital axes by $f_R = R'/R$; the time and all orbital periods by $[f_R^3/f_M]^{1/2}$; and all velocities by $[f_M/f_R]^{1/2}$. Orbital eccentricities and inclinations are unchanged.

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