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Kinematic Analysis of z = 4.3 Galaxies in the SPT2349-56 Protocluster Core

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Abstract

SPT2349–56 is a protocluster discovered in the 2500 deg² South Pole Telescope (SPT) survey. In this paper, we study the kinematics of the galaxies found in the core of SPT2349–56 using high-resolution (1.55 kpc spatial resolution at z=4.303) redshifted [C II] 158 μ m data. Using the publicly available code ^{3D}BAROLO, we analyze the seven far-infrared brightest galaxies within the protocluster core. Based on conventional definitions for the detection of rotating disks, we classify six sources to be rotating disks in an actively star-forming protocluster environment, with weighted mean $V_{\rm rot}/\sigma_{\rm disp}=4.5\pm1.3$. The weighted mean rotation velocity ($V_{\rm rot}$) and velocity dispersion ($\sigma_{\rm disp}$) for the sample are 357.1 \pm 114.7 km s⁻¹ and 43.5 \pm 23.5 km s⁻¹, respectively. We also assess the disk stability of the galaxies and find a mean Toomre parameter of $Q_{\rm T}=0.9\pm0.3$. The galaxies show a mild positive correlation between disk stability and dynamical support. Using the position–velocity maps, we find that five sources further classify as disturbed disks, and one classifies as a strictly rotating disk. Our sample joins several observations at similar redshift with high V/σ values, with the exception that they are morphologically disturbed, kinematically rotating, and interacting galaxies in an extreme protocluster environment.

Unified Astronomy Thesaurus concepts: Galaxies (573); Galaxy kinematics (602); Protoclusters (1297); High-redshift galaxies (734)

Materials only available in the online version of record: animation

1. Introduction

Galaxy formation is thought to be driven either by "hot" or "cold" processes. In the former scenario, in-falling gas is shock heated to virial temperatures, accreted spherically by the disk, and cooled over long timescales, eventually triggering star formation that is regulated by feedback from stars or active galactic nuclei (M. J. Rees & J. P. Ostriker 1977; S. D. M. White & M. J. Rees 1978; S. M. Fall & G. Efstathiou 1980; A. King & K. Pounds 2015). Theoretically, this implies an increase in turbulence within galaxies at earlier times since systems are dominated by violent disk instabilities (in other words, they are dynamically hotter at earlier epochs; A. Dekel & A. Burkert 2014; A. Zolotov et al. 2015; C. C. Hayward & P. F. Hopkins 2017; M. R. Krumholz et al. 2018; A. Pillepich et al. 2019).

"Cold" processes, however, describe efficient (and possibly coplanar) gas accretion via mergers or filamentary structures in

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the cosmic web (D. Kereš et al. 2005; A. Dekel & Y. Birnboim 2006; A. Dekel et al. 2009b, 2009a; M. Kretschmer et al. 2022). With infrequent mergers over long timescales, this process allows relatively cold $(V/\sigma \gtrsim 4)$ disks to be present across all epochs (F. Lelli et al. 2016; A. Dekel et al. 2020). Several observations have demonstrated the existence of rotational disks with $V/\sigma > 3$ at z > 2 (J. A. Hodge et al. 2012; F. Lelli et al. 2018; P. Sharda et al. 2019; F. Rizzo et al. 2020; F. Fraternali et al. 2021; F. Lelli et al. 2021; F. Rizzo et al. 2021), which most numerical simulations have struggled to reproduce (R. J. J. Grand et al. 2017; A. Pillepich et al. 2019). More recently, a study using high-resolution zoom-in cosmological simulations reproduced the presence of nontransient, massive $(M_{\star} > 10^{10} M_{\odot})$, super-cold $(V/\sigma > 10)$ disks at $z \ge 4$ (A. Pallottini et al. 2022; M. Kohandel et al. 2024). Understanding the kinematics of such galaxies across cosmic epochs allows for studying the physical processes involved in their mass accretion.

Studying the kinematics of galaxies at high redshift requires high-resolution data. At z < 3, the use of optical recombination and forbidden lines such as H α , [O III], and [N II] is common (N. M. Förster Schreiber et al. 2009; A. M. Swinbank et al. 2009;

E. Wisnioski et al. 2015; E. M. Di Teodoro et al. 2016; O. J. Turner et al. 2017). The rotational transitions of the carbon monoxide (CO) molecule are also useful for studying disk kinematics in the innermost parts of a galaxy. However, at $z \gtrsim 3$, these lines are difficult to detect and require long integration times to reach the required sensitivities (J. A. Hodge et al. 2012; M. Ginolfi et al. 2020). Improvements in adaptive optics techniques (N. M. Förster Schreiber et al. 2018) and in interferometric facilities (Atacama Large/submillimeter Array (ALMA), ATCA, NOEMA, Very Large Array, etc.) have significantly contributed toward improving the sensitivity and angular resolution required in such studies.

A commonly studied emission line in astronomy is that of singly ionized carbon (C⁺, hereafter [C II]). Occurring due to a transition between the fine-structure levels ${}^2P_{3/2} \rightarrow {}^2P_{1/2}$, it is one of the dominant cooling lines in the cool interstellar gas (I. De Looze et al. 2011; J. Wagg et al. 2012; R. Herrera-Camus et al. 2015; G. Lagache et al. 2018). [C II] emission traces the atomic and molecular gas across the different phases of the interstellar medium (ISM) due to its ionization potential being lower than that of neutral hydrogen (C. L. Carilli & F. Walter 2013). For solar metallicity gas, it is also the brightest emission line from far-infrared (FIR) to radio wavelengths. At $z \gtrsim 2$, it shifts into the (sub-)millimeter wavelength regime, becoming a popular candidate for studying the ISM at high redshift (A. C. Posses et al. 2023). Due to its brightness, the line is also used in obtaining high-resolution data such as those presented in M. Béthermin et al. (2020) and F. Walter et al. (2022).

Galaxy cluster progenitors, also known as "protoclusters" are found in the z > 1 epoch overlapping with the peak in the cosmic star formation rate (SFR; P. Madau & M. Dickinson 2014; R. A. Overzier 2016). G. Miley & C. De Breuck (2008) state that these protoclusters host massive starburst galaxies and are characterized by their large FIR luminosities (C. M. Casey et al. 2014). The way protoclusters are found differs from their virialized counterparts, as they lack an established intracluster medium and have a much larger angular extent. Protoclusters are usually found by examining the environments of tracer populations such as quasi-stellar objects (i.e., radio galaxies and quasars), Ly α emitters, and dusty star-forming galaxies, also known as submillimeter galaxies (A. Weiß et al. 2009; H. Dannerbauer et al. 2014; R. A. Overzier 2016). In recent years, surveys using the South Pole Telescope (SPT; J. E. Carlstrom et al. 2011) and the Herschel Space Observatory (G. L. Pilbratt et al. 2010) have revealed several rare, strongly lensed and a few unlensed millimeter-selected galaxies (S. Eales et al. 2010; J. D. Vieira et al. 2010; R. Williamson et al. 2011; L. M. Mocanu et al. 2013; I. Oteo et al. 2018). Among these, SPT2349-56 is the brightest unlensed protocluster core discovered at z = 4.303.

Since its discovery, SPT2349–56 has been the subject of several follow-up observations. T. B. Miller et al. (2018) presented ALMA (A. Wootten & A. R. Thompson 2009) Cycle 3 and 4 data targeting the [C II] and CO(4–3) transitions, where they identified 14 galaxies at the same redshift within a radius of 65 kpc, known as the "core" region. They report an estimated SFR of around $6000\,M_\odot\,\mathrm{yr}^{-1}$, making the system the most active protocluster core discovered to date. Further estimates provided in R. Hill et al. (2020) show the presence of over 30 galaxies contained within a 500 kpc region, with SFR of over $10,000\,M_\odot\,\mathrm{yr}^{-1}$. The protocluster is expected to be a

Coma-type progenitor, with a cluster mass of $M > 10^{15} M_{\odot}$ at z = 0 (Y.-K. Chiang et al. 2013; T. B. Miller et al. 2018).

K. M. Rotermund et al. (2021) presented Gemini-S (optical) and Spitzer-IRAC (near-infrared) observations of SPT2349 -56, identifying nine counterparts to existing galaxies and four additional Lyman-break galaxies. The protocluster core has an estimated stellar mass of $10^{12} M_{\odot}$, comparable to a z=1brightest cluster galaxy. With minimal detection in the optical wavelengths, the protocluster system appears to be predominantly composed of heavily dust-obscured galaxies. More recently, R. Hill et al. (2022) presented deeper optical and infrared observations using the Hubble Space Telescope and Spitzer-IRAC, showing that the galaxies in the core are broadly aligned with the galaxy main sequence (MS), resembling the distribution of field galaxies at a similar redshift. Noncosmological hydrodynamical simulations predict that the core region will collapse into a system resembling a low-redshift, giant elliptical galaxy within 100-300 Myr, depending on the true gas fraction (D. Rennehan et al. 2020).

The analysis of high-redshift galaxy kinematics is a vital component in examining galaxy evolution. The studies presented thus far have no known associations with their environments, i.e., they are "isolated" or "field" galaxies. This leaves a gap in our understanding of how galaxies behave in a turbulent and interactive environment like that of a protocluster core. In contrast to previous studies, in this paper, we present the kinematics of galaxies within the core region of the protocluster SPT2349–56.

In this paper, Section 2 describes the observations and data reduction process, Section 3 describes the kinematic fitting process, and Section 4 presents the results from the kinematic analysis. Section 5 discusses the results, comparing them to similar studies across redshifts, and explores a new classification method using position–velocity (p-v) maps. Lastly, Section 6 summarizes our findings. Throughout the analysis, we use a Λ CDM cosmology with h=0.678, $\Omega_{\rm m}=0.308$, $\Omega_{\Lambda}=0.692$, and 1''=6.897 kpc (Planck Collaboration et al. 2016).

2. Observations and Data Reduction

We use high-resolution ALMA Cycle 6 (2018.1.00058.S; PI: S. Chapman) Band 7 data, centered on the [C II] 158 μ m line. The data were obtained as a 6-point mosaic over several days in 2018 November, with a total on-source integration time of 35 to 57 minutes for each observation. The array configurations had baselines between 15 m and 1.4 km. The quasar J2357 –5311 was used as a phase calibrator, while J2258–2758 and J2056–4714 were used as bandpass calibrators. We note here that this data set exclusively targets the core region presented in R. Hill et al. (2020). See Table 1 in R. Hill et al. (2020) for more details about the observations.

The data were reduced using Common Astronomy Software Applications (CASA; J. P. McMullin et al. 2007). They were concatenated and imaged using the tclean task, first using the multifrequency synthesis routine to obtain a continuum image using channels without [CII] emission. We used the Briggs weighting mode and compared the results from a range of robust values between -2 and 2. We found that a robust value of 0.5 optimally balanced resolution and sensitivity. Applying the same weighting parameters, we construct a spectral cube, and subtract the continuum using the imcontsub task.

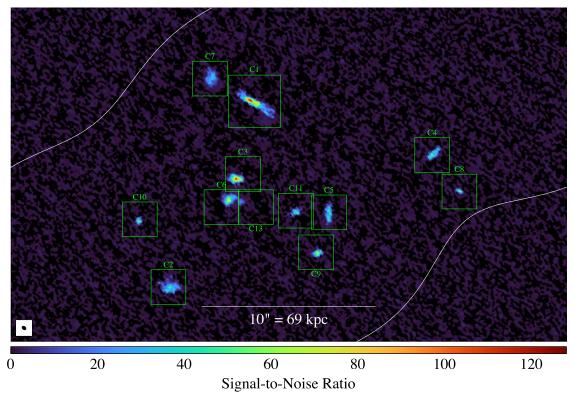


Figure 1. SNR presentation of the continuum-subtracted and primary-beam corrected integrated [C II] intensity (moment-0) distribution of the core region in SPT2349 –56. The sources are named according to R. Hill et al. (2020), and the green boxes indicate the cutout boundaries for each source. The white contour indicates where the primary beam response falls to 80%. The black areas are at SNR < 0. See Section 2 for a description of how the map was prepared.

The line cube was cleaned to a threshold of 0.55 mJy (1.4× the rms noise in the dirty cube), but we note that choice of this parameter does not have a significant impact on the resulting morphology of the [C II] maps. Figure 1 shows the signal-to-noise ratio (SNR) map of the integrated [C II] (moment-0) intensity distribution obtained using the continuum-subtracted spectral cube, averaged between -1250 and $1350 \, \mathrm{km \, s^{-1}}$.

The noise at each position was estimated using the emissionfree channels. An SNR cube was computed by dividing each channel map of the cube by this noise map. This approach is justified since the noise is mainly a function of position and is almost constant along the frequency axis (as verified at the emission-free positions). The SNR moment-0 was computed by summing all consecutive channels with SNR > 2.5 for positions with significant emission, while taking the noise reduction due to the decreased velocity resolution into account. For positions without significant emission, we summed the SNR channel maps centered at the mean velocity and used the mean line width of all consecutive pixels with SNR > 2.5 as integration borders (160 km s⁻¹). The spectral cube has an angular resolution of $\theta_x \times \theta_y = 0.225 \times 0.166$ (spatial resolution of 1.55 kpc \times 1.14 kpc at z = 4.303, θ_x and θ_y are the semimajor and semiminor axes of the synthesized beam). It has a channel width of $13 \,\mathrm{km \, s^{-1}}$, and rms noise $\sigma_{\mathrm{[C \, II]}} =$ $0.5 \,\mathrm{mJy\,beam^{-1}}$.

3. Methods

When studying galaxy kinematics in distant sources, the finite beam size of the observations is often larger than the spatial region over which a change in velocity takes place, in an effect known as beam smearing (R. A. Swaters et al. 2009;

R. Davies et al. 2011). The commonly used tilted-ring modeling technique (see D. H. Rogstad et al. 1974) has been used to extract galaxy kinematics in 2D (K. G. Begeman 1989; J. M. van der Hulst et al. 1992; D. Krajnović et al. 2006; J. A. Sellwood & K. Spekkens 2015), and also in 3D (F. Sicking 1997; G. I. G. Józsa et al. 2007; E. M. D. Teodoro & F. Fraternali 2015). 2D methods require an intermediate step between the model and observations, where a velocity field must be extracted from the spectral cube. Several methods can be used to perform this step, and they can often be inconsistent among themselves (E. M. D. Teodoro & F. Fraternali 2015). They also perform poorly with low angular resolution data due to beam smearing. 3D methods have an advantage where they skip this intermediate stage to work directly with the spectral cube, naturally taking into account the effect of the synthesized beam to provide better results in kinematic analyses. In this work, we use 3D-Based Analysis of Rotating Objects via Line Observations (^{3D}BAROLO; E. M. D. Teodoro & F. Fraternali 2015) for its ability to handle low SNR data and low angular resolution data.

3.1. Source Detection Using ^{3D}BAROLO

Using the same naming convention presented in R. Hill et al. (2020), we extract $2'' \times 2''$ ($3'' \times 3''$ for source C1) sub-cubes for the sources (green boxes in Figure 1) using the <code>imsub-image</code> task in CASA. We note that sources C3 and C6 appear off-center due to their proximity to nearby galaxies. These subcubes are then processed with the SEARCH task in ^{3D}BAROLO. The task detects sources in position–position–velocity space, creating a mask using a combination of smoothing and clipping. Here, we use only the clipping options, identifying

the sources at $5\sigma_{[C\ II]}$ and growing them down to $2.1\sigma_{[C\ II]}$ around the emission peaks for sources C2–C7, and $2.5\sigma_{[C\ II]}$ for source C1. The lower threshold includes sufficient signal without introducing excessive noise around the sources, while also being the SNR limit for use with $^{3D}BAROLO$. Using these thresholds, sources C1–C11 and C13 are identified in the [C II] spectral cube. Sources C12 and C14–C23, identified in R. Hill et al. (2020), are not detected here (see the discussion in Section 4).

3.2. Kinematic Fitting Using ^{3D}BAROLO

The 3DFIT task requires initial values for an array of geometrical parameters such as the kinematic center (x_0, y_0) , position angle (ϕ) , and inclination angle (i), along with kinematic parameters such as the rotation velocity (V_{rot}) , velocity dispersion ($\sigma_{\rm disp}$), and the systemic velocity ($V_{\rm sys}$) to perform a rotation curve fit in 3D space. A model observation is built in 3D space as concentric rings based on the initial parameter values, allowing for the gas motion to be characterized in a disk as rotational or turbulent. The model is then convolved with the beam, before performing a χ^2 minimization between the observed line emission and the model. The code continues to recompute models until a bestfitting model is found. The advantage of such a fitting process is the reduction of the aforementioned beam-smearing effects, where the comparable sizes of the source and the synthesized beam could underestimate the rotation velocity and, at the same time, overestimate the gas velocity dispersion (E. M. D. Teodoro & F. Fraternali 2015). We note that the term "velocity dispersion" refers to the galaxy's intrinsic value, corrected for instrumental effects of spatial and spectral resolution. The term "broadening" will refer to the noncorrected velocity dispersion.

We provide initial guesses for x_0 , y_0 , V_{rot} , and V_{sys} using the results from the SEARCH task. The values of x_0 , y_0 obtained as such are the flux-weighted average of the moment-0 map. We find that for some galaxies, x_0 and y_0 do not overlap with the kinematic center of the galaxy (where the line-of-sight velocity is $V_{\rm LOS} \approx 0 \, {\rm km \, s}^{-1}$). For these cases, we use the moment-1 (velocity field) map and the p-v maps to adjust the coordinates before supplying them as initial guesses. ϕ is measured counter-clockwise from the north toward the receding side of the galaxy using the moment-1 map. For i, we first compute (b/a), where a and b are the semimajor and semiminor axes of the source, respectively, using the CASA image analysis tool fitcomponents. i is then estimated using $\cos^2 i = ((b/a)^2 - q^2)/(1 - q^2)$, where q = 0.2 for a mildly thick disk. We note here that for galaxies that appear edge-on (C1, C4, and C5), we use $\cos i = (b/a)$ since the former definition consistently overestimates the inclination angle by \approx 5°. The estimated i is also verified against a fraction-of-peak contour that encloses 20% of the peak moment-0 intensity, [C II]_{peak}. Lastly, $\sigma_{\rm disp}$ is arbitrarily set at values between 30 and $150 \, \text{km s}^{-1}$.

Other relevant parameters used in the analysis are the ring separation (RADSEP), number of rings (NRADII), and normalization type (NORM). Generally, RADSEP defaults to the major axis of the synthesized beam in order to describe rotation curves with independently estimated points along the rotation curve. In our case, we use RADSEP = $\sqrt{\theta_x \theta_y}/2$, achieving a close-to-Nyquist sampling 15 of the rotation and dispersion

curves. NRADII provides the number of rings that are spaced at a width of RADSEP, where the kinematic parameters are extracted. Lastly, NORM allows for choosing between a pixel-to-pixel or an azimuthal normalization of the moment-0 map (see E. M. D. Teodoro & F. Fraternali 2015 for more details). Here, we choose azimuthal normalization.

We finally run the 3DFIT task to simultaneously fit four parameters per ring— $V_{\rm rot}$, $\sigma_{\rm disp}$, ϕ , and i—using a two-stage fitting process. The code allows the user to choose the regularization type for the geometry. Here, we use a Bézier fitting of geometrical parameters in the first stage, while the code automatically fits the kinematic parameters in the second stage. x_0 , y_0 , and $V_{\rm sys}$ are kept constant throughout after verification using the $(p-\nu)$ diagrams and the moment-1 map. We assume a thin-disk approximation and set the scale height z_0 to 1/10 of the half-light radius of the individual sources (see R. Hill et al. (2020) for values) and discuss the implications in Section 5. We also assume the large-scale radial motion of the gas is obscured in the high rotation velocities, and set the radial velocity $V_{\rm rad}=0$. A sample parameter file used in the fitting is presented in Appendix A.

4. Results

At the end of the kinematic analysis, we find converging models for sources C1-C7, i.e., the seven FIR brightest sources listed in Table 3 of R. Hill et al. (2020). While we were able to detect sources C8-C11 and C13 using the SEARCH task, we found that due to their spatial extent approaching the synthesized beam size, too few data points exist to properly model their kinematics. Sources C12 and C14-C23 are not detected in the SEARCH task due to reduced sensitivity when compared to R. Hill et al. (2020). They report $\sigma_{\rm [C\ II]} = 0.22 \,\rm mJy\,beam^{-1}\,channel^{-1}$ with a similar channel width, and a beam size that is 28% larger than that for our sample. However, they use a combination of Cycle 5 and 6 ALMA data to produce a single, deep [C II] data cube focusing on sensitivity, whereas we only use Cycle 6 data for its longer baseline, therefore prioritizing spatial resolution. Overall, this drop in sensitivity explains the lack of detection of the sources C12 and C14-C23.

For each source, Figures 2 and 3 show the p-v slices, the moment maps, and the spectra. The p-v slices are across the kinematic major and minor axes, while the moment maps and spectra are obtained from a spectral cube masked using SEARCH task parameters. We note that the p-v slices and moment maps are not corrected for beam smearing. In Tables 1 and 2, we present the resulting kinematic center, position angle, inclination angle, and systemic velocity with respect to z=4.303 (the flux-weighted kinematic center of the protocluster core).

4.1. P-V Slices

Major-axis slice. For source C1, we find a rising and flattening of the rotation curve. For the remaining sources, the rotation curve rises, but cannot be measured out to distances where it is expected to flatten (>3 kpc). There is, however, a symmetry between the approaching and receding sides in all the sources, showing a resemblance to the characteristic "S"-shape of a rotation-supported disk (W. J. G. de Blok et al. 2008).

 $[\]overline{^{15}}$ Nyquist sampling is when the synthesized beam is sampled ≈ 2.4 times.

¹⁶ https://encyclopediaofmath.org/wiki/B%C3%A9zier_curve

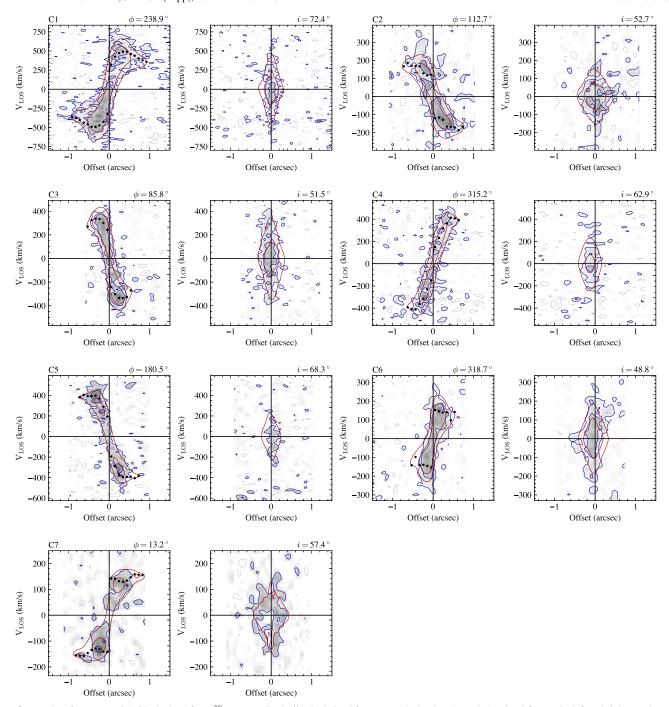


Figure 2. p–v plots for sources C1–C7 obtained from 3D BAROLO. Each slice is derived from unmasked cubes. In each 1×2 subfigure, the left and right panels are the p–v slices along the major and minor axes, respectively. ϕ and i are the derived position and inclination angle, respectively, for each source. The blue and red contours are at $n\sigma_{C\ II}$ (n=2,5) for the data and model, respectively. The gray contours are at $-n\sigma_{C\ II}$. The derived rotation curve is overplotted with black-filled circles.

Minor-axis slice. At low angular resolution, a minor-axis p-v slice of a moderately inclined rotating disk will present a broad, "blooming" pattern due to line broadening from instrumental effects (E. M. D. Teodoro & F. Fraternali 2015). This behavior is present in all our sources.

4.2. Moment Maps and Spectra

For our sample, we find from column (1) in Figure 3 that there is minimal scatter ($<0.^{\prime\prime}22$) between the kinematic center (black cross) and the flux-weighted average of the moment-0 map (blue cross). The red contour is at $0.2[C\ II]_{peak}$, and the

black ellipse describes the outermost evaluated ring. There is good agreement between the two for all the sources, except in the case of C2 where the [C II] emission appears to be asymmetrically concentrated around the center within a small region. In the case of source C7, we find substructures at this spatial scale that are perpendicular to its kinematic major axis.

The position angle for the morphological major axis is derived using the CASA image analysis tool fitcomponents, and is reported in Table 1. It is represented by the blue dashed line. We note that the angle obtained from the tool is degenerate by 180° , and we report the adjusted value in Table 1. The difference between the morphological and

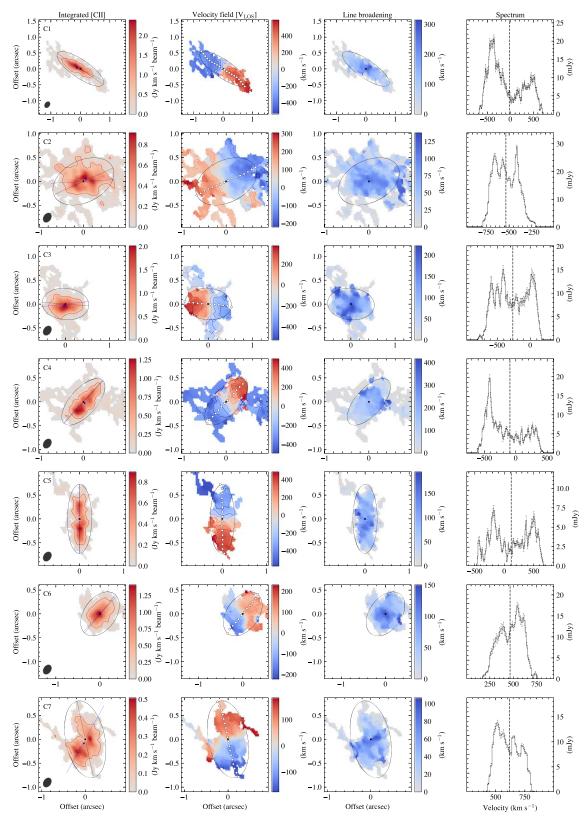


Figure 3. Moment maps and spectra from ^{3D}BAROLO for sources C1–C7. The first, second, and third columns are the moment-0, moment-1, and moment-2 maps, respectively. These moment maps are generated from data cubes that are not corrected for beam smearing. For each source, the synthesized beam is shown in the bottom-left of the moment-0 map. Column (1): the black ellipse is the outermost ring used in fitting with ^{3D}BAROLO. The black and blue crosses are the kinematic and flux-weighted centers of the [C II] emission, respectively. The black and blue dashed lines are the kinematic and morphological major axes, respectively. The red contour is at 0.2[C II]_{peak}. Column (2): the filled white circles mark the kinematic major axis of the galaxy, respectively. Column (4): spectrum of the source obtained from a data cube masked according to the SEARCH task. The dashed vertical line is the systemic velocity of the source.

 Table 1

 The Morphological Centers, Position Angles, and the Derived Geometrical Parameters After Kinematic Modeling

Source	R.A., Decl. (morph) ^a (J2000)	R.A., Decl. (kin) ^a (J2000)	$\phi_{ ext{morph}}^{ ext{b}}$ (°)	$\phi_{ m kin}^{}$ (°)	i ^c (°)	z ₀ ^d (kpc)
C1 (A)	23:49:42.7 -56:38:19.4	23:49:42.6 -56:38:19.4	244.3 ± 0.4	238.9 ± 2.4	72.4 ± 1.1	0.2
C2 (J)	23:49:43.2 -56:38:30.1	23:49:43.2 -56:38:30.1	93.1 ± 5.0	112.7 ± 1.3	52.7 ± 1.2	0.2
C3 (B)	23:49:42.8 -56:38:23.8	23:49:42.8 -56:38:23.8	95.7 ± 2.1	85.8 ± 1.2	51.5 ± 0.2	0.1
C4 (D)	23:49:41.4 -56:38:22.4	23:49:41.4 -56:38:22.4	316.0 ± 1.3	315.2 ± 1.3	62.9 ± 0.7	0.1
C5 (F)	23:49:42.1 -56:38:25.8	23:49:42.1 -56:38:25.8	180.6 ± 0.9	180.5 ± 2.7	68.3 ± 1.5	0.2
C6 (C)	23:49:42.8 -56:38:25.1	23:49:42.8 -56:38:25.1	314.5 ± 2.5	318.7 ± 1.3	48.8 ± 1.4	0.1
C7 (K)	23:49:43.0 -56:38:18.1	23:49:42.9 -56:38:18.0	328.5 ± 5.7	13.2 ± 2.0	57.4 ± 1.2	0.2

Notes. The sources are named according to R. Hill et al. (2020) and T. B. Miller et al. (2018) in brackets.

 Table 2

 The Derived Velocity and Stability Parameters After Kinematic Modeling

Source	$V_{\rm sys}^{\rm a}$ $({\rm km\ s}^{-1})$	$V_{\text{rot}}^{}}$	$\sigma_{\rm disp}^{}_{\rm (km\ s}^{}_{\rm -1})$	$(V_{ m rot}/\sigma_{ m disp})^{ m b}$	$Q_{\mathrm{T}}^{\mathrm{b}}$	$f_{ m gas}^{ m c}$
C1 (A)	-21.5	472.3 ± 12.0	95.6 ± 5.5	4.0 ± 0.2	1.1 ± 0.2	0.35
C2 (J)	-534.5	209.3 ± 7.3	37.6 ± 3.8	3.3 ± 0.4	0.6 ± 0.1	0.20
C3 (B)	-265.1	425.4 ± 12.4	49.3 ± 6.0	6.7 ± 0.8	0.9 ± 0.3	< 0.69
C4 (D)	-93.5	427.6 ± 14.1	50.6 ± 5.9	4.1 ± 0.4	1.3 ± 0.4	0.54
C5 (F)	118.2	425.3 ± 9.1	20.8 ± 3.3	5.9 ± 0.6	0.8 ± 0.3	0.40
C6 (C)	466.3	184.2 ± 10.1	35.7 ± 4.3	3.3 ± 0.4	0.6 ± 0.2	0.17
C7 (K)	618.7	173.3 ± 4.9	14.9 ± 2.4	4.2 ± 0.5	0.2 ± 0.1	0.31
Sampl	le Mean	357.1 ± 4.5 (114.7)	$48.4 \pm 2.0 \; (23.5)$	$4.5 \pm 0.2 \; (1.3)$	$0.9 \pm 0.1 \; (0.3)$	

Notes. In the last row, we give the mean value for the sample (excluding source C7), where the error corresponds to the uncertainty of the mean, while the number in brackets shows the standard deviation of the sample. We note here that there is a slight discrepancy between the reported $(V_{\text{rot}}/\sigma_{\text{disp}})$ ratio to the value that is obtained when using $(V_{\text{rot},\text{mean}}/\sigma_{\text{disp},\text{mean}})$. This is simply due to the fact that for individual sources, $(V_{\text{rot}}/\sigma_{\text{disp}})_{\text{mean}} \neq (V_{\text{rot},\text{mean}}/\sigma_{\text{disp},\text{mean}})$, ignoring the weights.

kinematic axes (black dashed line in Figure 3) is less than 30° for all the sources except C7.

Column (2) in Figure 3 shows the moment-1 maps, obtained as the intensity-weighted velocity of the spectral line. In each source, we find a smooth velocity gradient, with the kinematic and morphological major axes broadly aligned with each other. The blue and red contours constitute a "spider" diagram for each source and are placed at $\pm n \, 100$ ($n=1, \, 2, \, 3$) km s⁻¹ (K. G. Begeman 1989). There are no closed contours along the major axis, suggesting that there is no peak in the rotation curve. The exceptions are C6 and C7, where the map shows a closed loop. Since there is no peak in the velocity profile (see Figure 4, column (1)), we suggest this is due to a combination of observing a compact disk, low SNR, and remnant beam effects. The black cross is the kinematic center of the galaxy.

Column (3) in Figure 3 shows the line broadening map for the sources, i.e., a velocity dispersion map that is not corrected for instrumental broadening. We reiterate here that Figure 3 shows the moment maps obtained directly from the data cubes, without correcting for beam smearing. They are not used in the kinematic extraction and are presented here for completeness only. Figures 8–14 in Appendix B show the observed, modeled, and residual moment maps for sources C1–C7.

Column (4) in Figure 3 shows the spectrum of each source. The dashed vertical line is the systemic velocity of the source. We find double-peaked profiles with varying degrees of asymmetry across the systemic velocity for all the sources.

4.3. Velocity Profiles

Columns (1) and (2) in Figure 4 show the rotation curve and velocity dispersion profiles, respectively, derived using the spectral cubes of the sources. The errors are obtained via a Markov Chain Monte Carlo (MCMC) sampling of the parameter space around the best-fit value. We note here that the errors are not statistical errors, but a measure of how wellbehaved the parameter space is around the best-fit value (E. M. D. Teodoro & F. Fraternali 2015). In sources C3-C6, there is insufficient data to estimate the outermost parts of the rotation curve (>3.5 kpc). In Table 2, we tabulate the noiseweighted mean rotation velocity and dispersion, calculated by excluding the data points falling within the beam size (<1.55 kpc, vertical dashed line in Figure 4) to avoid possible remnant beam-smearing effects. We are then left with at least three independent measurements for each velocity and dispersion profile. Since we have a reasonable estimate of the inclination angles, the computed $V_{\rm rot}$ values are robust. The estimated $\sigma_{\rm disp}$ for all the galaxies are greater than the velocity

^a Morphological and kinematic center of the source, respectively.

^b Morphological and derived kinematic position angles, respectively.

^c Derived inclination angle.

^d Scale height used in kinematic analysis, $0.1R_{1/2}$ from R. Hill et al. (2020).

^a Systemic velocity, relative to z = 4.303.

^b Noise-weighted mean and uncertainty for rotation velocity, velocity dispersion, V/σ ratio, and Toomre parameter at r > 1.55 kpc.

^c Gas fraction, as presented in K. M. Rotermund et al. (2021).

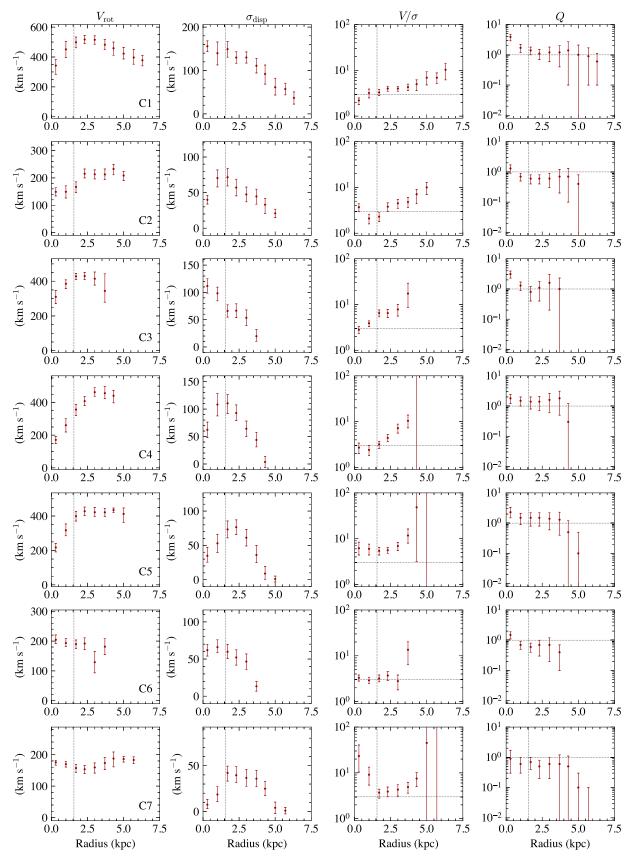


Figure 4. Results from 3D BAROLO for sources C1–C7. Columns (1) and (2) show the velocity and dispersion profiles, where the errors were obtained from an MCMC sampling of the parameter space surrounding the best-fit values. Column (3) shows the $V_{\rm rot}/\sigma_{\rm disp}$ profile for each source. Column (4) shows the Toomre parameter profile for each source (see Section 5.2). The vertical dashed lines denote the beam extent (\approx 1.6 kpc). The horizontal dashed line in column (3) marks the demarcation line between rotation- and pressure-supported systems. The horizontal dashed line in column (4) marks the Q=1 stability criteria.

resolution of 13 km s⁻¹, and we can therefore expect the values produced by 3DFIT to be reliable.

5. Discussion

We have presented the results of a 3D kinematic analysis of the seven FIR brightest galaxies within the SPT2349–56 protocluster core. To interpret the results, we first take a look at the assumptions made in the fitting process. First, we note that any further improvement in the derived kinematics in the inner part of the disks can only be achieved with a combination of higher resolution and deeper data.

Next, the two available types of normalization—localized and azimuthal—serve different purposes (E. M. D. Teodoro & F. Fraternali 2015). The former constructs nonaxisymmetric models, used to identify untypical regions such as small-scale clumps, outflows, or holes that could affect the overall velocity profile fit. This is presented via a model moment-0 map that is identical to that of the observations, i.e., the integrated spectrum in each pixel is the same for the model and the observations. In the latter case, an axisymmetric model is constructed such that the model flux is normalized to the azimuthally averaged flux of the data in each ring. This model is used to identify warps or large-scale clumps. We compared the output from both cases and found no large-scale structures in the galaxies, but the azimuthal normalization presented a better fit to the geometry. The data, model, residual moment maps, residual p-v maps, and fitting results for the four free parameters obtained from the azimuthal fitting are presented in Appendix B. We also found there is no significant, large-scale radial motion present in the galaxies by setting the radial velocity as a free parameter with an initial value of $V_{\rm rad} = 0$. We note that any possible radial velocity component much less than the rotation velocity would be lost due to resolution effects and low sensitivities.

The simultaneous modeling of geometry and kinematics often leads to unphysical gaps in the velocity and dispersion profiles. In our case, the 3DFIT code uses the first minimization stage to fit a Bézier function to both ϕ and i. The next stage is used purely to fit the velocity curves, holding the geometry constant. We find that this two-stage minimization process is efficient compared to user-supplied fixed angles.

The weakest link in kinematic modeling is the inclination angle. For galaxies that appear face-on, there is no significant visual distinction between $i=5^{\circ}$ and $i=20^{\circ}$, but their estimated rotation curves differ drastically since $V_{\rm rot} \propto V_{\rm obs}/\sin i$. For reference, $\sin 20^{\circ}/\sin 5^{\circ} \approx 4$. In such cases, the estimation of the minor-to-major (b/a) axis ratio has to be done with great precision. Here, we use a number of techniques as described in Section 3.2 to initially estimate b/a, and all the galaxies clearly present initial values greater than 40° .

Our assumption of a thin disk with $z_0 \approx 0.1$ times the half-light radius also affects the estimation of the inclination angle. The mean of the derived inclination angles for our sample is $\approx 60^{\circ}$, corresponding to the mean inclination of a random sample of galaxies (A. J. Romanowsky & S. M. Fall 2012). The sample also presents clear rotation curves, suggesting that we are not dealing with face-on disks, where the assumption of a thin disk may wreck our interpretation. While the generated model reproduces the [C II] emission well, it is still a simplified assumption since at high redshift, turbulence within the disk would give rise to a higher velocity dispersion and a thick disk.

M. Neeleman et al. (2020) present a comparison between assumptions of an infinitely thin disk and a disk where the scale height is 0.15–1 times the scale radius at $z \approx 4.2$. Their results show a decrease in the estimated inclination angles by $\approx 7^{\circ}$. Since we use $z_0 = 0.07-0.15$ times the scale radius provided in R. Hill et al. (2020), there may be a possibility that we are overestimating the inclination angles. However, in the absence of additional information about the disk thickness, we report values obtained using a simplified thin-disk assumption.

5.1. Kinematic Analysis

5.1.1. Rotators Versus Mergers

At the spatial resolution of our study, it remains difficult to distinguish between rotating disks and compact mergers. Several studies in the literature exist where the gas kinematics and morphology in FIR bright high-redshift galaxies appear to be fully consistent with a rotating disk, but the authors favor the interpretation of a compact merger (e.g., R. Neri et al. 2014; K. C. Litke et al. 2019). Merging of galaxies is a common interpretation for the cause of the extreme SFRs of local and high-redshift FIR bright sources. For the SPT2349-58 protocluster system, a strong interaction between the galaxies (D. Rennehan et al. 2020) is a likely trigger for the high SFRs in the gas-rich members, but as described in the following sections, we find evidence for rotating disk signatures along with mergers and/or tidal disturbance signatures in six of these galaxies.

For a given system to be dynamically classified as rotation supported, a series of criteria exist in the literature (N. M. Förster Schreiber et al. 2018; E. Wisnioski et al. 2019; N. M. Förster Schreiber & S. Wuyts 2020; G. C. Jones et al. 2021). The system:

- 1. must have a monotonically smooth velocity gradient that defines the kinematic axis,
- 2. is rotation supported and has $V/\sigma > 3$,
- has spatially coincident morphological and kinematic centers.
- 4. has morphological and kinematic major axes separated by less than 30°, and
- 5. has a centrally peaked velocity dispersion profile, such that the maximum defines the kinematic center.

For our sample, we find that all galaxies satisfy condition 1. In this work, the morphological center of a galaxy is defined as the flux-weighted center of the moment-0 map (column (2) in Table 1). Therefore, for condition 3, if the distance between the kinematic and morphological center (determined using simple geometry) is less than $\theta_x = 0.^{\prime\prime}22$, then we assume that the centers are spatially coincident. The sources in our sample, except C7, satisfy condition 3.

From Section 4.2, we have the difference between the kinematic and morphological axes to be $<30^{\circ}$ for all the sources except C7. In addition, if we use the definition for kinematic misalignment angle $(\phi_{\rm mis})$ from M. Franx et al. (1991), we find the morphological major axis of the [C II] gas distribution coaligned with the kinematic axis for the sample such that $\phi_{\rm mis} < 15^{\circ}$. The exceptions are sources C2 and C7, where in the former, the emission appears to be centrally clumpy (see Figure 3, columns (1) and (2)), and in the latter, the substructures appear perpendicular to the kinematic axis.

In addition to these criteria, we refer to Section 4.1, where we identified the presence of the distinctive symmetrical p-v slices. Lastly, we refer to column (4) in Figure 3, where we find double-peaked profiles for all the sources, considered a signature of rotating disks (M. Kohandel et al. 2019). Therefore, based on the conventional dynamical support criteria, we find no immediate evidence supporting the presence of mergers in the protocluster environment, allowing us to further investigate gas kinematics. The exception is source C7, which appears to be a major merger, and we discard it from the analysis in Section 5.1.3.

5.1.2. Gas Kinematics

Gas kinematics can help study the measure of rotational support in a galaxy. In this context, the rotational velocity and velocity dispersion correspond to ordered and random motions, respectively. There are a few definitions available in the literature to quantify this, such as $\Delta V_{\rm obs}/2\sigma_{\rm int}$ and $V_{\rm rot}/\sigma_{\rm disp}$ (N. M. Förster Schreiber et al. 2009; F. Rizzo et al. 2020). Here, $V_{\rm obs}$ is the velocity gradient of the tracer, and $\sigma_{\rm int}$ is the source-integrated velocity dispersion, where both are uncorrected for inclination. $V_{\rm rot}$ and $\sigma_{\rm disp}$ are the inclination-corrected rotation velocity and velocity dispersion, respectively, where two further definitions can be derived. The first is obtained by setting $V_{\rm rot} = V_{\rm max}$, the maximum inclination-corrected rotation velocity and $\sigma_{\rm disp} = \sigma_{\rm mean}$, the mean velocity dispersion of the profile. The second definition is used for our sample, where we set $V_{\rm rot} = V_{\rm flat}$ and $\sigma_{\rm disp} = \sigma_{\rm extended}$, both measured beyond 0." 22 (\approx 1.55 kpc, the beam size, marked as a vertical dashed line in Figure 4).

We exclude the innermost points due to possible remnant beam-smearing effects in the central regions. We use the A. Burkert et al. (2010) definition, where a galaxy is dynamically hot or pressure supported if $V/\sigma \leqslant 3$, and dynamically cold or rotation supported if $V/\sigma > 3$. We find, however, that there are other thresholds used across different works (see O. J. Turner et al. (2017) and references therein).

Simulations and comparative observational studies have found that the velocity dispersion measured from ionized tracers tends to be $\approx 15 \ \mathrm{km \, s^{-1}}$ higher than those obtained from molecular or neutral tracers, implying a lower V/σ when using ionized tracers (H. Übler et al. 2019; M. Kretschmer et al. 2022). Similar to recent high-redshift studies that use ionized gas as a tracer to study gas kinematics, we use the [C II] 158 $\mu \mathrm{m}$ line to study the galaxies within the SPT2349–56 protocluster core.

5.1.3. SPT2349-56

For the galaxies in our sample, we observe a rise and flattening of the rotation curves in sources C1–C5, and only flattening in source C6, while the dispersion profiles are all centrally peaked (excluding the beam, <1.55 kpc) and decaying (see Figure 4, columns (1) and (2), respectively). Column (3) in Figure 4 shows the complete V/σ ratio profile for the galaxies in our sample, while column (5) in Table 2 shows the

corresponding mean V/σ ratio. All seven sources show $V/\sigma>3$, categorizing them as rotation-dominated systems, also satisfying condition 2 in Section 5.1.1. The mean of the sample (excluding source C7) is 4.5 ± 0.2 . Since [C II] traces the cold inner molecular disk, our sample, with its high V/σ values, is in line with the results presented for the inner molecular disk in M. Kretschmer et al. (2022) and M. Kohandel et al. (2024). Figure 5 summarizes the current understanding of the evolution of the V/σ ratio with z, for both observational data and theoretical models. We discuss the relevant theoretical models and observational samples in the following sections.

5.1.4. Numerical and Analytical Studies

The gray-shaded region in Figure 5 includes results and analyses from A. Dekel & A. Burkert (2014), A. Zolotov et al. (2015), C. C. Hayward & P. F. Hopkins (2017), and A. Pillepich et al. (2019). Through theoretical methods and cosmological simulations, A. Dekel & A. Burkert (2014) and A. Zolotov et al. (2015) show that beyond z = 3, galaxies are dominated by violent disk instabilities, with $V/\sigma \le 2$.

C. C. Hayward & P. F. Hopkins (2017) presented an analytical model to study the consequences of stellar feedback processes. In this model, the velocity dispersion is not a measured quantity, but a derived one, and is obtained as $\sigma_{\rm disp} \approx f_{\rm gas} (V_{\rm c}/\sqrt{2})^{17}$ Here, $f_{\rm gas} = M_{\rm gas}/(M_{\rm gas}+M_{\rm star})$ is the gas fraction, and $V_{\rm c} = \sqrt{V_{\rm gas}^2 + V_{\rm star}^2 + V_{\rm DM}^2}$ is the circular velocity. Since we do not have stellar and dark matter velocity contributions on hand, we substitute $V_{\rm c} = V_{\rm gas}$ and first set $f_{\rm gas} = 0.7$ (K.-i. Tadaki et al. 2019; D. Rennehan et al. 2020). This leaves us with predicted σ_{disp} values that are approximately 2-5 times higher than the derived values. However, if we use the f_{gas} values presented in K. M. Rotermund et al. 2021 (column (7) in Table 2), we find that the predicted σ_{disp} values are between 0.5 and 3 times the derived values. This difference in predicted $\sigma_{\rm disp}$ values using the C. C. Hayward & P. F. Hopkins (2017) model possibly rises from the assumption that for high-redshift galaxies, the inferred gas fractions are usually high $(f_{\rm gas} \approx 0.7)$, spread over a range of 0.4–0.9 (K.-i. Tadaki et al. 2019).

Lastly, A. Pillepich et al. (2019) predict the evolution of V/σ with respect to redshift $(0 \le z \le 5)$ for a gas mass range of $10^9 - 10^{11} M_{\odot}$ from the TNG50 simulation. At z = 4.303, we find that the mean SPT2349-56 value (4.5 ± 0.2) is greater than the median TNG50 value of 3 ± 1.5 by 1 standard deviation. We also note that in Figure 5, this evolution is extrapolated beyond z = 5.

5.1.5. Observational Samples

Table 3 shows the observational samples used in Figure 5 as comparisons, including the tracer, the definition of $V_{\rm rot}$ and $\sigma_{\rm disp}$, and the V/σ values. We choose the samples based on two criteria—(i) The study uses an ionized gas tracer to study kinematics; (ii) The study uses a 3D kinematic modeling method to evaluate the kinematics. The objects in these studies are starbursts or MS galaxies. Beyond z=2.5, several samples deviate from the predicted V/σ evolution. Starbursts (colored crosses in Figure 5) appear to have higher V/σ compared to the MS samples (colored dots in Figure 5). SPT2349–56 consists mainly of MS galaxies (K. M. Rotermund et al. 2021;

 $[\]overline{^{17}}$ Equation (20) in their paper, setting $Q_{\text{turb}} = 1$.

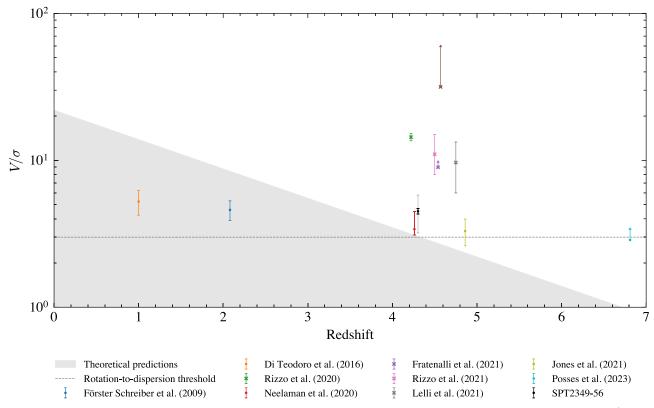


Figure 5. Comparison of the rotation-to-dispersion ratios of the galaxies within SPT2349–56 and samples of simulated and observed galaxies. The V/σ ratio for our sample is obtained using V_{flat} and σ_{ext} , both computed beyond ≈ 1.55 kpc. The solid and faded black error bars are the uncertainty of the mean and standard deviation of the sample, respectively. The gray-shaded region includes the theoretical predictions made by A. Dekel & A. Burkert (2014), C. C. Hayward & P. F. Hopkins (2017), A. Pillepich et al. (2019), and A. Zolotov et al. (2015). The dashed line at $V/\sigma = 3$ marks the A. Burkert et al. (2010) criteria we use for kinematic classification. Details of the comparison samples are presented in Table 3. The colored dot and cross markers represent MS and starburst galaxies, respectively.

R. Hill et al. 2022), and its mean and corresponding error (black-filled circle in Figure 5) is within the region between starbursts and MS samples at a similar redshift.

The comparison samples at a similar redshift are field galaxies, i.e., they are not associated with a protocluster-like environment. In these cases, it is possible to achieve a rotating disk via "cold" processes (see Section 1). However, if we assume that the SPT2349–56 core accretes via a "cold stream in a hot medium" as presented in A. Dekel et al. (2009b), we find that the tidal interaction timescale in a protocluster system is much shorter than the cold stream accretion time, rendering the cold streaming process inefficient. This is further discussed in Section 5.4.

5.2. Toomre Parameter Analysis

In the absence of sufficient random motion in a thin, smoothly distributed rotating disk, the disk is expected to suffer violent instabilities (A. Toomre 1964). The Toomre parameter (Q_T) measures the stability of a disk against gravitational perturbations. Q_T is defined as

$$Q_{\rm T} = \frac{\sigma_{\rm disp} \kappa}{\pi G \Sigma_{\rm gas}},\tag{1}$$

where $Q_{\rm T} < 1$ describes an unstable disk. $\kappa = \sqrt{R(d\Omega^2/dR) + 4\Omega^2}$ is the epicyclic frequency, with $\Omega = V_{\rm rot}/R$ (which simplifies to $\kappa = \sqrt{2}\,V_{\rm rot}/R$). $\Sigma_{\rm gas}$ is the

gas mass surface density, which is obtained in our case as

$$\Sigma_{\rm gas} = \frac{L_{\rm CII} \alpha_{\rm CII}}{\text{per unit area}} \quad (M_{\odot} \, \text{kpc}^{-2}), \tag{2}$$

where $L_{\rm C\ II}$ and $\alpha_{\rm C\ II}$ are the [C II] line luminosity and the atomic gas mass to [C II] line luminosity ratio, respectively. The $\alpha_{\rm C\ II}$ parameter takes a range of values between 5 and 30 (N. Sulzenauer et al. 2024, in preparation; A. Zanella et al. 2018; F. Rizzo et al. 2020; D. Vizgan et al. 2022). Here, we use values presented in F. Rizzo et al. (2020), where $\alpha_{\rm C\ II} = 7.3 \pm 1.2\,M_{\odot}/L_{\odot}$. There is a possibility to use dynamical mass estimates to deduce $\alpha_{\rm [C\ II]}$ for this sample; however, it is beyond the scope of this work.

 $L_{\rm C~II}$ is found by replacing the CO line luminosity calculations with the [C II] line in Equation (1) of P. M. Solomon et al. (1997),

$$L_{\text{CII}} = 1.04 \times 10^{-3} S_{\text{CII}} \Delta V \nu_{\text{rest}} (1+z)^{-1} D_{\text{L}}^2 \quad (L_{\odot}),$$
 (3)

where $S_{\text{C II}}\Delta V$ is the velocity integrated flux in Jy km s⁻¹, ν_{rest} is the [C II] line rest frequency in GHz, and D_{L} is the luminosity distance in Mpc.

Studies such as F. Rizzo et al. (2020) and M. Neeleman et al. (2020) obtain mean values of \approx 0.96 beyond 1 kpc radii at redshift \approx 4.2. For our sample of galaxies, the mean value is $Q_T = 0.8 \pm 0.1$, with individual values ranging from 0.2 to 1.1. The largest source of uncertainty is the gas surface density, which could be mitigated using sophisticated means of flux profile extraction in future works. Sources C2 and C7 show substructures in the moment-0 maps with low Q_T values,

Table 3

Comparison Samples with Inclination-corrected Rotation Velocities and Velocity Dispersion Values from the Literature

Study ^a	Type of Objects	Tracer	z	V	σ	V/σ
N. M. Förster Schreiber et al. (2009)	MS	$H\alpha$	2.08	$V_{ m rot}$	$\sigma_{ m disp}$	4.6 ± 0.6
E. M. Di Teodoro et al. (2016)	MS	$_{ m Hlpha}$	0.90	$V_{ m flat}$	$\sigma_{ m ext}$	5.5 ± 0.3
F. Rizzo et al. (2020)	Starburst	[C II]	4.22	$V_{ m flat}$	$\sigma_{ m ext}$	14.4 ± 0.4
M. Neeleman et al. (2020)	MS	[C II]	4.26	$V_{ m rot}$	$\sigma_{ m disp}$	$3.4^{+1.1}_{-0.3}$
F. Fraternali et al. (2021)	Starburst	[C II]	4.54	$V_{ m flat}$	$\sigma_{ m ext}$	9.0 ± 0.7
F. Rizzo et al. (2021)	Starburst and MS	[C II]	4.50	$V_{ m flat}$	$\sigma_{ m ext}$	11 ± 4
F. Lelli et al. (2021)	Starburst	[C II]	4.75	$V_{ m rot}$	$\sigma_{ m disp}$	9.7 ± 3.7
G. C. Jones et al. (2021)	MS	[C II]	4.86	$V_{ m rot}$	$\sigma_{ m disp}$	3.3 ± 0.7
A. C. Posses et al. (2023)	MS	[C II]	6.81	$V_{ m flat}$	$\sigma_{ m ext}$	2.9 ± 0.5

Notes. The samples are shown in Figure 5.

We use the following notations:— V_{rot} and σ_{disp} are the rotation velocity and velocity dispersion, respectively, across all resolution elements— $V_{\text{rot,flat}}$ and $\sigma_{\text{disp,ext}}$ are the rotation velocity and velocity dispersion, respectively, computed beyond/at the specified radius.

Table 4
PVsplit Parameter Values Derived for SPT2349-56

Source	$P_{ m major}$	$P_{ m V}$	P _R Mergers	Classification
		Disks <0 < Mergers	$0 \leftrightarrow 1$ Disks	
C1 (A)	-1.47	-1.18	0.30	Disturbed disk
C2 (J)	-1.62	-0.85	0.16	Disturbed disk
C3 (B)	-2.64	-0.52	0.41	Disk
C4 (D)	-1.32	-0.62	0.35	Disturbed disk
C5 (F)	-1.32	-0.55	0.42	Disturbed disk
C6 (C)	-2.33	-0.50	0.19	Disturbed disk
C7 (K)	-1.63	-0.40	0.35	Disturbed disk

suggesting an imminent collapse of unstable disks. Source C6, found in the central region of the core, appears to be extremely compact in its moment-0 map with low Q_T values, suggesting unresolved substructuring at our spatial resolution.

Figure 6 shows disk stability as a function of the V/σ ratio. Sources C1 and C4 show rotation support with a stable disk, while the rest of the sources show rotation support with unstable disks. There is a mild positive correlation between disk stability with respect to dynamical support, with a Pearson-r coefficient of \approx 0.19. In order to further explore the nature of these sources using their morphology, we utilize a newly developed tool, PVsplit (F. Rizzo et al. 2022).

5.3. PVsplit

In light of low-resolution data and its role in the incorrect kinematic classification of galaxies at high redshift, F. Rizzo et al. (2022) have developed a new tool, PVsplit. This method utilizes p-v maps instead of moment maps to quantify the morpho-kinematic nature of galaxies using three empirical parameters, provided that there are at least three independent elements and SNR \geqslant 10 across all the elements. The three parameters are defined as follows:

- (1) $P_{\rm major}$: asymmetry of the major-axis slice with respect to the systemic velocity of the source; disks $\leq 0 <$ mergers
- (2) P_V : distribution of the emission peak along the velocity axis; disks <0< mergers
- (3) P_R : distribution of the emission peak along the position axis; disks: closer to 1, mergers: closer to 0.

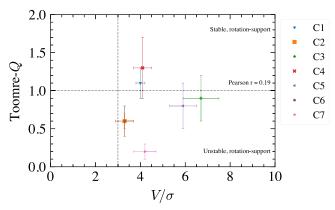


Figure 6. The Toomre parameter plotted against the V/σ ratio. The dashed line at $Q_{\rm T}=1$ marks the stability criteria, while the dashed line at $V/\sigma=3$ marks the rotation-to-dispersion transition. Note that the markers for sources C2 and C6 overlap.

Applying Equations (6), (7), and (8) in F. Rizzo et al. (2022) to our $p-\nu$ maps, we present the results for our sample in Table 4 and Figure 7. Targets in our sample do not meet the criteria for SNR, but we nevertheless apply the method since it gives valuable insights into the dynamical classification of the systems. The dividing plane in Figure 7 is obtained using $-0.63P_{\rm major}-0.27P_{\rm V}+2.78P_{\rm R}-2.72=0$ (F. Roman-Oliveira et al. 2023).

Comparing Figure 7 with Figure 17 in F. Rizzo et al. (2022), it is immediately apparent that our sample occupies the same space as those of disturbed disks and mergers. Based on the definitions of $P_{\rm major}$ and $P_{\rm V}$, we find from Table 4 that all the sources satisfy conditions for being "disk-like." This implies two things—first, the sources are symmetric about the systemic velocity; second, the emission is either slightly spread out along the LOS velocities or concentrated closer to the systemic velocity. Lastly, based on the intensity distribution along the position axis ($P_{\rm R}$) and the best-dividing plane, we find that only source C3 identifies as a disk in our sample.

A possible explanation for the differences in classifications obtained via dynamical analysis (Section 5.1.3) and PVsplit is tidal torques. In a highly overdense environment like that of a protocluster core, tidal torques can induce a velocity gradient across the galaxy, along with an asymmetric gas accumulation (B. Gullberg et al. 2019; A. M. Martínez-García et al. 2023). From column (4) in Figure 3, we know that the sources display double-peaked spectra with varying degrees of asymmetry arising from the corresponding asymmetric gas distributions.

^a The studies chosen depend on two criteria—(i) It uses 3D kinematic modeling methods, (ii) It uses an ionized tracer.

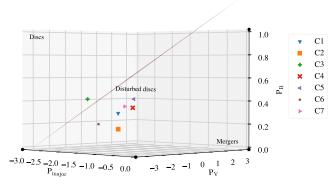


Figure 7. Results of the PVsplit tool. The 2D plane separates the mergers and disks. A 3D representation of this plot, with the same elevated viewing angle but different azimuthal viewing angles $(0^{\circ}-360^{\circ})$, is available online. (An animation of this figure is available in the online article.)

This interpretation also supports the low Toomre-Q values obtained in Section 5.2. We therefore find that at this resolution and sensitivity, our sample adheres to the "disturbed disks" region, despite the high V/σ values, i.e., they present with strong kinematic signatures and moderate morphological disturbances.

5.4. Rotating Disks in a Protocluster Core

The number of observations describing the presence of cold rotating disk galaxies at high redshift (A. Pillepich et al. 2019; M. Neeleman et al. 2020; F. Rizzo et al. 2020; F. Fraternali et al. 2021) is already challenging our current theories of galaxy evolution. In our case, we have found six seemingly well-ordered disks packed in an extreme environment containing 23 galaxies with average velocity $v = 360 \, \mathrm{km \ s^{-1}}$ (R. Hill et al. 2020) within a radius of $\approx 100 \, \mathrm{kpc}$. At z = 4.303, the age of the Universe is 1.4 Gyr. From P. Murdin (2001), the crossing time for the protocluster core is

$$t_{\rm cr} = \frac{R}{v} = \frac{100 \,\mathrm{kpc}}{360 \,\mathrm{km \, s^{-1}}} = 0.28 \,\mathrm{Gyr},$$

while the relaxation time is

$$t_{\rm r} = t_{\rm cr} \frac{N}{8 \ln N} = 0.27 \frac{23}{8 \ln 23} = 0.25 \text{ Gyr.}$$

In a protocluster system that is around 1 Gyr old (inferred from the stellar population, see K. M. Rotermund et al. 2021), we have $t_{\rm cr} \approx t_{\rm r}$, meaning that the galaxies are losing energy via collisions every 0.27 Gyr; i.e., they very likely had a close interaction within their lifetime, suggesting that their gaseous disks should be disturbed, clearly evident in Figure 7.

Explanations other than that of tidal torques in an overdense environment for ordered motion are that the disks are able to immediately recover after an interaction, or that the disks are simply so massive that a strong interaction does not affect its stability, or that the classical definitions strongly depend on the SNR of the source.

Numerical simulations of the SPT2349-56 protocluster system provide further evidence that the galaxies are undergoing strong interactions at a timescale of ≈ 0.5 Gyr (D. Rennehan et al. 2020). However, R.-S. Remus et al. (2023) present results from the Magneticum simulation, wherein they reproduce the fast-rotating galaxies at the protocluster core, suggesting that the disks need not be completely destroyed even if they experience close interactions. This is also supported by recent observations

of interacting galaxies in group environments at high redshift, where the kinematics traced by [CII] observations show well-ordered rotating disks, albeit in less dense environments (I. Oteo et al. 2016; F. Roman-Oliveira et al. 2023). Despite this possible evidence of another galaxy group presenting with ordered disks in its environment, we lack evidence to state whether the phenomenon of rotating disks in such environments is an outlier or the norm.

6. Conclusion

In this paper, we have presented kiloparsec-scale resolution ALMA observations of the [C II] 158 μ m transition of galaxies within the SPT2349–56 protocluster system at $z\approx 4.3$. Previous works describe the identification, multiwavelength studies, and forward simulations of the system (T. B. Miller et al. 2018; R. Hill et al. 2020, 2022; D. Rennehan et al. 2020; K. M. Rotermund et al. 2021), and here we report the kinematics of the constituent galaxies. The results are summarized as follows:

- 1. The [C II] emission of our sample of the seven submillimeter-bright galaxies is reproduced well using differentially rotating models with a thin-disk assumption.
- 2. The mean inclination-corrected rotation velocity of the sample is $V_{\rm rot} = 357.1 \pm 114.7 \, \rm km \, s^{-1}$, and individual values between 170 and 475 km s⁻¹.
- 3. The mean intrinsic velocity dispersion of the sample is $48.4\pm23.5\,km\,s^{-1},$ and individual values between 10 and $100\,km\,s^{-1}.$
- 4. On the basis of criteria found across literature, we find evidence for six rotating disks and one possible major merger at z = 4.303 within a protocluster environment.
- 5. The mean Toomre parameter for the sample is $Q_{\rm T} = 0.9 \pm 0.3$, where sources C1 and C4 are stable rotating systems, while the remaining sources classify as unstable rotating disks.
- 6. Analyzing the p– ν maps to further study the morphokinematic nature of these sources, we find evidence for disk disturbance in regions $<10\,\mathrm{kpc}$, supporting the low Toomre-Q values and high V/σ values. That is, the sources are observed as disturbed rotating disks characterized by an asymmetric gas distribution.

Overall, we find that the dynamical properties of the galaxies in our sample show considerable similarity to a number of other observations at a similar redshift. The main difference is that of morphology and the environment—while the comparison samples are not associated with turbulent environments, our galaxies exist in a highly active protocluster system that in itself has several unique properties.

Acknowledgments

This paper makes use of the following ALMA data: ADS/JAO.ALMA#2018.1.00058.S. ALMA is a partnership of ESO (representing its member states), NSF (USA) and NINS (Japan), together with NRC (Canada), MOST and ASIAA (Taiwan), and KASI (Republic of Korea), in cooperation with the Republic of Chile. The Joint ALMA Observatory is operated by ESO, AUI/NRAO and NAOJ. The National Radio Astronomy Observatory is a facility of the National Science Foundation operated under cooperative agreement by Associated Universities, Inc. The authors would like to thank E. M.

Teodoro for the many useful discussions about using ^{3D}BAROLO. M.A. acknowledges support from FONDECYT grant 1211951, ANID+PCI+INSTITUTO MAX PLANCK DE ASTRONOMIA MPG 190030, ANID+PCI+REDES 190194 and ANID BASAL project FB210003.

Facility: ALMA.

Software: Astropy (Astropy Collaboration et al. 2013, 2018), CASA (J. P. McMullin et al. 2007), ^{3D}BAROLO (E. M. D. Teodoro & F. Fraternali 2015).

Appendix A Initial Values and Parameter File for Kinematic Fitting

Table 5 presents the number of rings used per source, along with the initial guess for $V_{\rm rot}$, $\sigma_{\rm disp}$, ϕ , and i determined using the methods described in Section 3.2. Tables 6 and 7 show the sample parameter files used in the SEARCH and 3DFIT tasks. Keywords with blank keywords are those that change with respect to the source and take values provided in Tables 1 and 5. Further information about the keyword units can be found in E. Di Teodoro (2015).

Source	NRADII	VROT	VDISP	PA	INC
C1 (A)	10	612	147	237	67
C2 (J)	8	212	65	110	49
C3 (B)	6	408	227	89	47
C4 (D)	7	448	100	318	58
C5 (F)	8	540	150	179	64
C6 (C)	6	218	96	316	46
C7 (K)	9	175	81	12	53

Table 6
Keywords and Values for the SEARCH Task

Keyword	Value
SEARCH	true
FLAGROBUSTSTATS	false
ITERNOISE	true
SEARCHTYPE	spatial
SNRCUT	0
THRESHOLD	0.00250050
FLAGGROWTH	true
GROWTHCUT	0
GROWTHTHRESHOLD	0.00100020
MINPIX	1
MINCHANNELS	5
FLAGADJACENT	true
THRESHSPATIAL	1
THRESHVELOCITY	1
REJECTBEFOREMERGE	true
TWOSTAGEMERGING	true

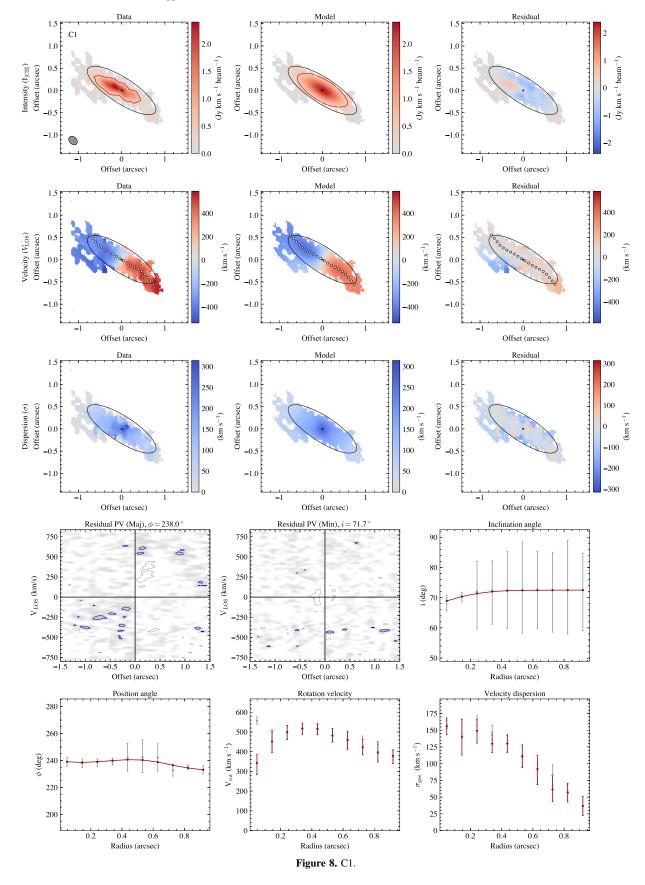
Table 7
Keywords and Values for the 3DFIT Task

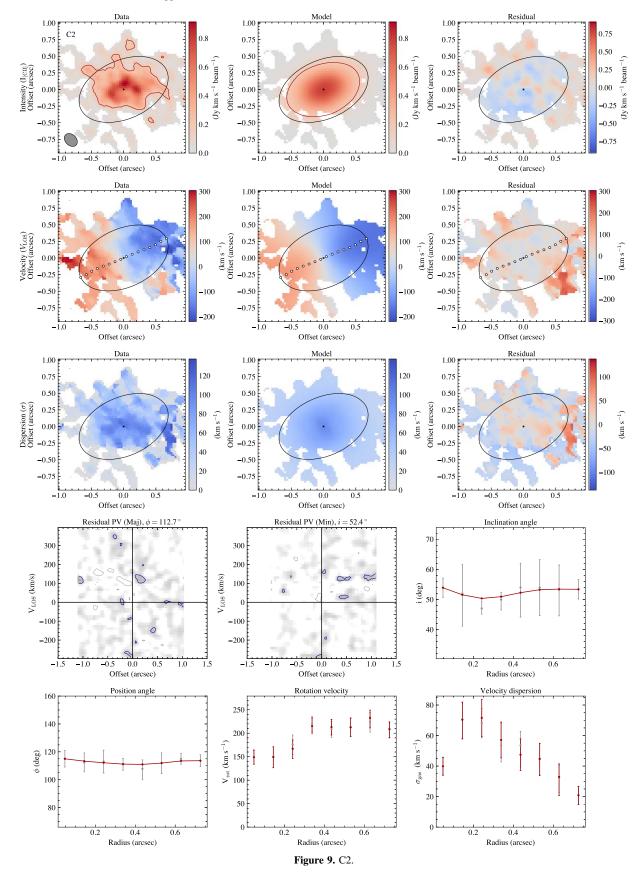
3DFIT true NRADII RADSEP 0.0968 XPOS YPOS VSYS VROT VRAD 0 VDISP INC PA Z0 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.00001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false	Keyword	Value
RADSEP 0.0968 XPOS YPOS VSYS VROT VRAD 0 VDISP INC PA Z0 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.00001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NORMALCUBE false	3DFIT	true
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YPOS VSYS VROT VRAD 0 VDISP INC PA ZO 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.00001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NORMALCUBE false	RADSEP	0.0968
VSYS VROT VRAD 0 VDISP INC PA ZO 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NORMALCUBE false	XPOS	•••
VROT VRAD 0 VDISP INC PA ZO 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NORMALCUBE false	YPOS	•••
VRAD 0 VDISP INC PA ZO 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	VSYS	•••
VDISP INC PA ZO 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	VROT	•••
INC PA ZO 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	VRAD	0
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ZO 0.029 FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	INC	•••
FREE vrot vdisp pa inc MASK search NORM azim TWOSTAGE true REGTYPE bezier REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	PA	•••
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REVERSE false LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	TWOSTAGE	true
LINEAR 0.42466 SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	REGTYPE	bezier
SIDE B FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	REVERSE	false
FLAGERRORS true ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	LINEAR	0.42466
ADRIFT false DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	SIDE	В
DELTAINC 5 DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	FLAGERRORS	true
DELTAPA 5 FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	ADRIFT	false
FTYPE 1 TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	DELTAINC	5
TOL 0.0001 WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	DELTAPA	5
WFUNC 2 LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	FTYPE	1
LTYPE 3 CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	TOL	0.0001
CDENS 10 BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	WFUNC	2
BIWEIGHT 3 STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	LTYPE	3
STARTRAD 0 PLOTMASK false NOISERMS 0 NORMALCUBE false	CDENS	10
PLOTMASK false NOISERMS 0 NORMALCUBE false	BIWEIGHT	3
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NORMALCUBE false	PLOTMASK	false
	NOISERMS	
BADOUT false	NORMALCUBE	false
	BADOUT	false

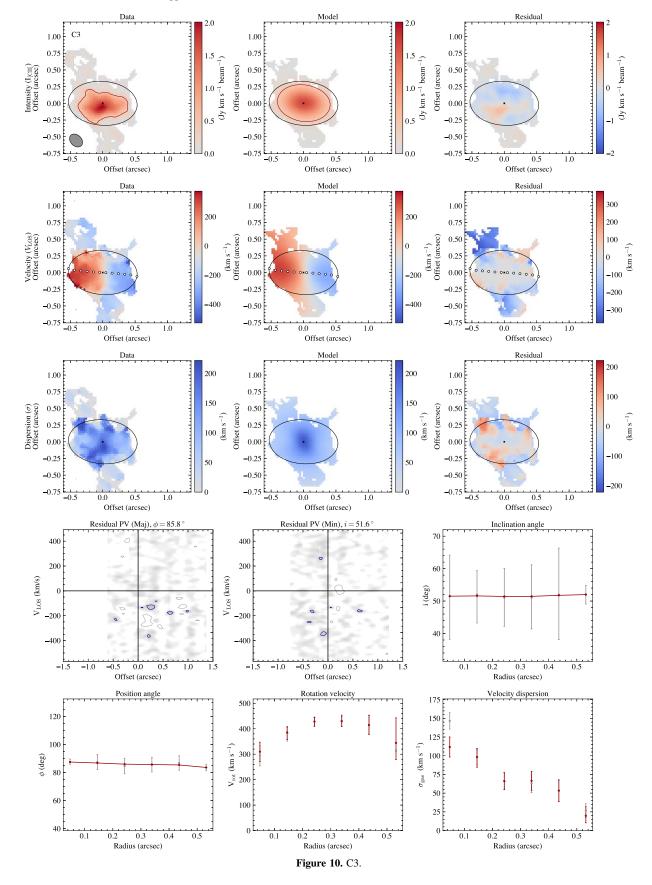
Appendix B Kinematic Modeling Results

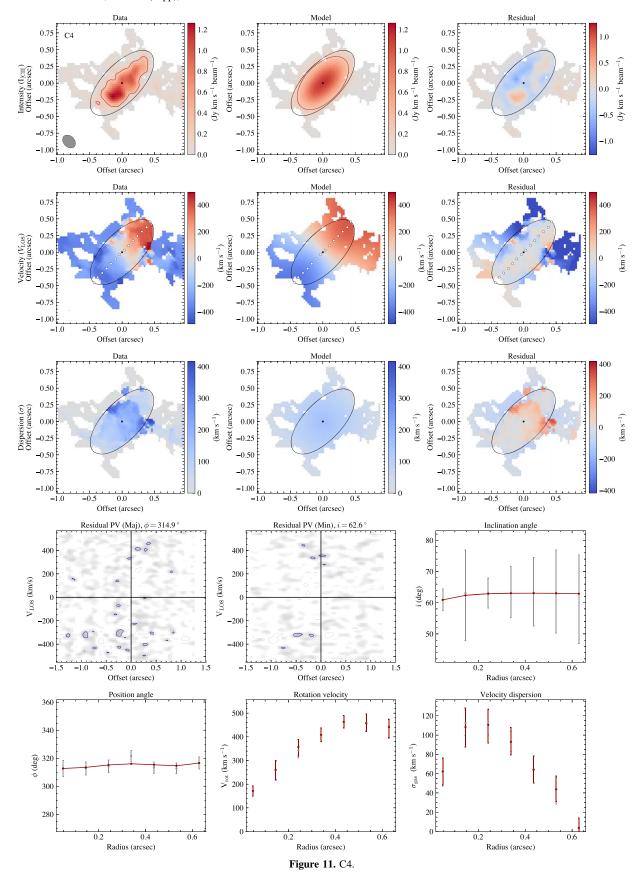
Here, we show the results from the kinematic modeling using the 3DFIT task. Each source is shown in a $2'' \times 2''$ ($3'' \times 3''$ for C1) cutout as follows:

- (1) Row 1 shows the data, model, and residual moment-0 map. The black cross marks the kinematic center, and the black ellipse denotes the maximum radius of analysis. The elliptical 0.225×0.166 beam is shown in the bottom-left corner. The red contour is at a 0.2% [C II]_{peak}.
- (2) Row 2 shows the data, model, and residual moment-1 map. Here, the moment-1 map is the LOS rotation velocity map corrected for the systemic velocity with respect to z = 4.303. The white circles mark the kinematic major axis of the galaxy (ϕ) .
- (3) Row 3 shows the data, model, and residual moment-2 map, not corrected for beam smearing.

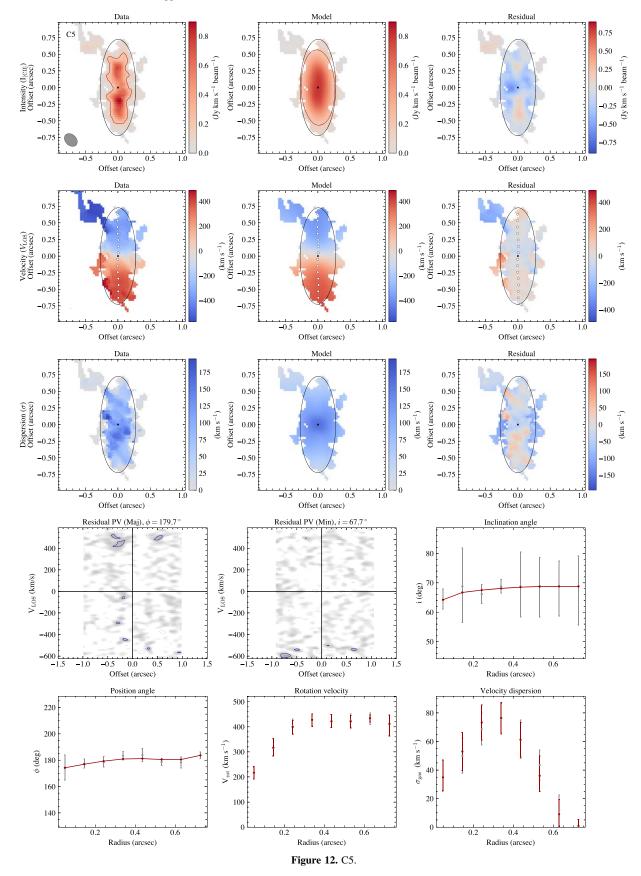


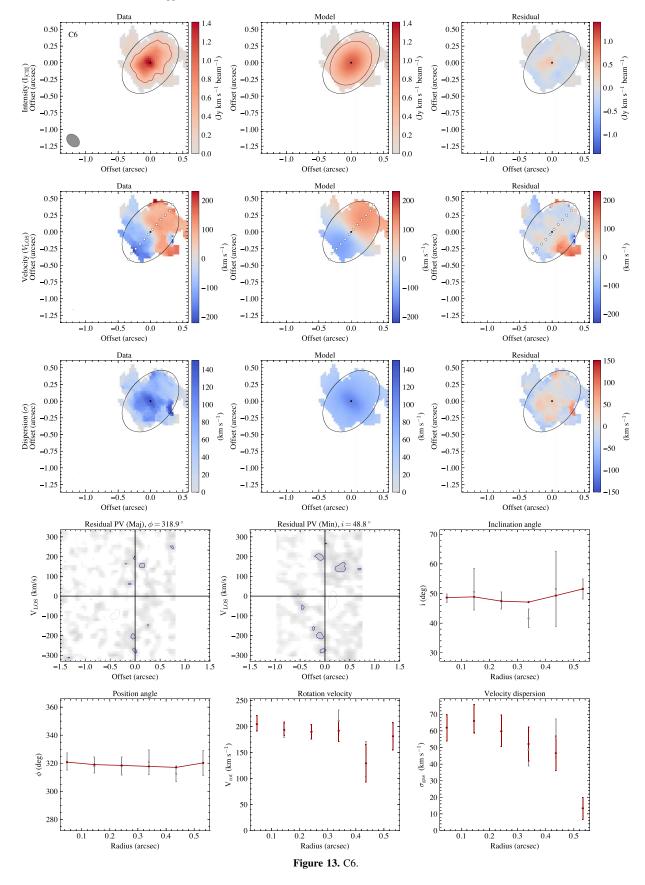


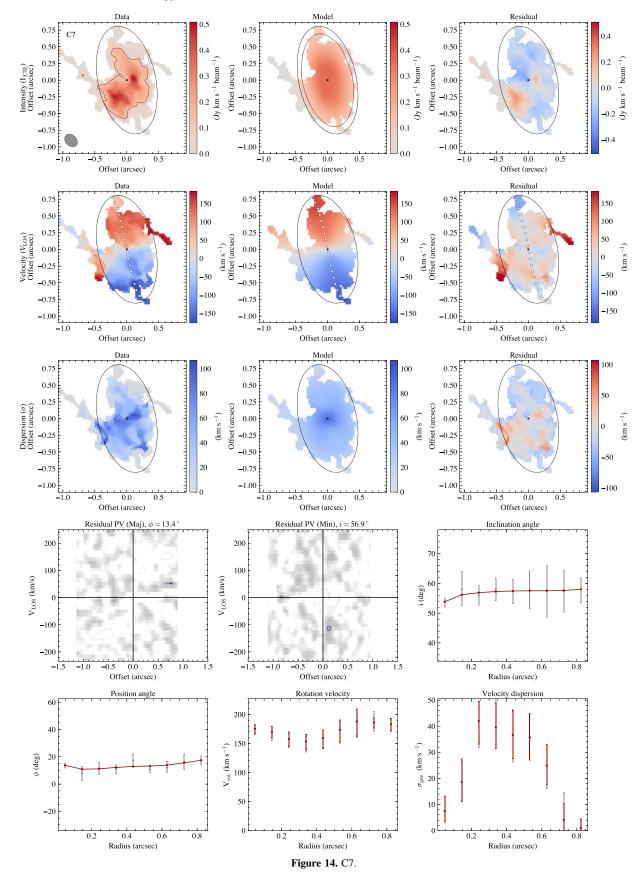




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- (4) Row 4, columns (1) and (2) are the residual major-axis and minor-axis p-v maps, extracted along ϕ and $\phi-90^\circ$, respectively. The blue contours are at $3\sigma_{\rm [C~II],rms}$, and the gray contours are at $-3\sigma_{\rm [C~II],rms}$.
- (5) Row 4, column (3) shows the inclination angle fitting. The first stage is shown in gray, while the second stage is in red.
- (6) Row 5 shows the position angle, rotation velocity, and velocity dispersion fitting in columns (1), (2), and (3), respectively. The first stage is shown in gray, and the second stage is shown in red.

In all images, north is up and east is to the left.

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