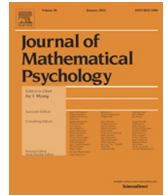




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# The philosophy of Bayes factors and the quantification of statistical evidence

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## HIGHLIGHTS

- We discuss the general philosophical concept of evidence, connecting it to statistics.
- We outline how statistical evidence can be quantified using the Bayes factor.
- We discuss the philosophical details and difficulties in using the Bayes factor.

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## ABSTRACT

A core aspect of science is using data to assess the degree to which data provide evidence for competing claims, hypotheses, or theories. Evidence is by definition something that should change the credibility of a claim in a reasonable person's mind. However, common statistics, such as significance testing and confidence intervals have no interface with concepts of belief, and thus it is unclear how they relate to statistical evidence. We explore the concept of statistical evidence, and how it can be quantified using the Bayes factor. We also discuss the philosophical issues inherent in the use of the Bayes factor.

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A core element of science is that data are used to argue for or against hypotheses or theories. Researchers assume that data – if properly analyzed – provide evidence, whether this evidence is used to understand global climate change (Lawrimore et al., 2011), examine whether the Higgs Boson exists (Low, Lykken, & Shaughnessy, 2012), explore the evolution of bacteria (Barrick et al., 2009), or to describe human reasoning (Kahneman & Tversky, 1972). Scientists using statistics often write as if evidence is quantifiable: one can have no evidence, weaker evidence, stronger evidence—but importantly, statistics in common use do not readily admit such interpretations. The use of significance tests and confidence intervals are cases in point (Berger & Sellke, 1987; Berger & Wolpert, 1988; Jeffreys, 1961; Wagenmakers, Lee, Lodewyckx, & Iverson, 2008). Instead, these statistics are designed to make decisions, such as rejecting a hypothesis, rather than providing for a measure of evidence. Consequently, statistical practice is beset by a difference between what statistics provide and what is desired from them.

In this paper, we explore a statistical notion that does allow for the desired interpretation as a measure of evidence: the Bayes factor (Good, 1979, 1985; Jeffreys, 1961; Kass & Raftery, 1995). Our central claim is that the computation of Bayes factors is an appropriate, appealing method for assessing the impact of data on the evaluation of hypotheses. Bayes factors present a useful and meaningful measure of evidence.

To arrive at the Bayes factor, we explore the concept of evidence more generally in Section 1. We make a number of reasoned choices for an account of evidence, identify certain properties that should be reflected in our account, and then show that an account using Bayes factors fits the bill. In Section 2.1 we give a detailed introduction into Bayesian statistics and the use of Bayes factors, giving particular attention to certain conceptual issues. In Section 3 we offer some examples of the use of Bayes factors as measure of evidence, and in Section 4 we consider critiques of this use of Bayes factors and difficulties inherent in their application.

## 1. Evidence

What is evidence? Our answer is that the evidence presented by data is given by the impact that the data have on our evaluation of

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a theory (e.g., Fox, 2011).<sup>1</sup> In what follows we develop an account that ties together three central notions in this answer (theory, evaluation, and the impact of data) and then motivate the use of Bayes factors in statistics. One important caveat: our exposition falls far short of a fully worked out theory of evidence, and we do not offer a defense of Bayes factors as the only statistical measure of it. We cannot treat evidence or Bayes factors in sufficient generality and detail to warrant such wide-scope conclusions; there may well be other suitable measures, e.g., model selection tools. We argue that Bayes factors reflect the key properties of a particular conception of evidence but we do not assess the competition.

### 1.1. Theory: empirical hypotheses

One possible goal of scientific inquiry is instrumental: it is enough to predict and control the world by means of some scientific system, e.g., a theory or a prediction device. The format of such a system is secondary to the goal. In particular, there is no reason to expect that system will employ general hypotheses on how the world works, or that it will involve evaluations of those hypotheses. But another important goal of science is epistemic: science offers us an adequate representation of the world, or at least one that lends itself for generating explanation as well as prediction and control. For such purposes, the evaluation of hypotheses seems indispensable. Of course, a system used for prediction and control might include evaluations of hypotheses as well. Our point is that in an instrumentalist view of science an evaluative mode (e.g., an interface with beliefs) is not mandatory while in an epistemic view it is.

The idea that scientific inquiry has epistemic implications is common among scientists. One important example of recent import is the debate over global climate change. The epistemic nature of this debate is hard to miss. Much attention has been given, for instance, to the *consensus* of climate scientists; that is, that nearly all climate scientists believe that global climate change is caused by humans. The available data is assumed to drive climate scientists' opinions; the fact of consensus then drives public opinion and policy on the topic. Those not believing with the consensus are called, pejoratively, "deniers" (Dunlap, 2013). It seems safe to say that we cannot altogether do away with epistemic goals in science.

An epistemic goal puts particular constraints on the format of scientific theory: it will have to allow for evaluations of how believable or plausible the theory is, and it must contain components that represent nature, or the world, in some manner. We call those components hypotheses.<sup>2</sup> There is a large variety of structures that may all be classified as hypotheses in virtue of their role in representing the world. A hypothesis might be a distinct mechanism, the specification of a type of process, a particular class of solutions to some system of equations, and so on. For all hypotheses, however, an important requirement is that they entail predictions of data. Scientists would regard a hypothesis that has no empirical consequences as problematic. Moreover, it is a deeply seated conviction among many scientists that the success of a theory should be determined on the basis of its ability to predict the data. In short, the hypotheses must have empirical content.

<sup>1</sup> Although there is a large debate within the philosophy of science about the relation between data, facts, phenomena, and the like (e.g., Bogen & Woodward, 1988), we will align ourselves with scientific practice here and simply employ the term "data" without making further discriminations. It will lead us too far afield to add further considerations.

<sup>2</sup> In the philosophy of science literature, those structures are often referred to as models. But in a statistical context models have a specific meaning: they are sets of distributions over the sample space that serve as input to a statistical analysis. To avoid confusion when we introduce statistical models later, we use the term "hypotheses".

The foregoing claims may seem completely trivial to our current readers. However, they are all subject to controversy in the philosophy of science. There are long-standing debates on the nature, the use and the status of scientific theory. It is far from clear that scientific hypotheses are intended to represent something, and that they always have empirical content.<sup>3</sup> And a closer look at science also gives us a more nuanced view. Consider a statistical tool like principal component analysis, in which the variation among data points is used to identify salient linear combinations of manifest variables. Importantly, this is a data-driven technique that does not rely on any explicitly formulated hypothesis. The use of neural networks and other data-mining tools for identifying empirical patterns are also cases in point, certainly when these tools are seen merely as pattern-seeking devices. The message here is that scientific theory need not always have components that do representational work. However, the account of evidence that motivates Bayes factors does rely on hypotheses as representational items, and does assume that these hypotheses have empirical content.<sup>4</sup>

### 1.2. Evaluations: belief and probability

As we have argued, the epistemic goals of science lead to a particular understanding of scientific theory: it consists of empirical hypotheses that somehow represent the world. Within statistical analysis, we indeed find that theory has this character: statistical hypotheses are distributions that represent a population, and they entail probability assignments over a sample space.<sup>5</sup> A further consequence of taking science as an epistemic enterprise was already briefly mentioned: scientific theory must allow for evaluations, and hence interface with our epistemic attitudes. These attitudes include expectations, convictions, opinions, commitments, assumptions, and more. But for ease of reference we will simply speak of beliefs in what follows. Now that we have identified the representational components of scientific theory as hypotheses, the requirement is that these hypotheses must feature in our beliefs. And our account of evidence must accommodate such a role.

The exact implications of the involvement of belief depend on what we take to be the nature of beliefs, and on the specifics of the items featuring in it. There are many ways of representing both the beliefs and the targets of beliefs. For example, when expressing the strength of our adherence to a belief we might take them as categorical, e.g., dichotomous between accepted and rejected, or graded in some way or other. Moreover, the beliefs need not concern the hypothesis in isolation. In an account of evidence, the beliefs might just as well pertain to relations between hypotheses and data. Consequently, the involvement of beliefs does not, by itself, impose that we assign probabilities to hypotheses. And it does not entail the use of Bayesian methods to the exclusion of others either. Numerous interpretations of, and add-ons to, classical statistics have been developed to accommodate the need for an epistemic interpretation of results (for an overview see Romeijn, 2014).

<sup>3</sup> See, e.g., Bird (1998) and Psillos (1999) for introductions into the so-called realism debate.

<sup>4</sup> Clearly this leaves open other motivations for using Bayes factors to evaluate neural networks and the like. Moreover, data-driven techniques are often used for informal hypothesis generation. While the formal evidence evaluation techniques discussed here may not be appropriate for such exploratory techniques, they may be appropriate for later products of such techniques.

<sup>5</sup> Notice that the theoretical structure from which the statistical hypotheses arise may be far richer than the hypotheses themselves, involving exemplars, stories, bits of metaphysics, and so on. In the philosophy of statistics, there is ongoing debate about the exact use of this theoretical superstructure, and the extent to which it can be detached from the empirical substructure. Romeijn (2013) offers a recent discussion of this point, placing hierarchical Bayesian models in the context of explanatory reasoning in science.

Be that as it may, in our account we choose for a distinct way of involving beliefs. First consider the representation of the items about which we have beliefs, e.g., whether we frame our beliefs as pertaining to sentences or events. A fully general framework, which we will adopt here, presents beliefs as pertaining to elements from an algebra that represents events in, or facts about, a target system. Next consider the beliefs themselves—predictions, expectations, convictions, commitments. They can be formalized in terms of a function over the algebra, like truth values or more fine-grained formalizations, e.g., degrees of belief, imprecise probabilities, plausibility orderings and so on (see Halpern, 2003, for an overview). It seems inevitable that any such function will impose its own constraints on what can be captured. Fortunately there are very convincing arguments for capturing beliefs about hypotheses in terms of probability assignments over an algebra (Cox, 1946; de Finetti, 1995; Joyce, 1998; Ramsey, 1931). In our account we follow this dominant practice.

Our choice for probability assignments suggests a particular way of formalizing the empirical evaluation of hypotheses. We express beliefs by a probability over an algebra, so items that obtain a probability, like data and possibly also hypotheses, are elements of this algebra. The relation between a hypothesis, denoted  $\mathbf{h}$ , and data, denoted  $\mathbf{y}$ , will thus be captured by certain valuations of the probability function. As will become apparent below, a key role is reserved for the probability of the data on the assumption of a hypothesis, written  $p_{\mathbf{h}}(\mathbf{y})$ , or  $p(\mathbf{y} | \mathbf{h})$  depending on the exact role given to hypotheses.<sup>6</sup>

Notice that the use of probability assignments puts further constraints on the nature of the empirical hypotheses: they must specify a distinct probability assignment over possible data, i.e., the hypothesis must be *statistical*. This means that if the hypothesis under consideration is composite – meaning that it consists of a number of different distributions over the sample space – we must suppose a probability assignment over these distributions themselves in order to arrive at a single-valued probability assignment over the sample space. This is simply a requirement for building up a probabilistic account of evidence.<sup>7</sup>

Let us take stock. We have argued that our account of evidence involves beliefs concerning hypotheses. These beliefs are determined by the relations that obtain between hypotheses and data, and probability assignments offer a natural means for expressing these beliefs. Against this background, we will now investigate the role of data, and thereby identify two key properties for our notion of evidence.

### 1.3. Impact of data: relative and relational

The evaluation of empirical hypotheses goes by a confrontation with the data. But how precisely do the data engage in our beliefs towards hypotheses, and so function as evidence? The data – in the context of statistics, dry database entries – do not present evidence

all by themselves. They only do so because, as we said, they impact on our beliefs about hypotheses. We turn to this idea of impact, to single out two properties that are central to our account of evidence: it is relational and relative. By relational, we mean that evidence is fundamentally about the relation between data and hypotheses, and not data alone; by relative, we mean that evidence for or against a hypothesis can only be assessed relative to another hypothesis.

First consider the relational nature of evidence. We might assess the evidence by offering an account of the evidential value of data taken in isolation. By contrast, we might also assess the evidence as a relation between hypothesis and data, e.g., by forming a belief regarding the support that the data give to the hypothesis. The notion of support clearly pertains to the relation between hypothesis and data, and this is different from an assessment that only pertains to the data as such. We prefer a relational notion of evidence in our account, namely one that is based on support relations.

In general, the support relation will be determined by how well hypotheses and data are aligned. We like to think about this alignment, and hence support relation, in terms of predictive accuracy. That is, hypotheses may be scored and compared according to how well they predict the data. In statistics, this is often done simply by the probability that the hypothesis assigns to the data, the so-called likelihood, written  $p(\mathbf{y} | \mathbf{h})$ . As will become apparent in the next section, precisely this particular use of predictive accuracy drops out of the choices for the account of evidence that we have made in the previous sections.<sup>8</sup>

As an aside, notice that predictions based on a hypothesis have an epistemic nature – they are expectations – but that their standard formalization in terms of probability is often motivated by the probabilistic nature of something non-epistemic: statistical hypotheses pertain to frequencies or chances, and the latter can be represented by probability theory as well. The use of predictions for evaluating hypotheses thus involves two subtle conceptual steps. The probability  $p(\mathbf{y} | \mathbf{h})$  refers to a chance or a frequency, which is then turned into an epistemic expectation, i.e., a prediction, and subsequently taken as a score that expresses the support for the hypothesis by the data.

Next consider the relative, or comparative, nature of evidence. Note that support can be considered in absolute or in relative terms. We might conceive of the support as something independent of the theoretical context in which the support is determined: we base the support *solely* on how well the hypothesis under scrutiny aligns with the data, where this predictive performance is judged independently of how well other hypotheses – which may or may not be under consideration – predict those data. By contrast, we might also conceive of support as an essentially comparative affair. We might say one hypothesis is better supported by the data than another because it predicts the data better, without saying anything about the absolute support that either receives from the data.

We think the comparative reading fits better with our intuitive understanding of support, namely as something context-sensitive, so we take this as another desideratum for our account of evidence. The data do not offer support in absolute terms: they only do so relative to rival hypotheses. Imagine that the hypothesis  $\mathbf{h}$  predicts the empirical data  $\mathbf{y}$  with very high probability. We will only say that the data  $\mathbf{y}$  support the hypothesis  $\mathbf{h}$  if other hypotheses  $\mathbf{h}'$  do not predict the same data equally well. If the other hypotheses also predict the data, perhaps because it is rather easy to predict

<sup>6</sup> Classical statisticians might object to the appearance of  $\mathbf{h}$  within the scope of the probability function  $p$ . If viewed as a function of the hypothesis, this expression is referred to as the (marginal) likelihood of the hypothesis  $\mathbf{h}$  for the (known and fixed) data  $\mathbf{y}$ .

<sup>7</sup> For instance, if we are interested in the probability  $\theta$  that an unfair coin lands with heads showing, then the hypothesis  $\theta > 1/2$ , which specifies that the coin is biased towards heads, is such a composite hypothesis. Each possible value for  $\theta$  implies a different sampling distribution over the number of heads. In addition to these sampling distributions we must have a weighting over all possible  $\theta$  values. Without such a weighting, typically a probability assignment, over these component distributions the aggregated or so-called marginal likelihood of the hypothesis cannot be computed, thereby leaving the empirical content of the composite hypothesis underspecified. Of course this invites further questions over the status of these marginal likelihoods but we cannot delve into these questions here.

<sup>8</sup> Following the recent interest in what is termed accuracy-first epistemology (e.g. Joyce, 1998; Pettigrew, 2013), it also aligns well with the epistemic goals of science.

them, then it seems that those data do not offer support either way. Conversely, if the data are surprising in the sense that they have a low probability according to all the other hypotheses under consideration, then still, they are only surprising relative to those other hypotheses. Hence, although we admit that more absolute notions of evidence can be conceived, our notion of support, and thereby of evidence, depends on what candidate hypotheses are being considered.

Summing up, we have now argued that data present evidence insofar as they impact on our beliefs about hypotheses, that this impact is best understood as relative support, and that it can be measured by a comparison among hypotheses of their predictive success. In what follows we will integrate these insights into an account of evidence and argue that Bayes factors offer a natural expression of this kind of evidence.

#### 1.4. Bayes factors

Let us return to the conception of evidence that was sketched at the start of this section: the evidence presented by the data is the impact that these data have on our evaluation of theory.<sup>9</sup> In the foregoing we have put in place conceptions of theory, evaluation, and the impact of data. In this section we assemble the pieces.

As indicated, we look at the way in which data impact on the evaluation of hypotheses, denoted  $\mathbf{h}_i$ . The evidence presented by the datum  $\mathbf{y}$  can thus be formalized in terms of the change in the probability that we assign to the hypotheses, i.e., the change in the probability prior and posterior to receiving the datum. To signal that these probabilities may be considered separate from the probability assignments  $p(\mathbf{y})$  over the sample space, we denote priors and posteriors as  $\pi(\mathbf{h}_i)$  and  $\pi(\mathbf{h}_i | \mathbf{y})$  respectively. A natural expression of the change between them is the ratio of prior and posterior.

The use of probability assignments over hypotheses means that we opt for a Bayesian notion of evidence. As is well known, Bayes' rule relates priors and posteriors as follows:

$$\pi(\mathbf{h}_i | \mathbf{y}) = \frac{p(\mathbf{y} | \mathbf{h}_i)}{p(\mathbf{y})} \pi(\mathbf{h}_i),$$

where we often write  $\pi(\mathbf{h}_i | \mathbf{y}) = \pi_{\mathbf{y}}(\mathbf{h}_i)$  to express that the posterior probability over the hypotheses is a separate function. In the above expression, the notion of evidence hinges entirely on the likelihoods  $p(\mathbf{y} | \mathbf{h}_i)$  for the range of hypotheses  $\mathbf{h}_i$  that are currently under consideration. In order to assess the relative evidence for two hypotheses  $h_i$  and  $h_j$ , we may focus on the ratio of priors and posteriors for two distinct hypotheses:

$$\frac{\pi_{\mathbf{y}}(\mathbf{h}_i)}{\pi_{\mathbf{y}}(\mathbf{h}_j)} = \frac{p(\mathbf{y} | \mathbf{h}_i)}{p(\mathbf{y} | \mathbf{h}_j)} \times \frac{\pi(\mathbf{h}_i)}{\pi(\mathbf{h}_j)}.$$

The crucial term – the one that measures the evidence – is the ratio of the probabilities of the data  $\mathbf{y}$ , conditional on the two hypotheses that are being compared. This ratio is known as the Bayes factor.

We can quickly see that the Bayes factor has the properties discussed in the foregoing, and that this reinforces our view that Bayes factors are a suitable expression of evidence. Obviously, the ratio

$$\frac{p(\mathbf{y} | \mathbf{h}_i)}{p(\mathbf{y} | \mathbf{h}_j)}$$

<sup>9</sup> See Kelly (2014) for a quick presentation and some references to a discussion on the merits of this approach to evidence. Interestingly, others have argued that we can identify the meaning of a linguistic expression with the impact on our beliefs (cf. Veltman, 1996). This is suggestive of particular parallels between the concepts of evidence and meaning, but we will not delve into these here.

involves our beliefs concerning empirical hypotheses. More specifically, it directly involves an expression for the empirical support for the hypotheses, and so the notion of evidence is relational. Support is expressed by predictive accuracy, in particular by the probability of the observed data under the various hypotheses under consideration. The evaluation is thus relative, in the sense that we only look at the ratios: we express evidence as the factor between the ratio of priors and posteriors of two distinct hypotheses. In sum, the Bayes factor comes out of the reasoned choices that we made for our account of evidence, and it exhibits the two properties that we deemed suitable for our account.

Note that we opted for an account of evidence that is explicitly Bayesian. After all it hinges on beliefs regarding hypotheses, rather than on beliefs regarding the support relation or on something else entirely. However, the eventual expression of evidential strength only involves probability assignments over data. Although we will not argue this in any detail, it therefore seems that a similar account of evidence can also be adopted as part of other statistical methodologies, certainly likelihoodism, which is concerned on our beliefs regarding support itself (e.g., Royall, 1997).

#### 1.5. The subjectivity of evidence

Our notion of evidence depends on the theory that we consider. If we consider different hypotheses, our evidence changes as well, both because we pick up on different things in the data if we consider different hypotheses, and because we might have different hypotheses to compare evidential supports. All of this points to a subjective element in evidence that affects statistical analyses in general: the idea that the data speak for themselves cannot be maintained. In this final subsection we briefly elaborate on this aspect of evidence, addressing in particular those methodologists and scientists who find the alleged subjectivity a cause for worry.

It is easy to see that evidence must be subjective when we realize that referring to data as “evidence” is a choice. A psychologist studying mechanisms of decision-making would ignore data from the exoplanet-hunting Kepler probe as being non-evidential for the particular questions that they ask. There is nothing about the data, by itself, that tells a researcher whether it counts as evidence; researchers must combine their theoretical viewpoint with the questions at hand to evaluate whether a particular data set is, in fact, evidential. This is by necessity a subjective evaluation.

Another illustration from statistics may help to further clarify the subjectivity of evidence. It is well-known that statistical procedures depend on modeling assumptions made at the outset. Therefore every statistical procedure is liable to model misspecification (Box, 1979). For instance, if we obtain observations that have a particular order structure, like 0101010101, but analyze those observations using a model of Bernoulli hypotheses, the order structure will simply go unnoticed. We will say that the data present evidence for the Bernoulli hypothesis that gives a chance of  $1/2$  to each observation. But we do not say that they provide evidence for an order structure, because there was no statistical context for identifying this structure.

It may be thought that the context-sensitivity of evidence is more pronounced in Bayesian statistics, because a Bayesian inference is closed-minded about which hypotheses can be true: after the prior has been chosen, hypotheses with zero probability cannot enter the theory (cf. Dawid, 1982). As recently argued in Gelman and Shalizi (2013), classical statistical procedures are more open-minded in this respect: the theoretical context is not as fixed. For this reason, the context-sensitivity of evidence may seem a more pressing issue for Bayesians. However, as argued in Berger and Wolpert (1988), Good (1988), and Hacking (1965) among others, classical statistical procedures have a context-sensitivity of their own. It is well known that some classical procedures violate

the likelihood principle. Roughly speaking, these procedures do not only depend on the actual data but also on data that, according to the hypotheses, could have been collected, but was not. The nature of this context sensitivity is different from the one that applies to Bayesian statistics, but it amounts to context sensitivity all the same.

The contextual and hence subjective character of evidence may raise some eyebrows. It might seem that the evidence that is presented by the data should not be in the eye of the beholder. We believe, however, that dependence on context is natural. To our mind, the context-sensitivity of evidence is an apt expression of the widely held view that empirical facts do not come wrapped in their appropriate interpretation. The same empirical facts will have different interpretations and different evidential value in different situations. We ourselves play a crucial part in this interpretation, by framing the empirical facts in a theoretical context or more concretely, in a statistical model.<sup>10</sup>

**2. Bayesian statistics: formalized statistical evidence**

The previous section laid out a general way of approaching the relationship between evidence and rational belief change which are broadly applicable in economic, legal, medical, and scientific reasoning. In some applications the primary concern is drawing inferences from quantitative data. *Bayesian statistics* is the application of the concepts of evidence and rational belief change to statistical scenarios.

Bayesian statistics is built atop two ideas: first, that the plausibility we assign to a hypothesis can be represented as a number between 0 and 1; and second, that Bayesian conditioning provides the rule by which we use the data to update beliefs. Let  $\mathbf{y}$  be the data,  $\theta$  be a vector of parameters that characterizes the hypothesis, or the statistical model,  $\mathbf{h}$  of the foregoing, and let  $p(\mathbf{y} | \theta)$  be the sampling distribution of the data given  $\theta$ : that is, the statistical model for the data. Then Bayes conditioning implies that

$$\pi_{\mathbf{y}}(\theta) = p(\theta | \mathbf{y}) = \frac{p(\mathbf{y} | \theta)}{p(\mathbf{y})} \pi(\theta).$$

This is Bayes' rule. A simple algebraic step yields a:

$$\frac{\pi_{\mathbf{y}}(\theta)}{\pi(\theta)} = \frac{p(\mathbf{y} | \theta)}{p(\mathbf{y})}. \tag{1}$$

The left-hand side is a ratio indicating the change in belief for a specific value of  $\theta$  due to seeing the data  $\mathbf{y}$ : that is, the weight of evidence. The right-hand side is the ratio of two predictions: the numerator is the predicted probability of the data  $\mathbf{y}$  for  $\theta$ , and the denominator is the average predicted probability of the data over all  $\theta$ . Examination of Eq. (1) the important link with statistical evidence. The evidence favors an explanation – in this case, a model with specific  $\theta$  – in proportion to how successfully it has predicted the observed data.

For convenience we denote the evidence ratio

$$Ev(\theta, \pi, \mathbf{y}) = \frac{p(\mathbf{y} | \theta)}{p(\mathbf{y})}$$

as a function of  $\theta$ , the prior beliefs  $\pi$ , and the data  $\mathbf{y}$  that determines how beliefs should change across the values of  $\theta$ , for any observed  $\mathbf{y}$ . As above, we use bold notation to indicate that the data, parameters, or both could be vectors. We should note that the evidence ratio  $Ev$  is not what is commonly referred to as

a Bayes factor because it is a function of parameter values,  $\theta$ . The connection between  $Ev$  and Bayes factors is straightforward and will become apparent below.

To make our discussion more concrete, suppose we were interested in the probability of buttered toast falling butter-side down. Murphy's Law – which states that “anything that can go wrong will go wrong” – has been taken to imply that the buttered toast will tend to land buttered-side down (Matthews, 1995), rendering it inedible and soiling the floor.<sup>11</sup> We begin by assuming that toast flips have the same probability of landing butter-side down, and that the flips are independent, and thus the number of butter-down flips  $y$  has a binomial distribution. There is some probability  $\theta$  that represents the probability that the toast lands butter down. Fig. 1 shows a possible distribution of beliefs,  $\pi(\theta)$ , about  $\theta$ ; the distribution is unimodal and symmetric around 1/2. Beliefs about  $\theta$  are concentrated in the middle of the range, discounting the extreme probabilities. The choice of prior is a critical issue in Bayesian statistics; we use this prior for the sake of demonstration and defer discussion of choosing a prior.

In Bayesian statistics, most attention is centered on distributions of parameters, either before observing data (prior) or after observing data (posterior). We often speak loosely of these distributions as containing the knowledge we have gained from the data. However, it is important to remember that the parameter is inseparable from the underlying statistical model that links the parameter with the observable data,  $p(\mathbf{y} | \theta)$ . Jointly, the parameter and the data make predictions about future data. The parameters specify particular chances, or else they specify our expectations about future observations, and thereby they make precise a statistical hypothesis, i.e., a particular representation. As we argued above, an inference regarding a hypothesis should center on the degree to which a proposed constraint is successful in its predictions. With this in mind, we examine the ratio  $Ev$  – a ratio of predictions for data – in detail.

The function  $Ev$  is a ratio of two probability functions. In the numerator is the probability of data  $y$  given some specific value of  $\theta$ : that is, the numerator is a set of predictions for a specific model of the data. We can understand this as a proposal: what predictions does this particular constraint make, and how successful are these predictions? For demonstration, we focus on the specific  $\theta = 0.5$ . The light colored histogram in Fig. 1(B), labeled  $p(y | \theta = 0.5)$ , shows the predictions for the outcomes  $y$  given  $\theta = 0.5$  and  $N = 50$ , as derived from the binomial(50, 0.5) probability mass function:

$$p(y | \theta = 0.5) = \binom{50}{y} 0.5^y (1 - 0.5)^{50-y}.$$

These predictions are centered around 25 butter-side down flips, as would be expected given that  $\theta = 0.5$  and  $N = 50$ .

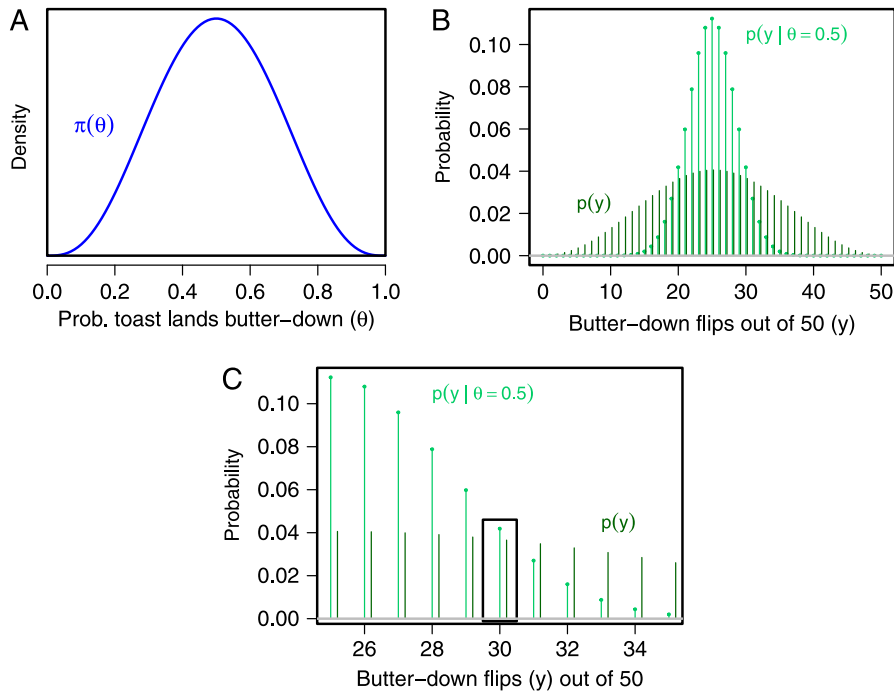
The denominator of the ratio  $Ev$  is another set of predictions for the data: not for a specific  $\theta$ , but averaged over all  $\theta$ .

$$p(\mathbf{y}) = \int_0^1 p(\mathbf{y} | \theta) \pi(\theta) d\theta.$$

The predictions  $p(\mathbf{y})$  are called the *marginal* predictions under the prior  $\pi(\theta)$ , shown as the dark histogram in Fig. 1(B). These marginal predictions are necessarily more spread out than those of  $\theta = 0.5$ , because they do not commit to a specific  $\theta$ . Instead, they use the uncertainty in  $\theta$  along with the binomial model to arrive at these marginal predictions. The spread of the predictions thus reflects all of the uncertainty about  $\theta$  contained in the prior  $\pi(\theta)$ .

<sup>10</sup> This formative role for theory echoes ideas from the philosophy of science that trace back to Popper (1959) and Kuhn (1962).

<sup>11</sup> There is ongoing debate over whether the toast could be eaten if left on the floor for less than five seconds (Dawson, Han, Cox, Black, & Simmons, 2007). We assume none of the readers of this article would consider such a thing.



**Fig. 1.** A: A prior distribution over the possible values  $\theta$ , the probability that toast lands butter-side down. B, C: Probability of outcomes under two models. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

The marginal probability of the observed data – that is, when  $y$  and  $p(y)$  have a specific values – is called the marginal likelihood.

The ratio  $Ev$  is thus the ratio of two competing models’ predictions for the data. The numerator contains the predictions of the model where the parameter  $\theta$  is constrained to a specific value, and the denominator contains the predictions of the full model, with all uncertainty from  $\pi(\theta)$  included. For notational convenience, we call the restricted numerator model  $\mathcal{M}_0$  and the full, denominator model  $\mathcal{M}_1$ . In statistics, models play the role of the hypotheses  $\mathbf{h}_i$  discussed in the previous section.

Suppose we assign a research assistant to review hundreds of hours of security camera footage at a popular breakfast restaurant, she finds  $N = 50$  instances where the toast fell onto the floor; in  $y = 30$  of these instances, the toast landed butter down. We wish to assess the evidence in the data; or, put another way, we wish to assess how the data should transform  $\pi(\theta)$  into a new belief based on  $y$ ,  $\pi_y(\theta)$ . Eq. (1) tells us that the weight of evidence favoring the model  $\mathcal{M}_0$  is precisely the degree to which it predicted  $y = 30$  better than the full model,  $\mathcal{M}_1$ . Fig. 1(C) (inside the rectangle) shows the probability of  $y = 30$  under  $\mathcal{M}_0$  and  $\mathcal{M}_1$ . Thus,

$$Ev = \frac{p(y = 30 \mid \theta = 0.5)}{p(y = 30)} = \frac{0.042}{0.037} = 1.145.$$

The plausibility of  $\theta = 0.5$  has grown by about 15%, because the observation  $y = 30$  was 15% more probable under  $\mathcal{M}_0$  than  $\mathcal{M}_1$ .<sup>12</sup>

We can compute the factor  $Ev$  for every value of  $\theta$ . The curve in Fig. 2(A) shows the probability that  $y = 30$  under every point restriction of  $\theta$ ; the horizontal line shows the marginal probability  $p(y = 30)$ . For each  $\theta$ , the height of the curve relative to the constant  $p(y)$  gives the factor by which beliefs are updated in favor of that value of  $\theta$ . Where the curve is above the horizontal line (the shaded region), the value of the particular  $\theta$  is more plausible, after observing the data; outside the shaded region, plausibility

decreases. Fig. 2(B) shows how all of these factors stretch the beliefs to form the posterior from the prior, making some regions higher and some regions lower. The effect is to transform the prior belief function  $\pi(\theta)$  into a new belief function  $\pi_y(\theta)$  which has been updated to reflect the observation  $y$ .

The prior and posterior are both shown in Fig. 2(C). Instead of being centered around  $\theta = 0.5$ , the new updated beliefs have been shifted consistent with the data proportion  $y/N = 0.6$ , and have smaller variance, showing the gain in knowledge from the sample size  $N = 50$ . Although simplistic, the example shows that the core feature of Bayesian statistics is that beliefs – modeled using probability – are driven by evidence weighed proportional to predictive success, as required by Bayes’ theorem.

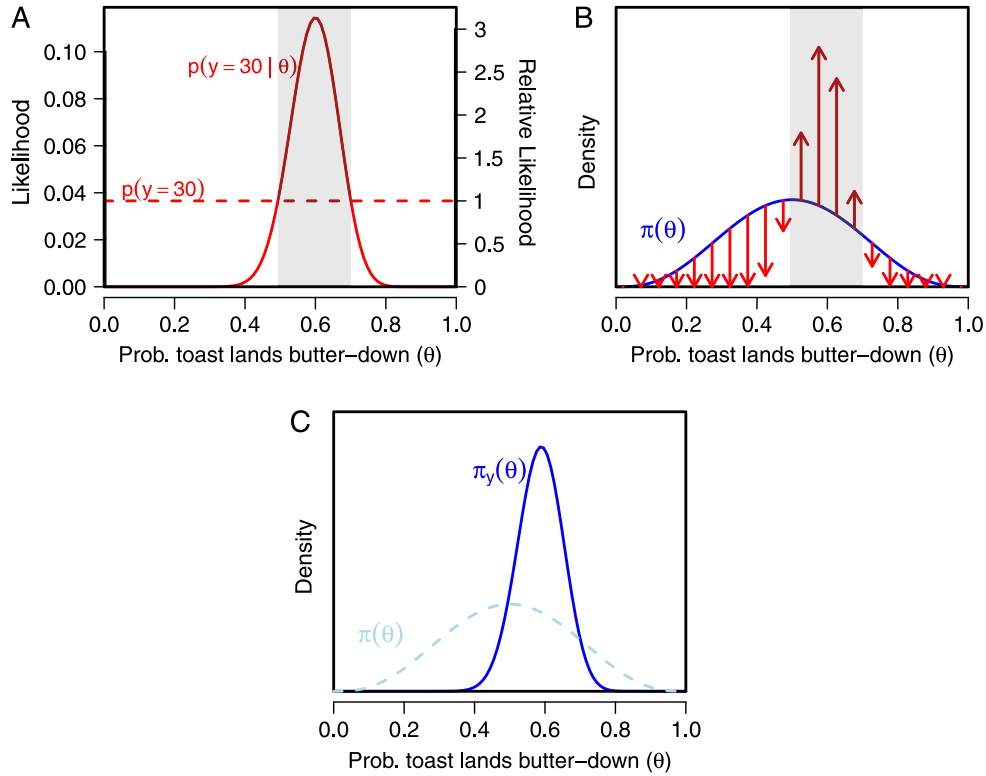
### 2.1. The Bayes factor

Suppose that while your research assistant was collecting the data, you and several colleagues were brainstorming about possible outcomes. You assert that if Murphy’s law is true, then  $\theta > 0.5$ ; that is, anytime the toast falls, odds are that it will land butter-side down.<sup>13</sup> A colleague points out, however, that the goal of the data collection is to assess Murphy’s law. Murphy’s law itself suggests that if Murphy’s law is true, your attempt to test Murphy’s law will fail. She claims that for the trials assessed by your research assistant, Murphy’s law entails that  $\theta < 0.5$ . A second colleague thinks that the toast is probably biased, does not specify a direction of bias: that is,  $\theta$  could be any probability between 0 and 1. A third colleague believes that  $\theta = 0.5$ : that is, the butter does not bias the toast at all.

You would like to assess the evidence for each of these hypotheses when your research assistant sends you the data. Because evidence is directly proportional to degree to which the

<sup>12</sup> We loosely speak of the plausibility of  $\theta$  here but strictly speaking, because  $\theta$  is continuous and  $\pi(\theta)$  is a density function, we are referring to the collective plausibility of values in an arbitrarily small region around  $\theta$ .

<sup>13</sup> Murphy’s law might be understood to imply that the toast will *always* land butter-side down. We could instead refer to this hypothesis as the “weak Murphy’s law”: anything that can go wrong will *tend* to go wrong.



**Fig. 2.** A: Likelihood function of  $\theta$  given the observed data. Horizontal line shows the average, or marginal, likelihood. B: The transformation of the prior into the posterior through weighting by the likelihood. C: The prior and posterior. The shaded region in A and B shows the values of  $\theta$  for which the evidence is positive.

observed outcomes were predicted, we need to posit predictions for each of the hypotheses. The predictions for  $\theta = 0.5$  are the exactly those of  $\mathcal{M}_0$ , shown in Fig. 1(B), while the predictions of the unconstrained model are the same as those of  $\mathcal{M}_1$ . For  $\theta < 0.5$  and  $\theta > 0.5$ , we must define plausible prior distributions over these ranges. For simplicity of demonstration, we assume that these prior distributions arise from restriction of the  $\pi(\theta)$  in Fig. 1(A) to the corresponding range (they each represent half of  $\pi(\theta)$ ). We now have three models:  $\mathcal{M}_0$ , in which  $\theta = 0.5$ ;  $\mathcal{M}_+$ , the “Murphy’s law” hypothesis in which  $\theta > 0.5$ ; and  $\mathcal{M}_-$ , the hypothesis in which our test of Murphy’s law fails because  $\theta < 0.5$ .

Having defined each of the models in such a way that they have predictions for the outcomes, we can now outline how the evidence for each can be assessed. For any two models  $\mathcal{M}_a$  and  $\mathcal{M}_b$  we can define prior odds as the ratio of prior probabilities:

$$\frac{\pi(\mathcal{M}_a)}{\pi(\mathcal{M}_b)}$$

The prior odds are the degree to which one’s beliefs favor the numerator model over the denominator model. If our beliefs are equivocal, the odds are 1; to the degree that the odds diverge from 1, the odds favor one model or the other. We can also define posterior odds; these are the degree to which beliefs will favor the numerator model over the denominator model after observing the data:

$$\frac{\pi_{\mathbf{y}}(\mathcal{M}_a)}{\pi_{\mathbf{y}}(\mathcal{M}_b)}$$

If we are interested in the evidence, then we want to know how the prior odds must be changed by the data to become the posterior odds. We call this ratio  $B$ , and an application of Bayes’ rule yields

$$B(\mathcal{M}_a, \mathcal{M}_b, \mathbf{y}) = \frac{\pi_{\mathbf{y}}(\mathcal{M}_a)}{\pi_{\mathbf{y}}(\mathcal{M}_b)} \bigg/ \frac{\pi(\mathcal{M}_a)}{\pi(\mathcal{M}_b)} = \frac{p(\mathbf{y} | \mathcal{M}_a)}{p(\mathbf{y} | \mathcal{M}_b)}. \quad (2)$$

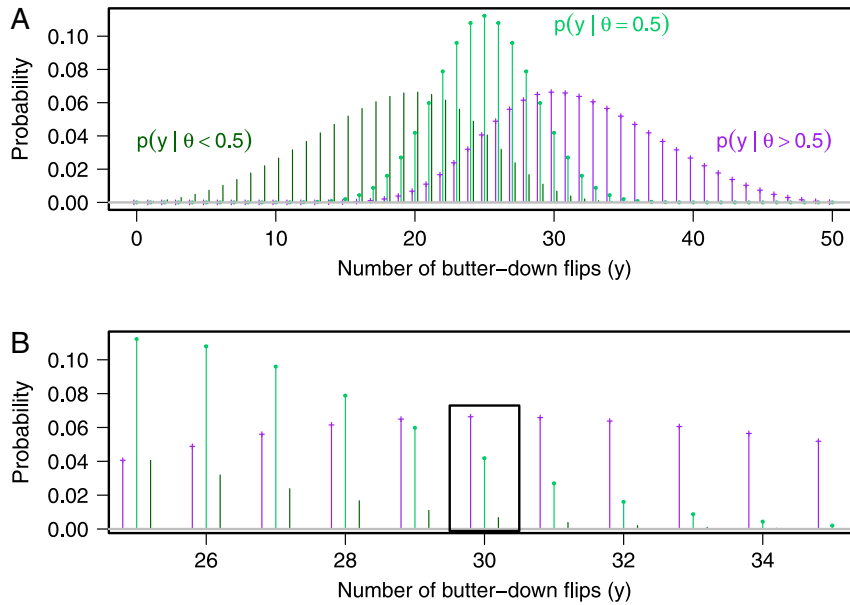
Here,  $B$  – the relative evidence yielded by the data for  $\mathcal{M}_a$  against  $\mathcal{M}_b$  – is called the Bayes factor. Importantly, Eq. (2) has the same form as Eq. (1), which showed how a posterior distribution is formed from the combination of a prior distribution and the evidence. The ratio  $Ev$  in Eq. (1) was formed from the rival predictions of a specific value of  $\theta$  against a general model in which all possible values of  $\theta$  were weighted by a prior. Eq. (2) generalizes this to any two models which predict data.

We can now consider the evidence for each of our four models,  $\mathcal{M}_0$ ,  $\mathcal{M}_1$ ,  $\mathcal{M}_-$ , and  $\mathcal{M}_+$ . In fact, we have already computed the evidence for  $\mathcal{M}_0$  against  $\mathcal{M}_1$ . The Bayes factor in this case is precisely the factor by which the density of  $\theta = 0.5$  increased against  $\mathcal{M}_1$  in the previous section: 1.145. This is not an accident, of course; a posterior distribution is simply a prior distribution that has been transformed through comparison against the “background” model  $\mathcal{M}_1$ .<sup>14</sup> This correspondence is not surprising: Bayes’ theorem provides a general account of belief change. These changes in belief (in this case, odds) must be the same regardless of whether we consider a particular value of  $\theta$  as part of an ensemble of possible values (as in parameter estimation) or by itself (as in hypothesis testing). If the Bayesian account of evidence is to be consistent, the evidence for  $\mathcal{M}_0$  must be the same whether we are considering it as part of a posterior distribution or not.

Fig. 3(A) shows the marginal predictions of three models,  $\mathcal{M}_0$ ,  $\mathcal{M}_-$ , and  $\mathcal{M}_+$ . The predictions for  $\mathcal{M}_0$  are the same as they were previously. For  $\mathcal{M}_-$  and  $\mathcal{M}_+$ , we average the probability of the data over the

$$p(\mathbf{y} | \mathcal{M}_+) = \int_{0.5}^1 p(\mathbf{y} | \theta) \pi(\theta | \theta > 0.5) d\theta$$

<sup>14</sup> In simple cases this is referred to as the Savage–Dickey representation of the Bayes factor. For example, see Dickey and Lientz (1970) and Wagenmakers, Lodewyckx, Kuriyal, and Grasman (2010).



**Fig. 3.** A: Probabilities of various outcomes under three hypotheses (see text). B: Same as A but showing only a subset of outcomes. From left to right inside the rectangle, the bars are  $p(y | \theta > 0.5)$ ,  $p(y | \theta = 0.5)$ , and  $p(y | \theta < 0.5)$ .

and likewise for  $\mathcal{M}_-$ . As shown in Fig. 3(A), these marginal predictions are substantially more spread out than those of  $\mathcal{M}_0$  because they are formed from ranges of possible  $\theta$  values. To assess the evidence provided by  $y = 30$  we need only restrict our attention to the probability that each model assigned to the outcome that was observed. These probabilities are shown in Fig. 3(B).

The Bayes factor of  $\mathcal{M}_+$  to  $\mathcal{M}_0$  is

$$B(\mathcal{M}_+, \mathcal{M}_0, y) = \frac{p(y = 30 | \mathcal{M}_+)}{p(y = 30 | \mathcal{M}_0)} = \frac{0.066}{0.042} = 1.585.$$

The evidence favors  $\mathcal{M}_+$  by a factor of 1.585 because  $y = 30$  is 1.585 times as probable as  $\mathcal{M}_+$  than under  $\mathcal{M}_0$ . Visually, this can be seen in Fig. 1(B) by the fact that the height of the bar for  $\mathcal{M}_+$  is 58% higher than the one for  $\mathcal{M}_0$ . This Bayes factor means that to adjust for the evidence in  $y = 30$ , we would have to multiply our prior odds – whatever they are – by a factor of 1.585.

The Bayes factor favoring  $\mathcal{M}_+$  to  $\mathcal{M}_-$  is much larger:

$$B(\mathcal{M}_+, \mathcal{M}_-, y) = \frac{p(y = 30 | \mathcal{M}_+)}{p(y = 30 | \mathcal{M}_-)} = \frac{0.066}{0.007} = 9.82,$$

indicating that the evidence favoring the “Murphy’s law” hypothesis  $\theta > 0.5$  over its complement  $\theta < 0.5$  is much stronger than that favoring the “Murphy’s law” hypothesis over the “unbiased toast” hypothesis  $\theta = 0.5$ .

Conceptually, the Bayes factor is simple: it is the ratio of the probabilities – or densities if the data are continuous – of the observed data under two models. It makes use of the same evidence that is used by Bayesian parameter estimation; in fact, Bayesian parameter estimation can be seen as a special case of Bayesian hypothesis testing, where many point alternatives are each compared to an assumed full model. Comparison of Eqs. (1) and (2) makes this clear. We also prefer this interpretation of parameter estimation because it makes clear that the “background” full model is always a part of the evaluation.

Having defined the Bayes factor and its role in Bayesian statistics, we now move to an example that is closer to what one might encounter in research. We use this example to show

how context dependence arises in the use of the Bayes factor in practice.

### 3. Examples

In this section, we illustrate how researchers may profitably use Bayes factors to assess the evidence for models from data using a realistic example. Consider the question of whether working memory abilities are the same, on average, for men and women; that is that working memory is invariant to gender (e.g., Shibley Hyde, 2005). Although this research hypothesis can be stated in a straightforward manner, by itself this statement has no implications for the data. In order to test the hypothesis, we must instantiate the hypothesis as a statistical model. To show how the statistical evidence for various theoretical positions, in the form of Bayes factors, may be compared, we first specify a general model framework. We then instantiate competing theoretical positions as constraints within the framework.

To specify the general model framework, let  $x_i$  and  $y_i$ ,  $i = 1, \dots, I$ , be the scores for the  $i$ th woman and man, respectively. The modeling framework is:

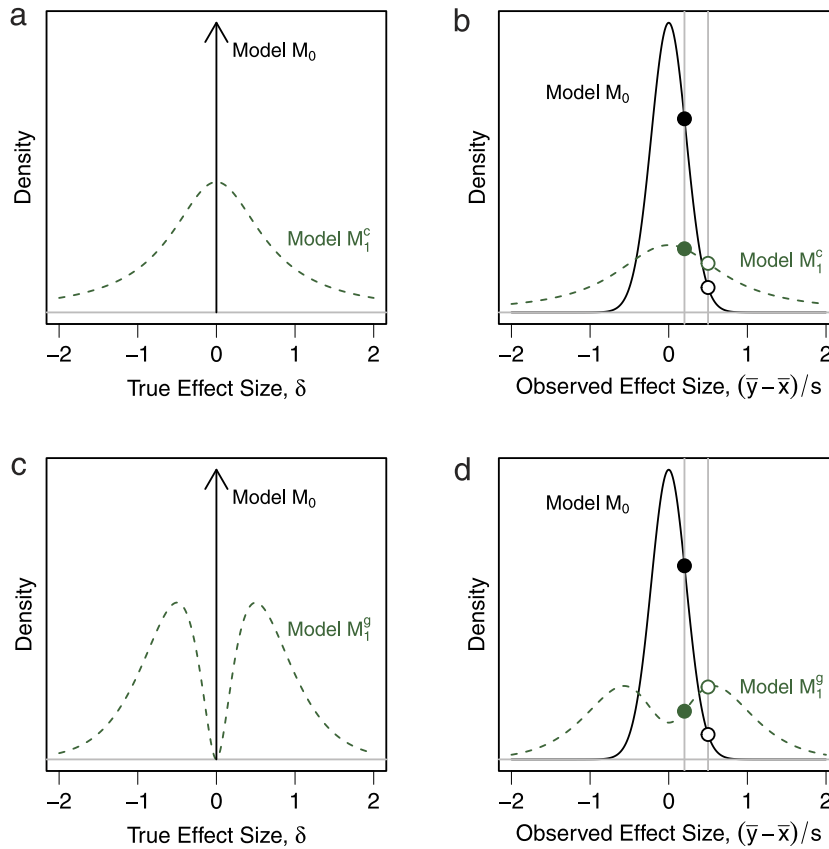
$$x_i \sim N(\mu + \sigma\delta/2, \sigma^2) \quad \text{and} \quad y_i \sim N(\mu - \sigma\delta/2, \sigma^2), \quad (3)$$

where  $\mu$  is a grand mean,  $\delta$  is the standardized effect size  $(\mu_x - \mu_y)/\sigma$ , and  $\sigma^2$  is the error variance.

The focus in this framework is  $\delta$ , the effect-size parameter. The theoretical position that working memory ability is invariant to gender can be instantiated within the framework by setting  $\delta = 0$ , shown in Fig. 4(A) as the arrow. We denote the model as  $\mathcal{M}_0$ , where the  $e$  is for equal abilities. With this setting, the Model  $\mathcal{M}_0$  makes predictions about the data, which are best seen by considering  $\hat{\delta}$ , the observed effect size,  $\hat{\delta} = (\bar{x} - \bar{y})/s$ , where  $\bar{x}$ ,  $\bar{y}$ , and  $s$  are sample means and a pooled sample standard deviation, respectively. As is well known, under the null hypothesis, the  $t$  statistic has a Student’s  $T$  distribution:

$$t = \frac{\bar{x} - \bar{y}}{s} \sqrt{I/2} \sim T(\nu),$$





**Fig. 4.** Models and predictions. (A) Competing models on true effect size ( $\delta$ ) used by Team A. (B) Corresponding predictions for observed effect size. The filled and open points show the density values for observed effect sizes of  $\hat{\delta} = 0.2$  and  $\hat{\delta} = 0.5$ , respectively. The ratio of these densities at an observed value is the Bayes factors, the evidence for one model relative to another. (C)–(D) The models and corresponding predictions used by Team B, respectively.

where  $T$  is a  $t$ -distribution and  $\nu = 2(l - 1)$  are the appropriate degrees-of-freedom for this example. The predictions for the effect size  $\hat{\delta}$  thus follow a scaled Student's  $t$  distribution<sup>15</sup>:

$$\hat{\delta} \sqrt{\frac{l}{2}} \sim T(\nu). \tag{4}$$

Predictions for sample effect size for Model  $M_0$  for  $l = 40$  are shown in Fig. 4(B) as the solid line. As can be seen, under the gender-invariant model of working memory performance, relatively small sample effect sizes are predicted.

Thus far, we have only specified a single model. In order to assess the evidence for  $M_0$ , we must determine a model against which to compare. Because we have specified a general model framework, we can compare to alternative models in the same framework that do not encode the equality constraint. We consider the case of two teams of researchers, Team A and Team B who, after considerable thought, instantiate different alternatives.

Team A follows Jeffreys (1961) and Rouder, Speckman, Sun, Morey, and Iverson (2009) who recommend using a Cauchy distribution to represent uncertainty about  $\delta$ :

$$M_1^c: \delta \sim \text{Cauchy}(r),$$

where the Cauchy has a scale parameter,  $r$ , which describes the spread of effect sizes under the alternative.<sup>16</sup> The scale parameter  $r$  must be set *a priori* and the team follows the recent advice of Morey and Rouder (Morey & Rouder, 2015) to set  $r = \sqrt{2}/2$ . With this setting for the model on  $\delta$ , denoted  $M_1^c$ , is shown in Fig. 4(A) as the dashed line. As can be seen this model is a flexible alternative that has mass spread across small and large effects, but very large effect sizes are substantially less likely than smaller ones. The symmetry of the distribution encodes an *a priori* belief that it is as likely that women outperform men as that men outperform women. The corresponding prediction on sample effect size is shown in Fig. 4(B) as the dashed line, and the model predicts a greater range of observed effect sizes than Model  $M_0$ .

Team B considers a different alternative formed by representing their uncertainty about the effect size with a symmetric, but bimodal, distribution. This bimodal distribution is formed by joining gamma distributions in a back-to-back configuration as shown in Fig. 4(C) as the dashed line. Similar bimodal priors were recommended by Johnson and Rossell (2010) and Morey and Rouder (2011). We denote this alternative as  $M_1^g$ , and this alternative makes a commitment that if there are effects, they are moderate

<sup>15</sup> Prior distributions must be placed on  $(\mu, \sigma^2)$ . These two parameters are common across all models, and consequently the priors may be set quite broadly. We use the Jeffreys priors,  $\pi(\mu, \sigma^2) \propto 1/\sigma^2$ , and the predictions in (4) are derived under this choice. We note, however, that the distribution of the  $t$  statistic depends only on the effect size,  $\delta$ , so by focusing on the  $t$  statistic we make the prior assumptions for  $\sigma^2$  and  $\mu$  moot.

<sup>16</sup> The scaled Cauchy distribution has density

$$f(\delta) = \frac{1}{r\pi \left[1 + \left(\frac{\delta}{r}\right)^2\right]}$$

for  $r > 0$ .

in value.<sup>17</sup> Compared to Team A's alternative, Team B's alternative has less mass for very large and very small magnitudes of effect size while retaining the symmetry constraint. A defense of such a prior could be that where gender effects are observed, say in mental rotation (see Matlin, 2003), they tend to be moderate in value. The corresponding prediction on sample effect size is shown in Fig. 4(B) as the dashed line.

It is critical to realize that neither Team A's nor Team B's choice needs to be considered more "correct" in their specification. Each team is interpreting the theoretical statement that men and women have different working memory capacities on average in good faith and their priors add value. In order to compute statistical evidence, choices such as these must be made. Hence, variation among priors is the reasonable and expected among analysts and should be viewed as part of the everyday variation across researchers and research labs, much as variations in experimental methods across laboratories are viewed as reasonable and expected. As with variations in experimental designs, so long as the choices made are transparent the answers will be interpretable.

Suppose the experiment resulted in an observed effect size of  $\hat{\delta} = 0.2$ , indicating that women somewhat outperformed men. For Team A, the predicted densities of observing  $\hat{\delta}$  of 0.2 are shown as filled points in Fig. 4(B). The Bayes factor is the ratio of the predicted densities under  $\mathcal{M}_0$  and  $\mathcal{M}_1^g$ . Because the density is 3.041 times higher under  $\mathcal{M}_0$  than under  $\mathcal{M}_1^g$ , the evidence yielded by  $\hat{\delta} = 0.2$  is a Bayes factor of 3.041. Team A can then state the evidence for the equality of working-memory performance by this same factor. Team B computes their Bayes factor analogously. Because the density is 4.018 times higher under  $\mathcal{M}_0$  than under  $\mathcal{M}_1^g$ , the relative evidence yielded by  $\hat{\delta} = 0.2$  is a Bayes factor of 4.018. Team B states evidence for the equality of working-memory performance by this factor. Although Team A and Team B reach the same conclusions, their evidence differs by a factor of 32%.

The open circles in Fig. 4(B) show the same two analyses for a different hypothetical observed effect size, in this case  $\hat{\delta} = 0.5$ . The Bayes factors reached by Team A and Team B are about 2-to-1 and 3-to-1 in favor of a performance effect, and once again, these values differ.

Although it may appear problematic that two teams assessed the evidence in the same data differently, it is important to note that the two teams asked slightly different statistical questions; that is, the teams used different instantiations of the theoretically relevant statement into statistical models. Team A compared the null hypothesis  $\delta = 0$  to their unimodal Cauchy prior, and Team B compared the null hypotheses to their bimodal prior. As we have argued, however, this dependence on context is a natural property of statistical evidence. Whereas the variation in modeling is expected and reasonable, so is the variation in evidence values. Data cannot impact different researchers in the same way across all contexts. We discuss this further in the next section.

#### 4. Discussion

In this paper, we defined evidence in a straightforward way: the evidence presented by data is given by the change in belief that it affects. We formalized this definition and showed how it can be put to use in statistics. A Bayesian notion of evidence

<sup>17</sup> The density of the model on  $\delta$  is

$$f(\delta) = \begin{cases} g(\delta, 3, 4)/2, & \delta \geq 0, \\ g(-\delta, 3, 4)/2, & \delta < 0, \end{cases}$$

where  $g(\delta, \nu, \lambda)$  is the density function of a gamma distribution with shape  $\nu$  and rate  $\lambda$  evaluated at the value  $\delta$ .

arises when it is assumed that "beliefs" are represented by probabilities, and that belief change is manifested by conditioning the probability of various hypotheses on the data. These choices can be questioned, of course. If one wants to quantify statistical evidence in another manner, it would be necessary to flesh out other models that tie together hypothesis, data, and evaluation (e.g., fiducial statistics; Fisher, 1930).

Given the importance to scientists of quantifying statistical evidence, why have researchers not moved from frequentist techniques to other techniques more suited to their goals? There are several reasons for this. First, researchers believe, falsely, that currently popular methods serve their purposes (Gigerenzer, Krauss, & Vitouch, 2004; Haller & Krauss, 2002; Hoekstra, Morey, Rouder, & Wagenmakers, 2014; Oakes, 1986). Second, there are several major critiques of Bayes factors that, thus far, have kept them from widespread usage. Here we outline some major critiques of Bayes factors that prevent them from being used as measures of evidence by working scientists: that Bayes factors are overly-sensitive to prior distributions, that prior distributions are too difficult to choose, and that Bayes factors depend on the true model being considered.

##### 4.1. Sensitivity to prior distributions

A number of authors have critiqued the use of Bayes factors for inference on the grounds that they are sensitive to the prior distribution chosen to represent the hypothesis (e.g., Aitkin, 1991; Grünwald, 2000; Liu & Aitkin, 2008; O'Hagan, 1995). In the example in Section 3, this was apparent: Team A and Team B chose different prior distributions over the effect size  $\delta$ . Each team had to decide what prior distribution best represented the alternative that women and men do have the same working memory ability on average. Although the two teams were nominally testing the same hypothesis, the Bayes factors computed by the two teams differed. This leads to the appearance that the Bayes factors are overly-dependent on the priors, which in turn causes the evidence to be arbitrary.

To some extent we defer this criticism to Bayesian statistics in general. As our development of the Bayes factor in Section 2 should make clear, the Bayes factor is neither less nor more dependent on the prior than any other Bayesian method. In fact, the transformation from prior to posterior is a special case of a Bayes factor analysis, where every point-restriction in a full model is compared to the full model itself. Any general critique of Bayes factors as a method is a critique of the foundations of Bayesian analysis itself. To avoid already well-trod ground, we refer the reader to other proponents of Bayesianism (Edwards, Lindman, & Savage, 1963; Jeffreys, 1961). In our account of evidence, we simply assume the Bayesian perspective.

It is important, however, to emphasize that the Bayes factor is not sensitive to prior distributions in all cases; the use of Bayes factors does not always require the specification of a prior distribution. Inspection of Eq. (2) reveals that the Bayes factor is solely a function of the probability of the data under the two hypotheses in question. Whenever the hypotheses are composite, these probabilities will be obtained through marginalizing over priors. But this is not the only way of obtaining predictions. It may so happen that the hypothesis, or model, under consideration does not involve any further parameters, and hence does not require any priors over the parameters (e.g., Jeffreys & Berger, 1991).<sup>18</sup>

<sup>18</sup> It may be thought that all modeling is accompanied by some degree of freedom but this need not be. A good example is given by statistical predictions about measurements of radioactive decay and subatomic particle spin. Predictions for these quantities can be derived from quantum mechanics, and they have unique distributions under the theory.

Even if the Bayes factors depend on the choice of a prior, a case can be made that this is as it should be. We obtain the marginal likelihoods of a model by taking an average of the likelihoods of the component hypotheses, weighted by the prior distribution. The prior distribution thus ensures that the model has a definite marginal likelihood, and thus establishes a bridge between the hypothesis and the data. Importantly, the Bayes factor is not dependent on the priors in any other way than through this marginal likelihood. Moreover, it is sensitive to the priors only insofar as the priors impact on the predictions of a model or a hypothesis. Arguably, this sensitivity of the Bayes factor to the priors is precisely what one would expect: the priors are included in the evaluation insofar as they have empirical content (see also Vanpaemel, 2010).

For users of classical significance testing, the above idea can at first be counter-intuitive. Consider a pair of standard classical hypotheses assuming known  $\sigma$ :

$$z \sim \text{Normal}(\delta\sqrt{N}, 1) \quad (5)$$

$$\mathcal{H}_0 : \delta = 0 \quad (6)$$

$$\mathcal{H}_a : \delta \neq 0. \quad (7)$$

No Bayes factor analysis is possible on this pair of hypotheses: one can never determine the support of this particular instantiation of  $\mathcal{H}_a$ , because it makes no predictions at all. In a classical significance test, by contrast, there are two possible outcomes: either we retain  $\mathcal{H}_0$ , or we reject it. One cannot make any positive claims about the evidence in favor of  $\mathcal{H}_0$ , and so the test is asymmetric, allowing only an argument for  $\mathcal{H}_a$ . A classical account of the evidence, in other words, is incomplete.

The use of Bayes factors requires that one instantiate hypotheses in such a way that they have constrained predictions for the data. One cannot test empty hypotheses such as “the population mean is not 100”, because the predictions of such hypotheses are left indeterminate. But in order to arrive at a definite likelihood, we need a prior probability. And we believe that this is as it should be; any valid inference will hinge on the marginal data predictions, and hence on the choice of a prior. Even stronger, we believe that this prior dependence signals an important property of inference in general: evidence for or against a hypothesis should always be based on that hypothesis’ empirical content—in our case: its predictions. However, because the choice of prior distributions is sometimes critical, we are required to put careful thought into this when we construct hypotheses.

#### 4.2. Choosing prior distributions

As we said, the use of Bayes factors forces the analyst to specify what the empirical content of a hypothesis is. But specifying the empirical content of a hypothesis may require substantial work. If used well, the Bayes factor rewards the analyst with an easily-interpretable measure of statistical evidence. If used badly – that is, without consideration of whether the instantiations of the hypotheses are meaningful – the Bayes factor is useless. Careless, automatic application of Bayes factors will lead to meaningless evidence measures that compare hypotheses not of interest to anyone. Solving the problem of careless, automatic application of Bayes factors is not trivial. For some relatively simple classes of models – e.g., linear models – it is possible to define flexible families of alternative models to compare (Liang, Paulo, Molina, Clyde, & Berger, 2008; Rouder, Morey, Speckman, & Province, 2012; Zellner & Siow, 1980).

However, for testing complex, non-nested models, the challenge of placing priors over unknown parameters is a serious impediment to the use of Bayes factors. There are several ways we might meet the challenge. One seemingly attractive way to instantiate the assumption that the values of the unknown parameters

are irrelevant is to assume a so-called “non-informative” (possibly improper) prior over the parameter space. This sort of prior can be specially chosen to reflect indifference across possible values of the parameters (Berger & Bernardo, 1992; Bernardo, 1979; Jeffreys, 1946, 1961, e.g.,). However, given the development above, such a prior would be unwise. Bayes factors with improper priors have many issues stemming from the fact that the priors are not true probability distributions, and the marginal likelihood is not uniquely defined (Atkinson, 1978; Bartlett, 1957; Jeffreys, 1961; Spiegelhalter & Smith, 1982). Even relatively uninformative proper priors are open to the critique that practically, these hypotheses are unlike those that any researcher might consider, due to their heavy weighting of large effect sizes (DeGroot, 1982).

Another approach to avoiding the arbitrariness of noninformative priors is to always specify “reasonable” priors. Lindley was a strong advocate of this approach. In his critique of O’Hagan’s (1995), he wrote: “It is better to think about [the parameter] and what it means to the scientist. It is his prior that is needed, not the statistician’s. No one who does this has an improper distribution”. Although this approach is attractive in principle, in practice it can be daunting for a scientist to think of prior distributions. Some parameters can be difficult to interpret, and when there are hundreds or thousands of parameters in a statistical model, a scientist may not be able to generate meaningful priors (c.f. Berger, 2006; Goldstein, 2006, and discussion) in practice.

Another possible solution is to build a “default” prior for the parameters using the data itself. Because improper priors can yield proper posteriors given a minimal sample size, one could use a small part of the sample to compute the priors needed for the marginal likelihood to be defined for each model, then compute the Bayes factor as the ratio of the marginal likelihoods for the remaining data, given the priors built from the training data. Variations on this basic approach, called “partial Bayes factors”, have been suggested by multiple authors, including Aitkin (1991); Atkinson (1978); Berger and Pericchi (1996, 1998); Spiegelhalter and Smith (1982). O’Hagan (1995) has suggested using a fraction of the likelihood itself as a prior. These approaches all attempt to circumvent, in some way, the problem of generating a reasonable prior for model comparison. They can all be critiqued on the basis that the hypothesis to be tested was derived from the data itself, and so interpreting the results of the hypothesis test may be difficult.

Discussion of the details of each of these statistics is outside the scope of this paper. However, we agree with the principle put forward by Berger and Pericchi (1996): “Methods that correspond to use of plausible default (proper) priors are preferable to those that do not correspond to any possible actual Bayesian analysis”. Not all of the above default methods correspond to actual Bayesian analyses (see Berger & Pericchi, 1998, for discussion). The methods that correspond to a plausible default priors will have an interpretation in terms of statistical evidence for some pair of hypotheses; methods that do not correspond to any possible Bayesian analysis will not. Of course, even if a default method corresponds to a possible actual Bayesian analysis, one must always ask whether the comparison offered by a default method is interesting.

#### 4.3. Selection versus comparison, truth versus representation

Bayes factors are often described as a model selection method; that is, one may compute the Bayes factors across a number of models, and select the model that has the highest Bayes factor as the “best” model. We have deliberately avoided discussion of model selection. In our minds, the most useful feature of the Bayes factor is its interpretation as a measure of evidence. Our view is that the concept of evidence is of paramount value. How one uses

the evidence is a separate issue from the weighing of the evidence itself (see Fisher, 1955, for a similar point).

The distinction between model comparison and model selection is critically important. Selecting a model on the basis of a Bayes factor implies that one believes that the model is “good enough” in some way. However, as Gelman and Rubin (1995) point out, this cannot be argued on the basis of the Bayes factor alone. A model with the highest Bayes factor in a set of models may nonetheless fit badly. A model having the highest Bayes factor means nothing more than that the model had the highest amount of evidence in favor of it out of the models currently under consideration. However, a new model that could be considered may perform substantially better. We have stressed here and elsewhere that a model comparison perspective – as opposed to a model selection perspective – respects the fact that the evidence is always relative (Morey, Romeijn, & Rouder, 2013). This will not be so surprising to scientists, who are used to the tentative nature of scientific conclusions.

Finally, it has been argued that the use of Bayes factors requires an implicit belief that one of the models under consideration is true (Gelman & Shalizi, 2013; Sanborn & Hills, 2014; Yu, Sprenger, Thomas, & Dougherty, 2014). Some statistical properties of Bayes factors – for instance, their convergence to the true model under regularity conditions – do depend on the “true” model being in the set of considered models (Schervish, 1995). We believe, however, that in scientific practice the notion of true or false models is misguided. Statistical models are impoverished representations that attempt to capture an important aspect of a phenomenon. Although they may be used to generate propositions that can be true or false, by themselves they are not true or false. Or at least, put more carefully, their truth conditions are far from clear.

This may appear to threaten the entire enterprise of quantifying statistical evidence. After all, if models are not necessarily true or false, what does it mean to accumulate evidence for a model? We suggest that just as statistical models are proxies for real-world phenomena, statistical evidence is a proxy for real-world evidence. The applicability of the computed statistical evidence to the scientific question at hand will depend on a number of factors, including the degree to which the models compared correspond to the scientific question at hand (Morey et al., 2013). The rarefied property of statistics applies as much to statistical evidence as it does to other aspects of statistics. For instance, often statistical inferences are described as being about populations. However, the idea of a population is abstract, and a single, unique population – in the statistical sense – may not meaningfully exist. This, of course, does not prevent the population from being a useful concept; likewise, that a model may not be true does not mean that statistical evidence for the model is not interesting. Careful consideration is required to know whether a statement of statistical evidence is useful in understanding the phenomenon of interest to the researcher.

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